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LIQUID ROCKET DIVISION

STABILITY CHARACTERIZATION OF ADVANCED INJECTORS

Design Guide, Volume 2
Operation of the Computer Program

Report 20672-P2D

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AEROJET-GENERAL CORPORATION

SACRAMENTO, CALIFORNIA

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STABILITY CHARACTERIZATION OF
ADVANCED INJECTORS

DESIGN GUIDE

Volume 2, Operation of the Computer Program

Report 20672-P2D

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Aerojet-General Corporation
Liquid Rocket Division

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Phase II, Final Report

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FOREWORD

This volume is submitted as partial fulfillment of contract provisions of Contract NAS 8-20672 and meets the requirements of Supplement No. 10 of that contract. The NASA project engineer was Mr. R. J. Richmond.

Volume I of this report is written specifically for the designer with the intent of providing combustion stability information which may be applied directly during a program's design phase. This volume (Volume II), on the other hand, is to provide the tools by which the analyst may characterize the combustion stability of a system. The combustion model which provided the basis for this analytical technique is the Sensitive Time Lag theory first developed by Dr. L. H. Crocco and later extended by Dr. F. H. Reardon. This volume provides description of a computer program, written in FORTRAN V, which may be utilized in characterizing a variety of combustion systems.

The work was conducted by the Thrust Chamber Engineering Section of the Liquid Rocket Division under Dr. N. E. Van Huff, acting manager; Mr. J. M. McBride, project manager; and Mr. W. W. Howard, project engineer.

Special acknowledgement is given to Mr. R. C. Waugh for his contribution in the development of analytical models, Mr. D. P. Dudley for programming and conversion of the computer program, Mr. R. K. Turner for the reduction of combustion stability theory into design criteria and analysis and correlations of test data, and Mr. W. J. Nord for organizing and editing the material contained in these reports.

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I. PROBLEM

A. ABSTRACT

This program solves the combustion instability problem using the sensitive time lag theory. This amounts basically to solving the inhomogeneous Helmholtz equation for the condition of neutral stability. The inhomogeneous terms in the Helmholtz equation account for the mean flow and combustion effects. The program considers longitudinal and transverse modes of oscillation. It includes effects of non-uniform injection, velocity effects, and non-linear combustion response.

The program is divided into several subprograms which can either be run together or separately. These subprograms include nozzle admittance, longitudinal mode analysis, transverse mode analysis, describing functions for combustion response, and nonuniform injection parameters.

B. TECHNICAL DESCRIPTION

1. The Nature of Combustion Instability

It is well known that the processes occurring within a liquid rocket combustion chamber are never entirely smooth. Even when the mean operating conditions are constant, fluctuations around these mean values occur in all of the quantities that characterize the flow. The nature of the fluctuations can vary widely from one combustor to another and in a single combustor for different operating conditions. If the fluctuations are random and of small amplitude, this unsteadiness is referred to as "combustion noise". With random fluctuations of large amplitude, the operation of the rocket is said to be "rough", and the functioning of the system of which the rocket is a part may be impaired.

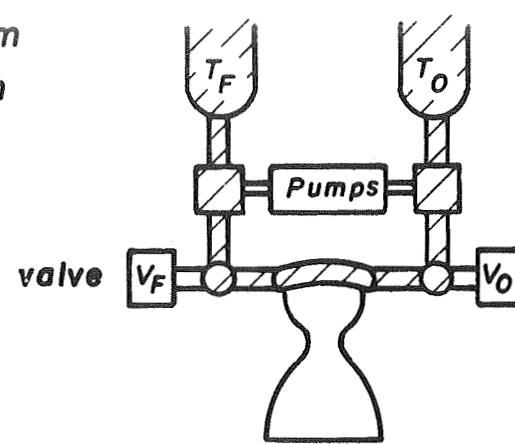
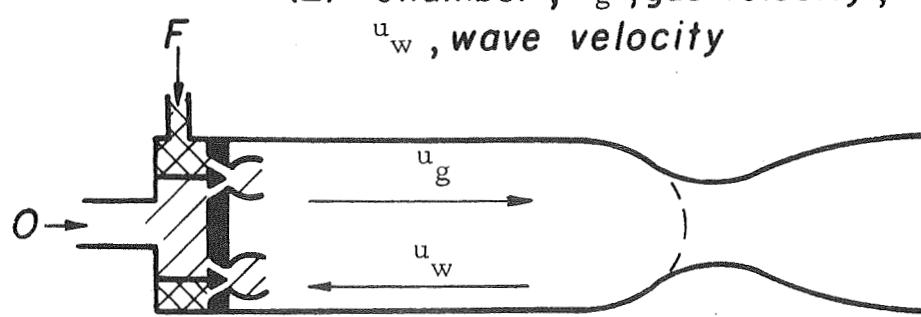
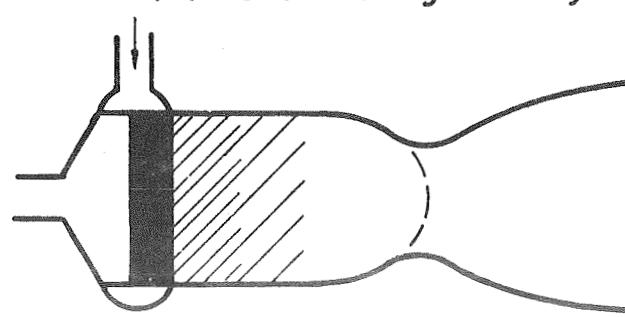
<u>Type</u>	<u>Characteristic coupling</u>
1. Chugging (low frequency)	(1) feed system (2) combustion chamber
	
2. Entropy wave	(1) injector (mixture ratio) (2) chamber ; u_g , gas velocity ; u_w , wave velocity
	
3. Hi-frequency	(1) combustion process (2) chamber geometry (wave travel time)
	

Figure 1 --- Liquid Propellant Combustion Instability

I, B, Technical Description (cont.)

Much more serious than rough operation is the problem of combustion instability, also termed unstable combustion, oscillatory combustion, or resonant combustion. Whereas rough combustion refers to random fluctuations, combustion instability consists of organized oscillations that are maintained and amplified by the combustion process itself. The various types of combustion instability can be classified roughly into three categories: low frequency, intermediate frequency, and high frequency. However, the classification is not based simply on frequency alone. Just as electrical and mechanical systems respond to specific frequencies depending on the type of coupling, so also liquid rocket systems exhibit representative frequency and amplitude patterns.

The basic coupling mechanisms for the three general types of combustion instability found in liquid propellant rocket engines are illustrated in Figure 1. For the low frequency ("chugging") type, interaction between the propellant feed system and the combustion chamber places the frequency generally less than 200 Hertz. The coupling is effected by the oscillating propellant feed rates. In the case of intermediate frequency combustion instability (sometimes referred to as entropy wave instability), the injector characteristics (especially the internal injector manifolding and orifice impedances) account for part of the interaction, with the mean gas flow and pressure wave propagation in the combustion chamber completing the process. Typical frequencies are in the several hundred Hertz range.

In this report, attention will be focused on the third type of combustion instability, namely, high frequency instability. This type depends upon a coupling between the combustion processes and flow oscillations in the combustion chamber. Such coupling requires no input from the feed system, although it is possible for the feed system to have an effect when the combustion chamber is large and acoustic frequencies are reduced to several hundred cycles per second. Normally, the frequencies to be expected are in the thousand Hertz range for most current engines.

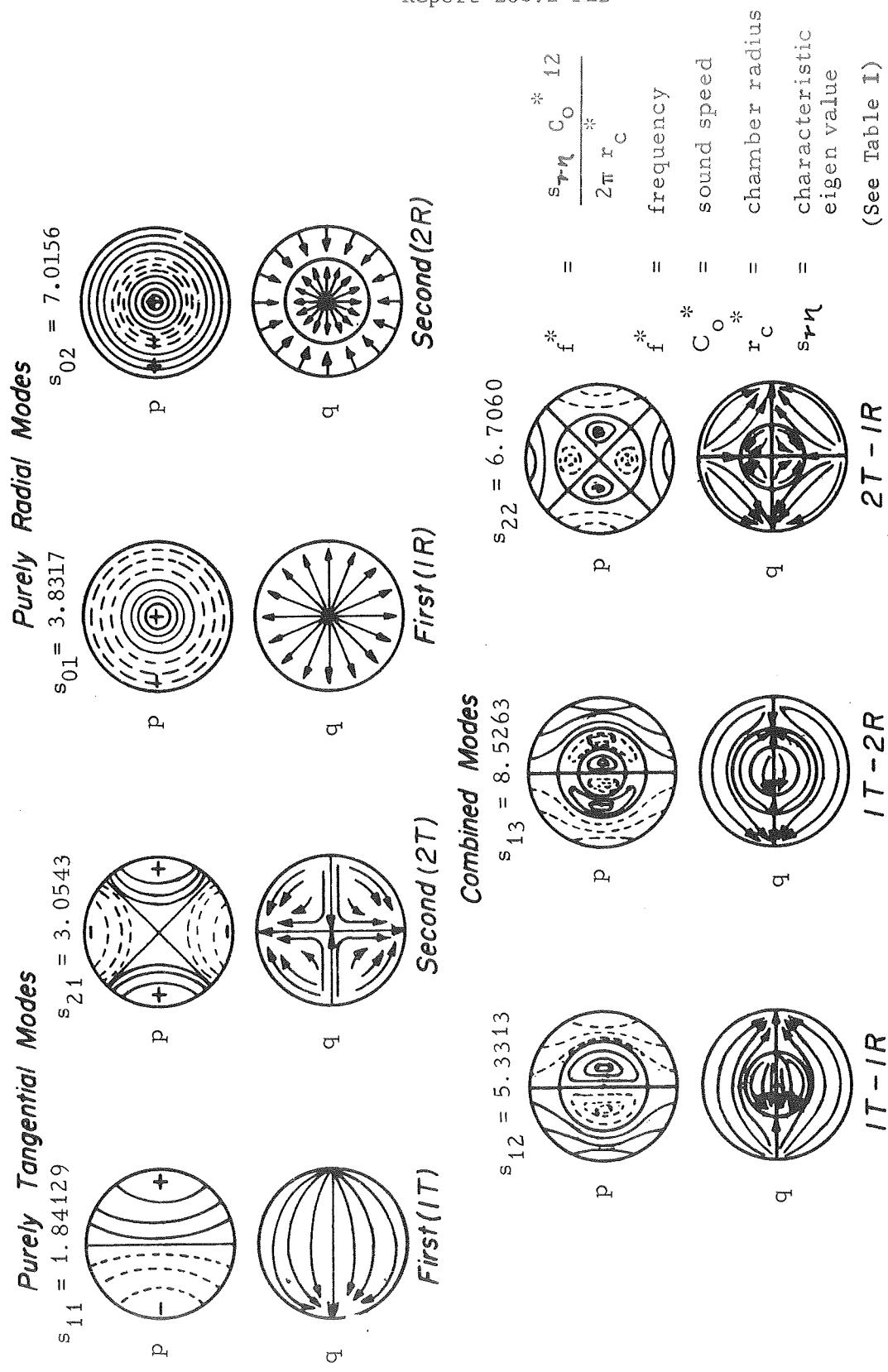


Figure 2 -- Pressure, p, and Velocity, q, Characteristics of Several Transverse Modes

TABLE I s_{vn} FOR A CYLINDRICAL CHAMBER

For transverse modes the frequency of oscillation is given by:

$$f^* = \frac{s_{vn} C_0^* \times 12}{2 \pi r_c^*}$$

<u>Mode</u>	<u>v</u>	<u>n</u>	<u>s_{vn}</u>
1st radial	0	1	3.8317
2nd radial	0	2	7.0156
3rd radial	0	3	10.1734
1st tangential	1	1	1.8413
2nd tangential	2	1	3.0543
3rd tangential	3	1	4.2012
4th tangential	4	1	5.3175
5th tangential	5	1	6.4154
6th tangential	6	1	7.5013
1T, 1R combined	1	2	5.3313
2T, 1R combined	2	2	6.7060
3T, 1R combined	3	2	8.0151
4T, 1R combined	4	2	9.2825
1T, 2R combined	1	3	8.5263

For a longitudinal mode the frequency can be estimated by:

$$f^* = \frac{C_0^* \times 12}{2 (L_c^* + 2/3 L_N^*)} (1 - M_m^2)$$

where: L_N^* = length of nozzle in inches.

M_m = average Mach number in nozzle-chamber combination

I, B, Technical Description (cont.)

The combustion chamber geometry is an important factor in high frequency combustion instability because the possible frequencies depend on the internal geometry. Since it is effectively closed at one end by the injector and has a choked-flow exhaust nozzle at the other end, the chamber acts acoustically much as a double closed-end cavity. For instance, for purely longitudinal modes, an approximate point of effective reflection in the nozzle can be determined theoretically; between that point and the injector face standing patterns of acoustic waves can be established. Similarly in the transverse plane, tangential modes of the spinning or standing types as well as radial modes may be established. Frequencies correspond approximately to those of the acoustic modes, either the fundamental or higher harmonics. Modes containing combinations of tangential, radial and longitudinal oscillations may also exist, each characterized by its own frequency. Pressure and velocity patterns for several transverse modes are illustrated in Figure 2. However, despite the similarity of the modes and the closeness of frequencies, the continuous generation of gases produces effects that do not exist in a closed chamber. In a closed chamber, the only source of damping originates from the friction on the walls. This source of damping is active of course also in the combustion chamber, but it plays a very modest role compared to other, more powerful sources of damping. Indeed, the very existence of the nozzle produces damping in the case of pure or combined longitudinal modes because the reflection of waves from the convergent (subsonic) portion of the nozzle departs from that of the ideal closed end. For purely transverse waves this source of damping is missing, and actually is replaced by a slight source of amplification.

The most important source of damping, however, is related to the process of gas generation itself, and consists of two parts of approximately equal importance. The most obvious comes from the fact that, from the conditions of the steady propellant injection flow (steady, of course, only if the feed system perturbations are disregarded) the combustion gases must have

I, B, Technical Description (cont.)

acquired, at the moment of generation, the perturbed momentum corresponding to the oscillatory flow. The acquisition of this momentum demands a certain work which must be absorbed from the system. The fact that momentum exchanges due to the drag of the droplets can take place prior to the moment of generation can only add additional damping.

The other, more subtle source of damping comes from the fact that at the moment of generation the volume of the propellant must change from its practically negligible liquid volume, to the full volume of the burned gases. To this change of volume corresponds a certain "pumping work" proportional to the local instantaneous pressure. Hence, more work must be absorbed from the system when the pressure is higher, and less when it is lower, thus providing an effective damping mechanism.

The significance of the preceding discussion is that, from the point of view of instability, each combustion system is characterized by certain well-defined proper frequencies at which the gases can oscillate in well-defined modes, and by certain damping mechanisms which absorb energy from the oscillating system. It is clear that self-sustained oscillations can exist (and instability appear) only if the combustion process is able to generate, at any one of the proper frequencies, enough feedback combustion energy (in excess of the steady-state conditions) to restore continually the amount which is being lost.

Suppose, for a moment, that the amount of combustion feedback energy is independent of frequency. Then the only important factor in the balance would be the energy damping corresponding to each mode, that (or those) mode(s) becoming unstable which correspond(s) to the lowest level of damping. Experience shows that this is not the case, and that, for a given injector, the selection of the unstable mode is rather governed by its proper frequency than by its damping level. This has been shown to be the case both for

I, B, Technical Description (cont.)

longitudinal and for transverse forms of instability. In both it has been possible to observe the switch from one unstable mode to another (for instance from the fundamental to the second mode) when the geometrical (or other) conditions are gradually changed. It is not our purpose to discuss here the details of the transition from one mode to the other (it does not take place suddenly), but rather to point out that the transition occurs in such a way as to maintain the oscillation frequency within a well-defined narrow range.

The only logical interpretation of this observation is that not only the combustion feedback energy must depend on frequency, but that actually only in a narrow range around one, well defined, frequency (determined in a complicated way by the various geometrical, physical and chemical conditions on which the combustion process depends), can the combustion feedback energy reach a level sufficient to balance the damping.

The empirically observed existence for a given combustion system of one narrow frequency range in which instability can appear can be interpreted by stating that, among the features characterizing the response of a given combustion system to oscillatory conditions, one can single out a "characteristic time" simply proportional to the reciprocal of frequency, such that only when its ratio to the oscillation period is around a certain value, maximum feedback can be generated and, possibly, instability produced.

This behavior has similarities to that of a resonant system, which is able to oscillate at certain natural frequencies with amplitudes that depend on the value of the frequency of the exciting forces compared to those of the natural frequencies. In the combustion instability problem also the exciting force due to the unsteady combustion processes is characterized by its own frequency (or its characteristic time), and maximum amplitudes are to be expected where there is coincidence with one of the proper frequencies.

I, B, Technical Description (cont.)

However, there is an important difference, residing in the fact that the exciting force is not independently applied from the outside, but is produced (in a sort of feedback loop) by the oscillations themselves, with the result that considerations of stability appear and take fundamental importance, and that the eventual oscillatory situation is determined by nonlinear effects. Nevertheless the terms "resonance" and "resonant" are often applied also to this case.

It appears that the knowledge of the characteristic time associated with a particular combustion system would be of primary importance in the design of new rockets, since it determines in which mode instability is able to appear. Such a knowledge could, for instance, allow the choice of the chamber and injector geometry in such a way that all of the proper frequencies would be too high to become unstable. Unfortunately, even assuming the characteristic time to be known, the choice of the propellant combination, as well as the chamber and basic injection system geometry, has always been fixed in the past during the early stages of development programs based on other stringent requirements of size, weight and performance, and there is very little chance that even in the future the designers may base their designs only on stability requirements. Therefore, a more sophisticated approach to the problem of stability is necessary, in which the second condition for appearance of instability, that of the energy balance, is also taken into consideration. In other words, even if it is impossible to avoid having some of the proper frequencies fall in the range where they may become unstable for the given combustion system one should make sure that for the corresponding modes the combustion feedback is not sufficient to balance the damping.

Clearly there are two ways in which this balance can be improved in favor of stability: one is the depression of the combustion feedback, the other the increase of the damping. Of the two solutions, the

I, B, Technical Description (cont.)

second has been favored in recent times because it is better understood and hence easily controlled. Such damping devices as baffles or acoustic liners have been introduced, to the cost of more or less profound design complications, and have been very effective in producing substantial levels of damping, due to the dissipation caused by the devices. At the same time these devices also entail a change of the proper frequencies, and, in view of the previous discussion, this change can also have an effect on the balance.

On the other hand, the solution of depressing the combustion feedback has not been used in any consistent and systematic fashion, but only by looking for injector designs which, fortuitously or nearly so, result in the most stable operation on the test stand.

It may be added that a third, and the most effective solution, clearly consists in applying simultaneously the two solutions above, by (1) using an injector as stable as possible, and (2) adding a certain amount of extra damping to attain whatever safety margin is required.

The difficulty with a systematic application of the second (or the third) solution has been that the behavior of the combustion systems under oscillatory conditions is still very incompletely understood, so that it is impossible today, starting from the fundamental consideration of the basic physico-chemical processes involved, not only to predict the value of the characteristic time or the magnitude of the energy feedback, but often even the very direction in which these quantities are affected by a change in design.

However, a less fundamental approach exists, which may still help the designer considerably, that is based upon the idea of establishing empirical correlations between the characteristic time and the energy feedback on one side and, on the other side, a certain number of appropriate combinations of parameters characterizing the injector geometry, the propellant mixture and the

I, B, Technical Description (cont.)

operating conditions. The feasibility of such an approach is offered by the sensitive time lag concept, introduced by Crocco in 1951 (Ref. 1). Although originally formulated with the sole intent of gaining an insight into the essential features of the high frequency instability phenomenon, the sensitive time lag combustion model was later found to predict accurately the quantitative behavior of the system in quite a few cases. In fact, this was beyond the expectations for such a heuristic approach.

This is indeed the primary advantage of the sensitive time lag concept, that the complexity of the actual combustion process can be avoided through the use of a very small number of lumped parameters. This is not to say that phenomena, such as droplet breakup, vaporization, mixing, chemical reactions, etc., are not important in determining stability and performance characteristics, but rather that, lacking such specific knowledge, the general nature of the coupling between the chamber conditions and the combustion process may still be described.

According to the Crocco model, the dynamic aspects of the injection-combustion process that are of significance in high frequency instability are characterized by a time lag, which is sensitive to the local, instantaneous values of pressure, temperature, gas velocity, etc. The degree of sensitivity is measured by one or more interaction indices. The sensitive time lag, then, plays the role of the above discussed characteristic time, while the interaction indices, properly combined, hold the key to the magnitude of the energy feedback. Thus, the occurrence of high frequency combustion instability is seen to result from the matching of the sensitive combustion time lag with one of the proper frequencies of the combustion chamber, provided that the degree of sensitivity of the combustion is sufficiently large to offset the damping effects present in the chamber. The stability conditions can then be expressed only in terms of the time lag and the interaction indices, and the ways to stabilization are easily discussed.

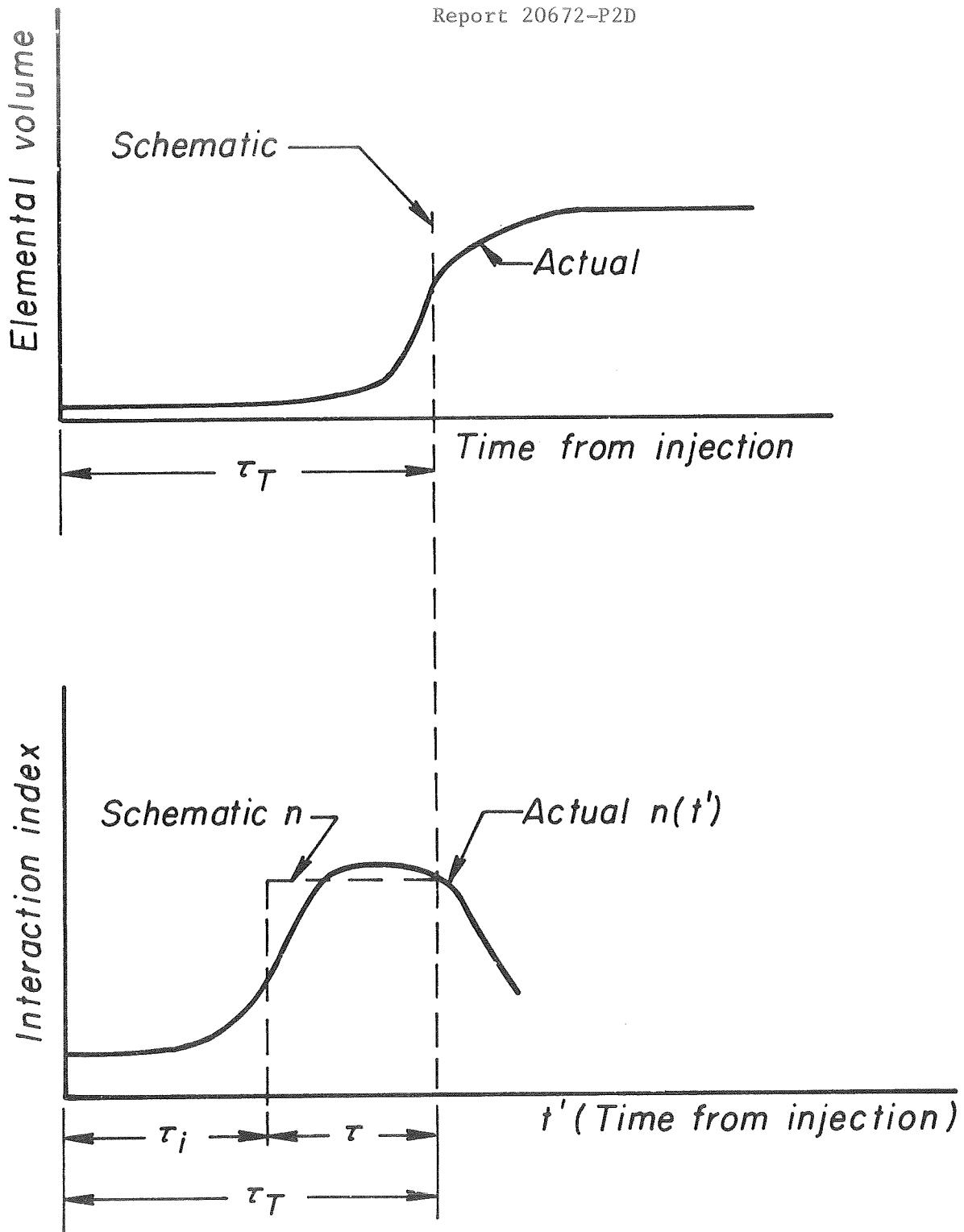


Figure 3 -- Time Lag Schematization

I, B, Technical Description (cont.)

2. The Sensitive Time Lag Concept

The liquid propellant combustion process may be represented schematically as in Figure 3, which shows the volume of a propellant element from the instant of injection until conversion to final combustion products is accomplished. Initially, in the liquid state, the volume is small. The conversion to gaseous products takes place more or less gradually, depending on the degree of atomization, the intensity of mixing, the chemical nature of the reactants, and so on. This gradual change is replaced, for analytical simplicity, by a step function, as shown in Figure 3. This is not to say that the combustion process is thought to occur instantaneously, but that such simplification may reasonably describe the essential nature of the combustion process from a dynamic point of view. The step function approximation of the overall combustion process defines a characteristic time, called the "total time lag" for the propellant element considered and denoted by τ_T . This time, of the order of a few milliseconds, is not representative of the characteristic times of high frequency instability. Rather, the total time lag is basic to the low frequency type of combustion instability. However, the total time lag, together with the velocity history of the injected propellants, determines the space lag, that is, the location in the chamber at which combustion of the particular propellant element is taking place. It is this aspect of the total time lag that cannot be disregarded when considering high frequency instability. This point will be discussed further in a later section. It suffices to say here that the step function approximation is compatible with any combustion distribution in the chamber, since τ_T can be different for different propellant elements.

The lower diagram of Figure 3 illustrates the important concept that not all of the processes that occur during the combustion of liquid propellants are equally affected by the combustion environment. Consider first only the effect of pressure (and correlated temperature) oscillations.

I, B, Technical Description (cont.)

Initially, only liquid streams, ligaments, or relatively large droplets are available in conditions unfavorable to combustion. It is to be expected that pressure perturbations interact only slightly with propellants in that degree of preparation. In the later portion of the preparation phase (as the nominal τ_T value is approached), droplets are small and interspersed; moreover fuel and oxidizer species are mixed. Hence, burning rates are readily influenced by instantaneous pressure changes. This increased sensitivity to disturbances in pressure and temperature is represented on the figure by a higher instantaneous "pressure interaction index", n . The portion of the total time lag that is associated with this high sensitivity can be attributed an approximately constant mean value of the interaction index and is called the "sensitive time lag", denoted by τ . The early portion is referred to as the "insensitive time lag", τ_i , and the corresponding interaction index is taken to be zero. Again, the step-function approximation is useful to reach a simple analytical description. The sensitive time lag is of the order of a few tenths of a millisecond (an order of magnitude smaller than the total time lag). It plays the role in the frequency combustion instability of the "characteristic time" discussed previously. The energy feedback resulting from pressure oscillations can be calculated in terms of τ and the interaction index, n . Similarly the energy feedback resulting from gas velocity oscillations can be calculated in terms of a velocity-sensitive time lag (which may coincide with the one already defined) and of an appropriate "velocity interaction index", and the same would apply to the interaction with other possible physical quantities.

In the schematic representation just discussed two (or more) combustion parameters have been defined that are of key importance to further discussions of high frequency instability. The first is the sensitive time lag, τ , which places the combustion process in proper perspective with the times corresponding to the various acoustic modes associated with the chamber geometry. The second parameter, the interaction index, n (and, possibly, other parameters, representing the additional interaction indices of relevance), must exceed a certain minimum level if the damping is to be balanced and self amplifying or sustained oscillations are to be generated.

I, B, Technical Description (cont.)

These points are further clarified (where only one interaction index is relevant) by a stability diagram using τ as the abscissa and n as the ordinate (Figure 4), relative to the first tangential (1T) mode. As already observed, the resonant behavior of the system is such that the maximum amount of energy feedback is obtained when the ratio of the characteristic time to the oscillation period (in this case of the 1T mode) is around a certain value (which for the present simple combustion model is 1/2). At the corresponding value of τ , evidently, the damping processes can be balanced with the minimum value of n_{\min} . At other values of τ the effectiveness of the feedback process decreases, and hence larger values of n are required to reach the balance, the values increasing with increasing deviations of τ from the value of maximum effectiveness. The curve of Figure 4 represents, for the given mode, the $n-\tau$ combinations for which a balance between feedback and damping is obtained. If, for given τ , n is smaller than the value which produces the balance, perturbations will decay as a result of the excessive damping; if on the contrary n is larger, perturbations will amplify as a result of the excessive feedback. Hence the curve provides the stability boundary between the stable region of Figure 4 (under the curve) and the unstable region (above the curve).

A given combustion system is characterized by a certain value of the interaction index. If this value is less than n_{\min} no instability at all is possible. If the interaction index is just equal to n_{\min} , then instability is possible, but only if the matching of the proper time of the chamber and the characteristic combustion time is perfect. For $n > n_{\min}$ the time-matching requirement is less stringent, i.e., a certain mismatch of the times will still result in instability. As the value of n increases, the amount of allowable mismatching also increases.

For other modes than the 1T mode, the stability boundary can be represented in a similar way, the scale of τ properly shifted. Putting the stability boundaries corresponding to different modes on the same plot results

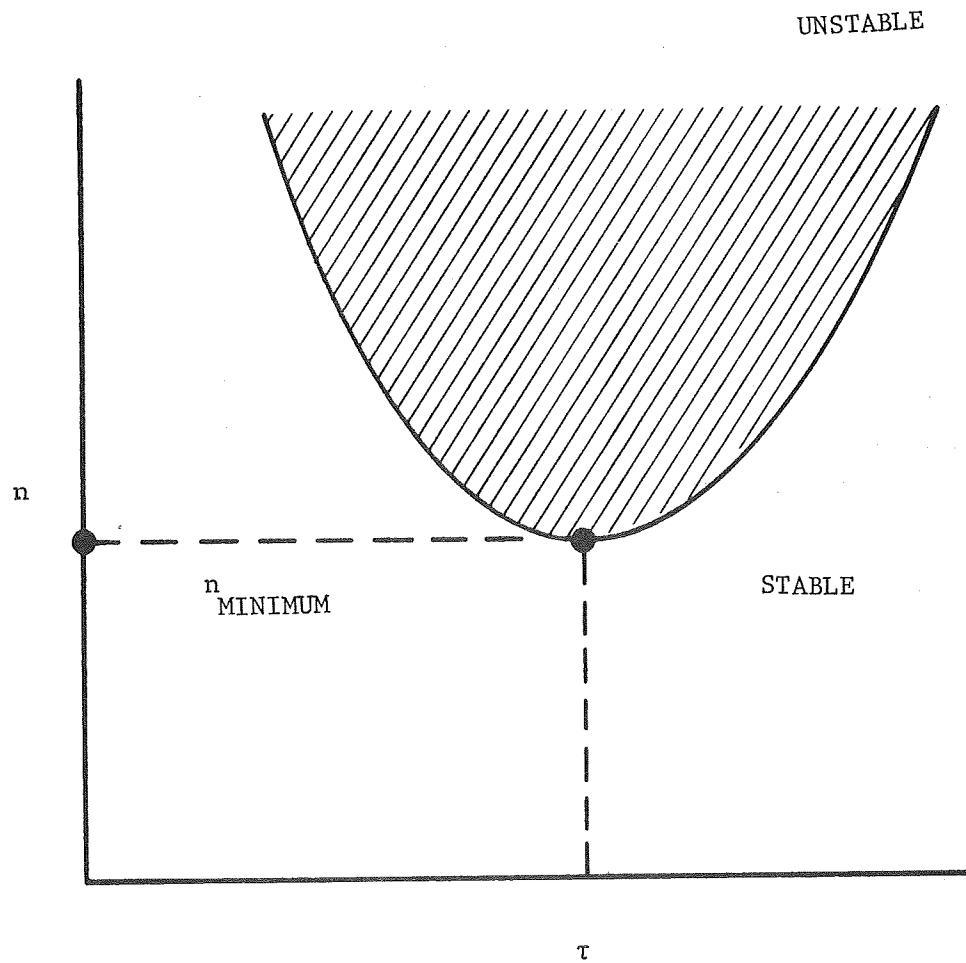
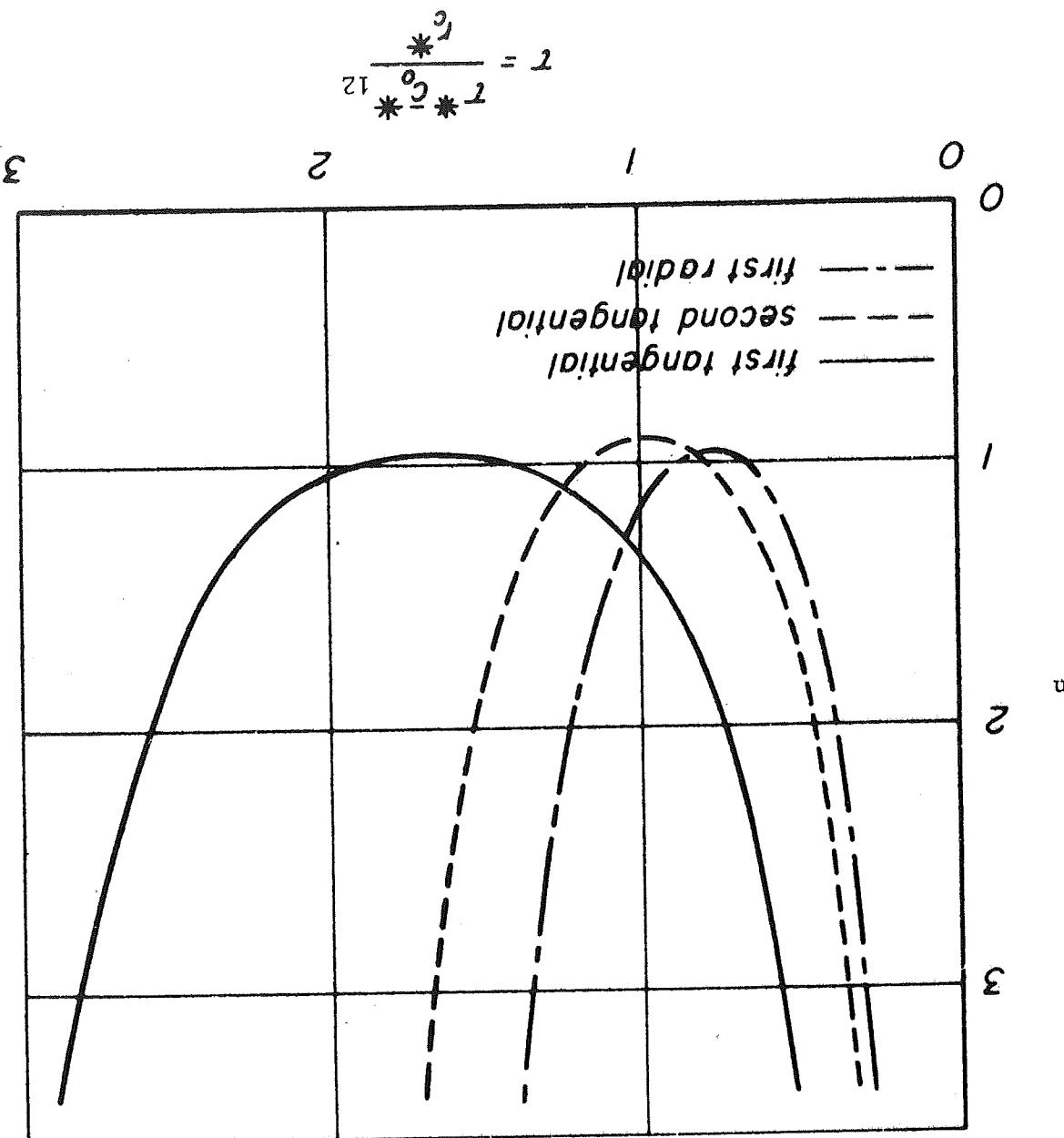


Figure 4 -- Stability Diagram, n , τ , - Plane

Figure 5 -- Theoretical Stability Limits for Several Purely Transverse Modes



$$\bar{U}_0 = 0.10$$

uniformly distributed combustion,

I, B, Technical Description (cont.)

in Figure 5, where an overall stability region, regardless of mode, is now evident. Plots of this kind are fundamental to the methods to be discussed extensively in this report. However, two remarks, to be substantiated later, should be made.

The first remark is that such a clearcut boundary between stability and instability is obtained only if the perturbations are assumed to be of small amplitude. This is indeed the assumption on which most of the theoretical developments on combustion instability have been based. Within this assumption all effects of the perturbations can be assumed to vary linearly with the perturbation amplitudes, the mathematical treatment is accordingly substantially simpler, and the (linear) stability boundary unequivocally defined, the linearly unstable region being practically interpreted as that in which oscillations grow spontaneously out of the random combustion noise. However, in real practice the perturbations are not necessarily limited to the range where all of their effects vary linearly with the amplitude, and when the contrary happens important nonlinear effects may appear. Some effects of nonlinearity can be derived theoretically, at the cost of substantial mathematical complexities. But what is important to the present qualitative discussion is that, while the linearly unstable region always remains a region of instability, the corresponding statement for the linearly stable region is not true. In other words, a system corresponding in the $n-\tau$ plane to a point of the linearly stable region may be triggered into amplifying or self-sustaining oscillations by a perturbation (for instance, a pulse) of sufficiently large amplitude. Only if the pulse remains under a certain critical level do the resulting oscillations decay - in agreement with the predictions of the linear theory. This nonlinear behavior plays an important role in rockets, and has to be taken into account when interpreting the experimental results.

I, B, Technical Description (cont.)

The second remark is that the curves of Figures 4 and 5 depend not only on the chamber and nozzle geometries, but also on the transverse and longitudinal distributions of combustion, the first being substantially determined by the distribution of the injection flux across the injector, the second by the details of the individual combustion processes (such as atomization, evaporation, mixing and chemical reactions, recirculation flow, etc.). The significance of the total time lag τ_T in this connection has been mentioned already. Large values of τ_T , other factors being equal, will spread the combustion toward the nozzle end of the chamber. If the total time lag is too large for the chamber in question, performance will suffer because of incomplete burning prior to the nozzle entrance. Since the region of maximum combustion is closely associated with the region where propellants have reached the sensitive state in the preparation process, it is in this general location that interaction between the combustion process and the acoustic modes reaches a maximum level.

For the fundamental longitudinal mode, pressure antinodes are found at the injector and the nozzle end of the chamber, as shown in Figure 6. Higher harmonics will have additional pressure antinode locations. If combustion is uniformly distributed from one end of the chamber to the other, maximum instability coupling cannot take place since there is a region (or regions, in the harmonics) in which a pressure nodal environment is approached. If the wave is sinusoidal, a true node is found; otherwise, only an oscillation with reduced amplitude will be observed. The limiting case of a non-sinusoidal wave is that of a shock wave, the amplitude variation of which is shown in Figure 6. In the nodal region, even with proper time phasing, too little energy is available from the increased burning rate to cause the pressure oscillations to be amplified. However, if combustion is concentrated at the injector end, the best environment for energy transfer to the pressure oscillations is provided.

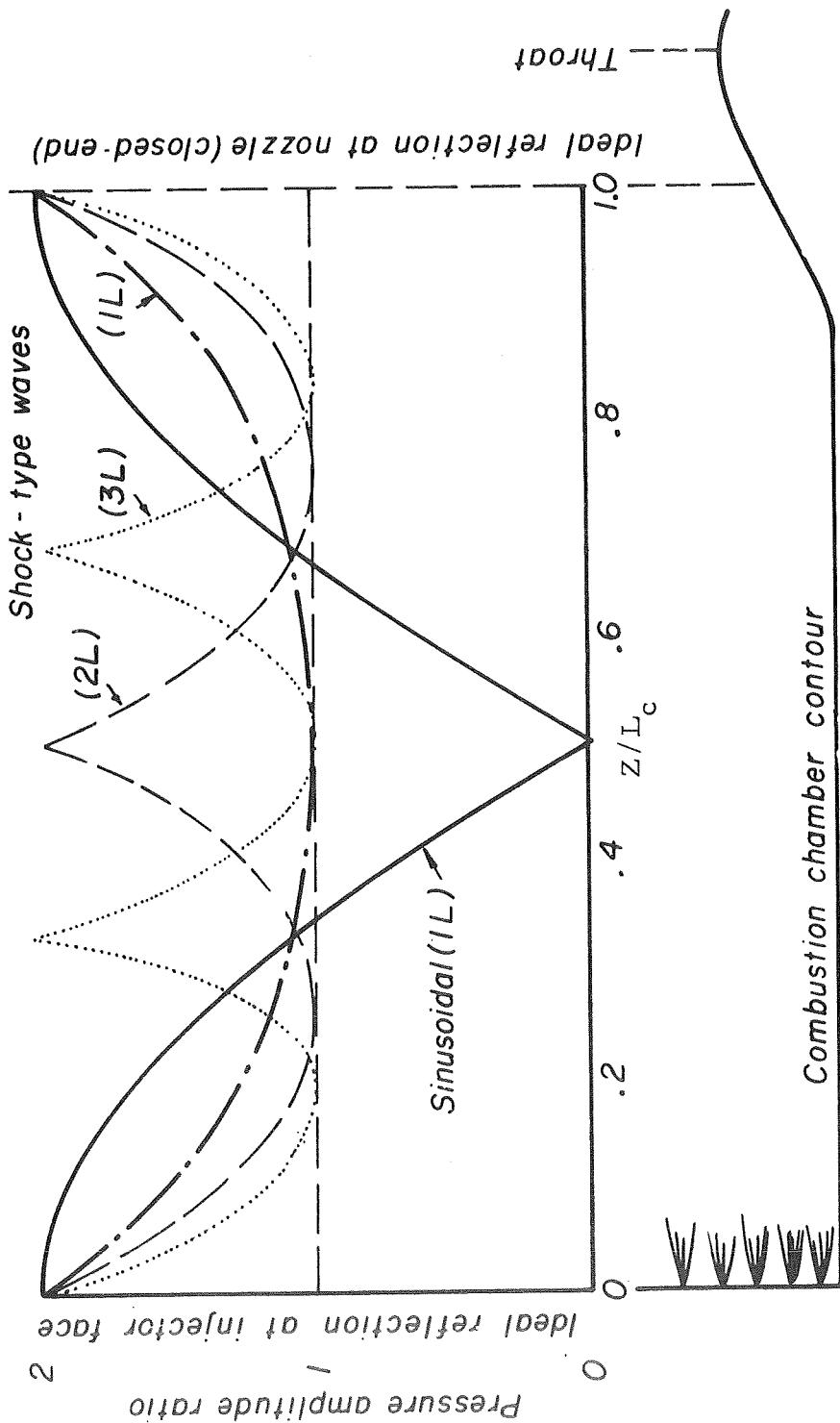


Figure 6 -- Axial Pressure Variations for Several Longitudinal Modes

I, B, Technical Description (cont.)

The steady state combustion rate is approximately proportional to the rate of change of axial gas velocity with distance from the injector. Typical velocity profiles are shown in Figure 7. Two extremes are apparent: (1) the concentrated combustion case in which near-maximum gas velocities are produced within a short distance from the injector, as shown by curve "A", and (2) the nearly uniform combustion case in which the axial velocity curve is nearly linear, as represented by curve "B". Rocket experience has shown that the actual velocity distributions fall within these extremes. Thus, combustion concentrated near the nodal point and combustion concentrated near the antinode at the nozzle end are both unrealistic situations.

The transverse modes may also be discussed on a somewhat similar basis. Experimental measurements at a number of laboratories have shown that maximum amplitudes for the tangential modes are always found at the injector end. Thus, to reduce coupling, axially distributed combustion can offer considerable improvement as compared to the concentrated combustion case, just as was found for the longitudinal mode. In the radial direction the combustion distribution picture is more complicated. As shown in Figure 8, pressure oscillation amplitudes vary radially, and the vibration is strongly dependent on the mode. The first and second tangential modes are similar to each other but quite different from the first radial mode. To promote instability in the first tangential mode, assuming that the n , τ values are suitable, one would choose an injector design that would provide rapid burning (i.e., small τ_T , to keep the combustion near the injector face) and would have the injection orifices concentrated at the outer radii. Either spreading the combustion axially or moving the injection toward the center of the chamber would reduce the degree of coupling. If the first radial mode is also considered, then a compromise location near the half-radius point would prove to be the best injection point. This principle has been verified in an investigation of a number of injection distributions by the Aerojet-General Corporation using high-thrust hardware (Ref 2).

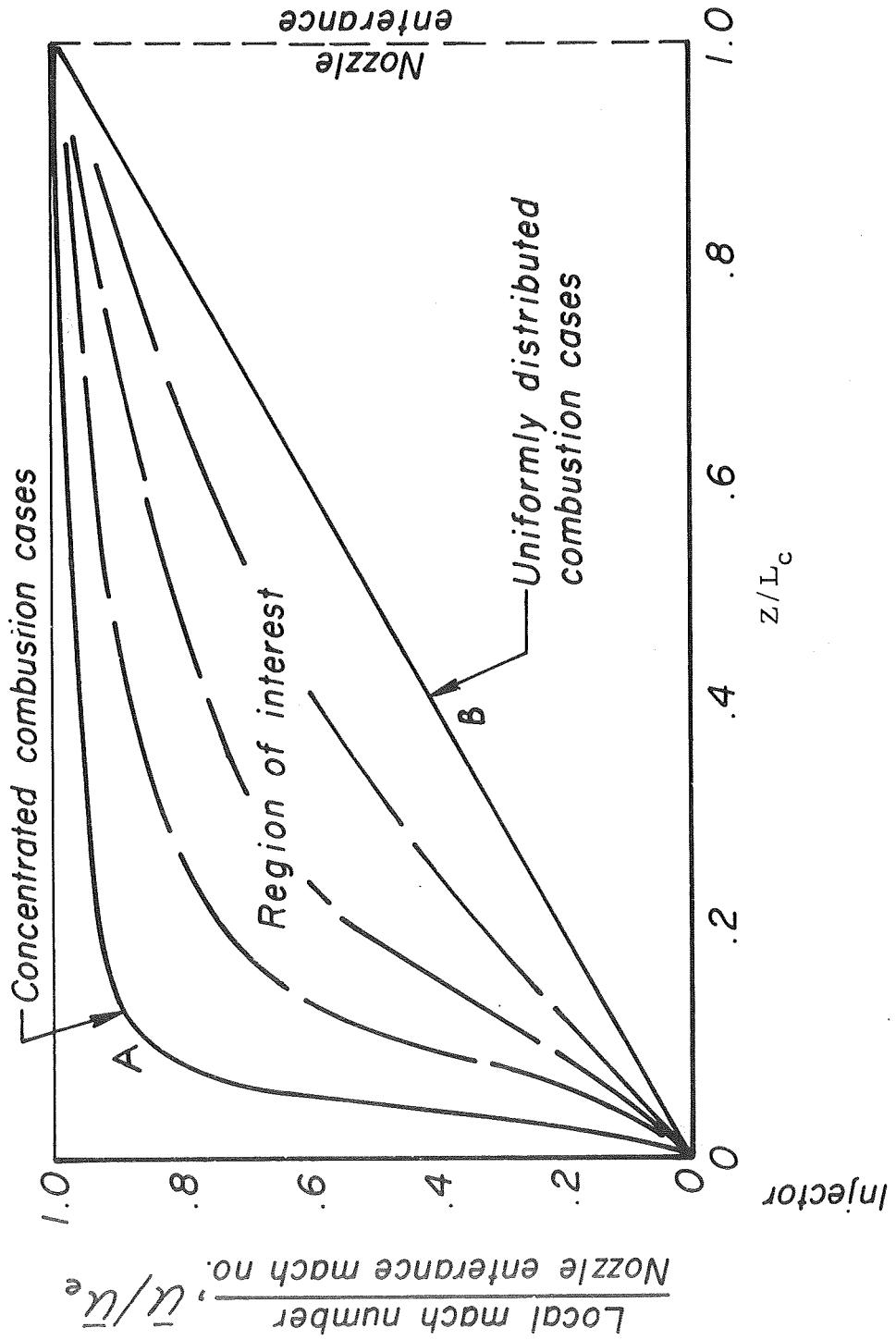


Figure 7 -- Typical Combustion Distributions

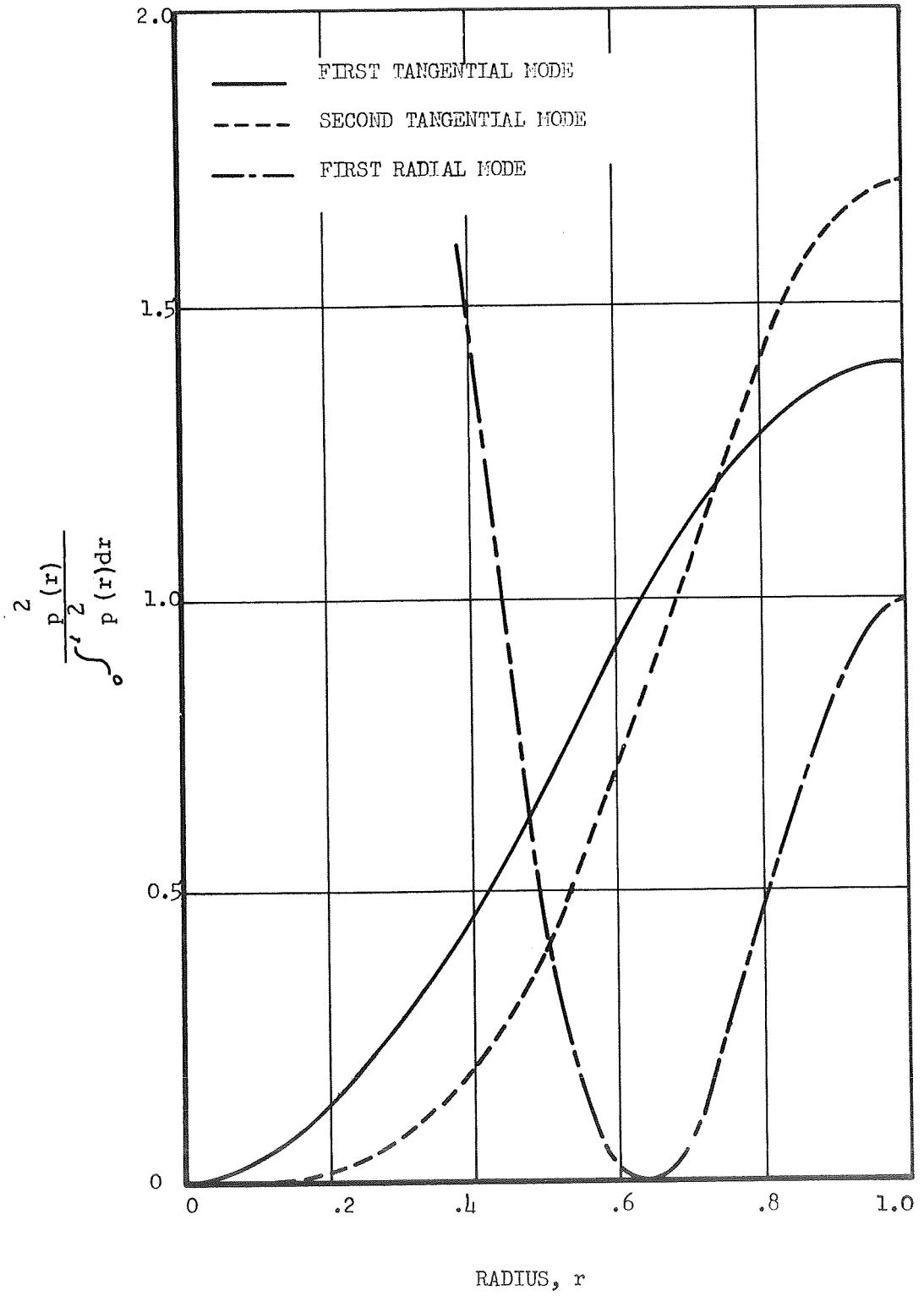


Figure 8 -- Pressure Non-Uniformity Coefficient for Concentrated Combustion

I, B, Technical Description (cont.)

The qualitative discussion just given is based on the assumption that there is only one relevant interaction index. When more than one has to be taken into account, the effect of each additional interaction index produces a displacement of the stability boundaries in the $n-\tau$ plane, and the interpretation becomes correspondingly more difficult. Effects of this kind are found, for instance, when the combustion rates are sensitive to the transverse velocity perturbations characteristic of transverse oscillations. One can visualize important coupling mechanisms related to the inequalities in the displacements of liquid drops and propellant vapors that are produced by such oscillations. The local mixture ratio can be altered, with resulting changes in the burning rate, if one of the propellants is displaced with respect to the other. Even with unlike-impinging injector elements such an effect exists, but it may be especially significant in like-on-like designs, where the fact that a certain level of displacement must be reached before significant alterations of mixture ratio occur, may result in a particular type of triggering into nonlinear instability.

It is interesting in this connection to observe that this effect may be particularly intense in the region immediately adjacent to the injector where one can expect droplets and vapors to be present in abundance, and in very unmixed conditions. Thus, it is clear that in the use of baffles and liners there must be a consideration of the combustion distribution in the chamber. In general, it has been found that for tangential modes the oscillation amplitudes are greatest at the injection end of the chamber, combustion rates are maximum a few inches from the injector and coupling between the combustion process and tangential waves is greatest in the outer regions of the injector face. If the chamber volume is subdivided by baffles, the dimensions of the cavities between baffles determine the period of oscillation. Combining these principles, it is concluded that if baffles are to be used to control tangential modes they must be placed at the injector end, they must

I, B, Technical Description (cont.)

protect the preparation zone found in the first few inches downstream of the injector, they must extend as close as possible to the chamber wall, and the circumferential blade spacing must be small enough to prevent cavity modes from existing. Similarly, acoustic liner orifices are most effective near the injector end of the chamber, and liner absorption characteristics must be designed to match the resonance properties of the chamber and the combustion process, as described by the sensitive time lag theory.

3. Development of the Sensitive Time Lag Theory

The historical background of the development of the sensitive time lag theory is important to the understanding of the concepts described in the preceding section. The earliest published paper on combustion instability theory was that of Gunder and Friant (Ref 3) in 1950, with a subsequent discussion by Yachter (Ref 4). Probably the most important contribution of these early treatments was the introduction of the concept of a combustion time lag (conceived independently, but not published, by other groups) between the instant of injection of a propellant element and the succeeding instant of burning, in which the propellant element is transformed into hot gas capable of contributing to the chamber pressure.

Interest at Princeton University in the problem of combustion instability in liquid propellant rocket motors was given impetus by a Bureau of Aeronautics Symposium held at the Naval Research Laboratory in December, 1950. This interest resulted in theoretical analyses by Professors Summerfield and Crocco.

Professor Summerfield's work (Ref 5) considered the effects of inertia in the propellant feed lines and the capacitance of the combustion chamber, assuming a constant combustion time lag. His analysis treated the case of low frequency oscillations for frequencies up to about 200 cps.

I, B, Technical Description (cont.)

Professor Crocco advanced the concept of the pressure dependence of the combustion time lag. His paper (Ref 1) presented the fundamentals resulting from this concept. In his paper, Crocco treated the case of low frequency instability in a bipropellant rocket, and also the case of high frequency instability with combustion concentrated at the injector end of the combustion chamber.

The analytical work on the high frequency case was continued by S. I. Cheng under the direction of Professor Crocco. His studies of the effects of the axial distribution of combustion (on the longitudinal modes) were published as his Ph.D. thesis. A thorough discussion of these and other aspects of the theory was published by Crocco and Cheng in 1956 as an AGARD monograph (Ref 6). The general theories of low and longitudinal high frequency instability, the effects of the combustion distribution, the influence of the exhaust nozzle, as well as the (scarce) experimental evidence substantiating the analyses were all discussed at length. A brief discussion of the transverse modes of combustion instability was included, and general adherence to the sensitive time lag model was predicted.

The extension to the transverse modes was initiated by S. M. Scala (Ref 7). Following Crocco's pressure dependence model, he determined the fundamental behavior of the transverse modes, including the influence of the nozzle. In addition, Scala treated the case of intermediate frequency instability, in which the coupling mechanism consists of entropy perturbations, generated by off-design mixture ratio combustion, which reflect from the nozzle as pressure waves and propagate back to the injector to cause perturbations in the injection rates.

I, B, Technical Description (cont.)

The study of transverse instability was continued by F. H. Reardon (Ref 8), who developed several extensions to the basic theory to explain certain experimental results (which are discussed in the following section). The sensitive time lag concept was extended to include sensitivity to the transverse components of the oscillating gas velocity. The effect on the combustion rate was visualized in the oscillatory displacement of the vapors of one propellant with respect to the liquid droplets of the other. In addition, Reardon introduced an approximate treatment of the effects of nonuniform distribution of propellant injection on the transverse modes, and applied the modified theory to a sector-shaped combustor, which simulates the "pocket-mode" behavior of a baffled chamber.

I, B, Technical Description (cont.)

4. Theory

a. General Approach

The simplifying assumptions on which the mathematical treatment of combustion instability is based are the following:

(1) The substance contained in the combustion chamber is either in the form of liquid propellants, of practically zero volume, or in the form of complete combustion gases. It will be noticed that this assumption disregards the contribution of the propellants in vapor form, and of the intermediate products of combustion. Hence the assumption is equivalent to saying that not only the liquids, but also the vapors and the intermediates occupy a negligible volume compared to the final products of combustion. This assumption (first used by Crocco in Ref. 1) is actually in agreement with the step-function combustion model discussed in Section I. Even more important, it represents quite well the actual conditions in rockets where indeed, with the exception of the region immediately adjacent to the injector, practically the same gas temperature is observed throughout the chamber. Of course, it is clear that the above is true when using liquid propellants, and not for the combustion of gaseous propellants. The difference is that while in the latter case there is a constant mass flux with energy addition, in the case of liquid propellants the gas flow has a variable mass flux with energy addition being produced through an addition of mass to the gaseous flow.

(2) The combustion gases are of constant composition, they obey the perfect gas law and have constant specific heats.

(3) Frictional effects on the walls are neglected, and only those are taken into account which result in the liquid droplet drag.

I, B, Technical Description (cont.)

Also, Reynolds stresses associated with the high turbulence level caused by combustion are neglected, in spite of the fact that they may play an important role with respect to the uniformity assumption (Assumption 5).

(4) The flow of injected propellants is unaffected by oscillations in the chamber, and hence the injection flux and velocity are always the same as in steady conditions. This assumption is not necessarily verified in actual rockets where, especially for large rockets, the possibility of matching the wave propagation times in the feed lines and in the chamber may lead to interactions. However, the assumption is rather good if matching is avoided, and substantially simplifies the treatment by making the chamber behavior independent of the feed system varieties and complexities. The resulting instability problem has been termed "intrinsic instability" of the combustion chamber.

(5) The steady-state gas flow is uniform across any chamber section. This is possible partly because the previous assumption allows the boundary layer formation on the walls to be disregarded. However, it involves more. For instance, it would require the injected propellants to be uniformly distributed so as to produce no recirculation. Of course, this is not the actual situation, and the uniform flow considered in the theory should be interpreted as an average flow from which the actual flow can depart substantially if the injection is far from being uniform. For large rockets the injection systems are generally rather uniform, and hence the uniformity assumption can be quite accurate. However, it will be seen in the following that transverse stability conditions can be improved by using particular non-uniform injection systems. It is felt that the contradiction that results in these cases is not very important for not too large flow Mach numbers because of the strongly equalizing effects of the high turbulence due to combustion.

I, B, Technical Description (cont.)

(6) In steady-state, the total energy (internal and kinetic) of the droplets remains constant. Obviously this is not exactly true, because of the heat exchanges affecting the internal energy and the droplet drag affecting the kinetic energy in ways that are not so simply related. The assumption has, however, the advantage of providing a substantial simplification of the treatment, and it is believed not to hide any of the fundamental effects.

(7) The steady-state flow in the nozzle is one-dimensional. Although not true, this assumption is known to result in very accurate predictions concerning the steady flow itself. Here, however, the same assumption is extended to the treatment of the oscillatory nozzle flow obtained when the steady flow is perturbed. It should be observed that this assumption is consistent with that of uniform steady flow in the chamber (Assumption 5).

(8) The unsteady, oscillatory quantities in the chamber and in the nozzle can be obtained by superposing small perturbations to the steady-state quantities. By "small" is meant as usual, that only "linear" (first order) terms in the perturbations are to be retained, while terms containing products or powers of perturbations (second and higher order) are to be neglected. The great advantage of this assumption is of a mathematical nature, since the resulting equations, being linear, can be treated in a much simpler way. One of the implications is that a harmonic time dependence can be chosen, as discussed under Assumption 10. But, of course, the disadvantage is that only the linear effects can be accounted for, all the nonlinear effects being left out. Under the small perturbation assumption only the "linear" stability problem can be attacked.

(9) The gas flow Mach number is always sufficiently small so that the square can be neglected compared to unity. Because of this assumption, the analysis cannot be applied to thrust chambers in which the Mach

The equations governing the unsteady, two-phase flow in the combustion chamber are derived from the principles of conservation of mass, momentum, and energy, and the equation of state, according to the assumptions discussed in the previous section. It is convenient to work with the equations in nondimensional form. The reference quantities for the nondimensionalization are taken as the stagnation gas properties at the injector face (pressure, temperature, density, and speed of sound) together with a dimensionless parameter in the form of the ratio of the total enthalpy to the total entropy.

(1) General Equations

b. Governing Equations

(10) The time dependence of the perturbations can be expressed in complex form as $\exp(\omega t)$ where $\omega = \alpha + i\omega$ is the same complex quantity for all perturbations. Here ω is the angular frequency and α the amplitude coefficient. As usual when using the complex representation each perturbation is obtained by multiplying the above exponential by a complex quantity which is a function of the space coordinates only, and by taking the real part of the result. The assumption of exponential time dependence is common in problems of linear stability. It does not affect the generality of the result, since within the linear frame work the development of independent components each behaving exponentially, and since superposition of independent components each behaving exponentially, and since, from the point of view of stability, the only thing that matters is that no single component should show amplification. Hence all the information required is the behavior of exponentially varying perturbations when the frequency is made to change over all possible values.

Such is not an essential assumption; its relaxation leads only to complexity. This assumption does not apply to the longitudinal analysis.

I, B, Technical Description (cont.)

I, B, Technical Description (cont.)

reference length, which is the chamber radius for transverse modes. (The chamber length is generally used for longitudinal modes). The governing equations take the following forms:

Conservation of mass,

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho q) = Q = - \frac{\partial \rho_L}{\partial t} - \nabla \cdot (\rho_L q_L) \quad (1)$$

Conservation of momentum,

$$\rho \frac{\partial q}{\partial t} + \rho q \cdot \nabla q + \frac{1}{\gamma} \nabla p = (Q + \kappa \rho_L) (q_L - q) \quad (2)$$

Conservation of energy,

$$\rho \frac{\partial h_s}{\partial t} + \rho q \cdot \nabla h_s - \frac{\gamma-1}{\gamma} \frac{\partial p}{\partial t} = Q (h_{Ls} - h_s) \quad (3)$$

Equation of state for the gas,

$$p = \rho T \quad (4)$$

Droplet drag (gas/liquid momentum interchange) using Stokes law,

$$\frac{\partial q_L}{\partial t} + q_L \cdot \nabla q_L = \kappa (q - q_L) \quad (5)$$

And droplet energy,

$$\frac{\partial h_{Ls}}{\partial t} + q_L \cdot \nabla h_{Ls} = 0 \quad (6)$$

I, B, Technical Description (cont.)

The symbols used in these equations are defined in Section I.D.

It is necessary to express the governing equations, (1) to (6), in steady state form and perturbed form. The separation is accomplished by writing all the dependent variables, as the sum of a steady state solution and an unsteady solution. For example,

$$p = \bar{p} + p' e^{\sigma t} \quad (7)$$

$$u = \bar{u} + u' e^{\sigma t}$$

It is noted that the perturbed portion of each parameter is harmonic with respect to time.

(2) Steady State Equations

The steady state solution is assumed to be one dimensional although the perturbations are considered in three dimensions. Therefore, the steady state vectorial components of gas velocity, \mathbf{q} and liquid velocity, \mathbf{q}_L are given by the following relationships:

$$\begin{aligned} \overrightarrow{q} &= \overrightarrow{u}, \quad \overrightarrow{q_L} = \overrightarrow{u_L} \\ \overrightarrow{v} &= \overrightarrow{w} = \overrightarrow{v_L} = \overrightarrow{w_L} = 0 \end{aligned} \quad (8)$$

where u, u_L are the axial components, v, v_L are the radial components, and w, w_L are the tangential components of \mathbf{q}, \mathbf{q}_L .

I, B, Technical Description (cont.)

Substituting the relationships given by (7) and (8) into (1) to (6) and neglecting the time dependence yields the following system of steady state equations:

Conservation of mass

$$\frac{d}{dz} (\bar{\rho} \bar{u}) = \bar{Q} = - \frac{d}{dz} (\bar{\rho}_L \bar{u}_L) \quad (9a)$$

Conservation of momentum

$$\frac{d}{dz} (\bar{\rho} \bar{u}^2) + \frac{d}{dz} (\bar{\rho}_L \bar{u}_L^2) = - \frac{1}{\gamma} \frac{dp}{dz} \quad (9b)$$

Conservation of energy

$$\bar{\rho} \bar{u} \frac{dh_s}{dz} = - \bar{Q} (\bar{h}_s - \bar{h}_{Ls}) \quad (9c)$$

Equation of state (gas)

$$\bar{p} = \bar{\rho} \bar{T} \quad (9d)$$

Droplet drag

$$\bar{u}_L \frac{du_L}{dz} = \kappa (\bar{u} - \bar{u}_L) \quad (9e)$$

Droplet energy

$$\frac{dh_{Ls}}{dz} = 0 \quad (9f)$$

I, B, Technical Description (cont.)

It should be noted that at $Z = 0$, $u = 0$ and $\bar{p} = \bar{\rho} = 1$ because of the nondimensionalizing scheme. At $Z = L_c$, combustion is assumed to be complete so that $\bar{\rho}_L = 0$ and $\bar{Q} = 0$.

(3) The Perturbation Equations: Wave Equations

The perturbed equations are considered in three dimensional form in cylindrical coordinates and the resulting system of equations is linearized. That is, the perturbed quantities are considered to be small, and therefore, all products of two or more perturbed terms are considered to be zero. Substituting equations (7) and (8) into equations (1) to (6) yields the following system of equations.

$$\begin{aligned} (\sigma + \frac{du}{dz}) \rho' + \bar{u} \frac{\partial \rho'}{\partial z} + \frac{d\bar{\rho}}{dz} u' + \bar{\rho} (\frac{\partial v'}{\partial r} + \frac{v'}{r} \\ + \frac{1}{r} \frac{\partial w'}{\partial \theta} + \frac{\partial u'}{\partial z}) = \bar{Q} (P_p' + Rv' + Tw') \end{aligned} \quad (11a)*$$

where

$$P = n (1 - e^{-\sigma T}), R = 1_r (1 - e^{-\sigma T}) = \frac{1_r}{n} P, \text{ and } T = 1_\theta (1 - e^{-\sigma T}) = \frac{1_\theta}{n} P$$

Conservation of axial momentum

$$\begin{aligned} (\sigma \bar{u} + 2\bar{u} \frac{du}{dz}) \rho' + (\sigma \bar{u}_L + 2\bar{u}_L \frac{du_L}{dz}) \rho'_L + \bar{u}^2 \frac{\partial \rho'}{\partial z} + \bar{u}_L^2 \frac{\partial \rho'_L}{\partial z} \\ + (\sigma \bar{\rho} + 2\bar{\rho} \frac{du}{dz} + 2\bar{u} \frac{d\rho}{dz}) u' + (\sigma \bar{\rho}_L + 2\bar{\rho}_L \frac{du_L}{dz} + 2\bar{u}_L \frac{d\rho_L}{dz}) u'_L \\ + 2\bar{\rho} \bar{u} \frac{\partial u'}{\partial z} + 2\bar{\rho}_L \bar{u}_L \frac{\partial u'_L}{\partial z} + \bar{\rho} \bar{u} (\frac{\partial v'}{\partial r} + \frac{v'}{r} + \frac{1}{r} \frac{\partial w'}{\partial \theta}) \\ + \bar{\rho}_L \bar{u}_L (\frac{\partial v'_L}{\partial r} + \frac{v'_L}{r} + \frac{1}{r} \frac{\partial w'_L}{\partial \theta}) = - \frac{1}{\gamma} \frac{\partial p'}{\partial z} \end{aligned} \quad (11b)$$

*Equation 10 is an intermediate step deleted during revision.

I, B, Technical Description (cont.)

Conservation of radial momentum

$$\begin{aligned}
 & (\bar{\sigma\rho} + \bar{\rho} \frac{du}{dz} + \bar{u} \frac{d\rho}{dz}) v' + (\bar{\sigma\rho}_L + \bar{\rho}_L \frac{du}{dz} + \bar{u}_L \frac{d\rho_L}{dz}) v'_L \\
 & + \bar{\rho} \bar{u} \frac{\partial v'}{\partial z} + \bar{\rho}_L \bar{u}_L \frac{\partial v'_L}{\partial z} = - \frac{1}{\gamma} \frac{\partial p'}{\partial r}
 \end{aligned} \tag{11c}$$

Conservation of tangential momentum

$$\begin{aligned}
 & (\bar{\sigma\rho} + \bar{\rho} \frac{du}{dz} + \bar{u} \frac{d\rho}{dz}) w' + (\bar{\sigma\rho}_L + \bar{\rho}_L \frac{du}{dz} + \bar{u}_L \frac{d\rho_L}{dz}) w'_L \\
 & + \bar{\rho} \bar{u} \frac{\partial w'}{\partial z} + \bar{\rho}_L \bar{u}_L \frac{\partial w'_L}{\partial z} = - \frac{1}{\gamma r} \frac{\partial p'}{\partial \theta}
 \end{aligned} \tag{11d}$$

Conservation of energy and equation of state, combined

$$\begin{aligned}
 & (\bar{\sigma\rho} + \bar{Q} - \bar{u} \frac{dp}{dz}) \rho' + \bar{\rho} \bar{u} \frac{\partial \rho'}{\partial z} - (\gamma - 1) \bar{\rho} \bar{u} (\bar{\sigma\rho} + \bar{Q} + \bar{\rho} \frac{du}{dz}) u' \\
 & - (\gamma - 1) (\bar{\rho} \bar{u})^2 \frac{\partial u'}{\partial z} = (\sigma \frac{\rho}{\gamma} + \bar{Q} - \bar{u} \frac{dp}{dz}) p' + \bar{\rho} \bar{u} \frac{\partial p'}{\partial z}
 \end{aligned} \tag{11e}$$

Droplet dynamics

defining $K = \frac{\kappa}{\kappa+\sigma}$

and $\xi = (\kappa+\sigma) \int \frac{dz}{u_L}$

then

$$u'_L = Ku' - \frac{K}{u_L} e^{-\xi} \left[\int_0^Z \frac{du_L}{dz} e^{\xi} u' dz + \int_0^Z \bar{u}_L e^{\xi} \frac{\partial u'}{\partial z} dz \right] \tag{11f}$$

I, B, Technical Description (cont.)

$$v'_L = K (1-e^{-\xi}) v' - K e^{-\xi} \int_0^Z e^{\xi} \frac{\partial v'}{\partial Z} dZ \quad (11g)$$

$$w'_L = K (1-e^{-\xi}) w' - K e^{-\xi} \int_0^Z e^{\xi} \frac{\partial w'}{\partial Z} dZ \quad (11h)$$

$$\begin{aligned} & (\sigma + \frac{du}{dZ}) \rho' + (\sigma + \frac{du_L}{dZ}) \rho'_L + \bar{u} \frac{\partial \rho'}{\partial Z} + \bar{u}_L \frac{\partial \rho'_L}{\partial Z} \\ & + \bar{\rho} \left(\frac{\partial v'}{\partial r} + \frac{v'}{r} + \frac{1}{r} \frac{\partial w'}{\partial \theta} + \frac{\partial u'}{\partial Z} \right) + \bar{\rho}_L \left(\frac{\partial v'_L}{\partial r} + \frac{v'_L}{r} \right. \\ & \left. + \frac{1}{r} \frac{\partial w'_L}{\partial \theta} + \frac{\partial v'_L}{\partial Z} \right) + \frac{dp}{dZ} u' + \frac{dp_L}{dZ} u'_L = 0 \end{aligned} \quad (11i)$$

In general, separation of variables is not possible with these equations. A solution can be obtained by writing each quantity in a series such that each successive term in the series is less than its predecessor. Therefore, the pressure perturbation is written in the form

$$p' = p_0 + p_1 + p_2 + p_3 + \dots + p_n + \dots \quad (12)$$

where p_0 can assume any magnitude within the restrictions of the analysis. Then $p_1 = 0$ ($u_e \cdot p_0$)*, $p_2 = 0$ ($\bar{u}_e^2 \cdot p_0$) and $p_n = 0$ ($\bar{u}_e^n \cdot p_0$) where \bar{u}_e is essentially the chamber Mach number. Applying this approach to equations (11a) through (11i), collecting terms of like order, and solving for the pressure results in wave equations for p_0 and p_1 :

$$\sigma^2 p_0 - \nabla^2 p_0 = 0 \quad (13a)$$

* This notation is used to indicate the order of magnitude of a given parameter.

I, B, Technical Description (cont.)

$$\sigma^2 p_1 - \nabla^2 p_1 = \sigma\gamma \bar{Q} (P p_0 - R \frac{1}{\sigma\gamma\rho} \frac{\partial p_0}{\partial r} - T \frac{1}{\sigma\gamma\rho\theta} \frac{\partial p_0}{\partial\theta}) - \sigma \left[2 \frac{du}{dz} + (\gamma-1) \frac{\bar{Q}}{\rho} + \sigma \frac{\kappa}{\kappa+\sigma} \frac{\rho_L}{\rho} \right] p_0 \quad (13b)$$

For a cylindrical chamber the solutions of (13a) and (13b) are given by

$$p_0(z, r, \theta) = P_{oo} \cosh(\Omega z) \psi(r) \theta(\theta) \quad (15a)^*$$

$$p_1(z, r, \theta) = P_{oo} (\Gamma_{11} P + \Gamma_{10}) \psi(r) \theta(\theta) \quad (15b)$$

where

$$\psi(r) = J_v(s_{vn} \cdot r) \quad (15c)$$

$$\theta(\theta) = \begin{cases} \cos v \theta & \text{STANDING MODE} \\ e^{-v\theta} & \text{SPINNING MODE} \end{cases} \quad (15d)$$

and J_v represents the Bessel function of the first kind of order v (see Table I)

Also,

$$\Gamma_{11} = \frac{1}{\Omega} (-\sigma\gamma A_{vn} + \frac{1}{n} r B_{vn} + \frac{1}{n} l_\theta C_{vn}) \int_0^Z \bar{Q}(\zeta) \sinh[\Omega(z-\zeta)] d\zeta \quad (15e)$$

where

$$\Omega^2 = \sigma^2 + s_{vn}^2$$

the factors A_{vn} , B_{vn} and C_{vn} are discussed in Section B.4.b.(5).

* Equation 14 is an intermediate step deleted during revision.

I, B, Technical Description (cont.)

$$\begin{aligned} r_{10} = \frac{\sigma}{\Omega} & \left\{ (\gamma-1) \int_0^z \bar{Q}(\zeta) \sinh [\Omega(z-\zeta)] d\zeta \right. \\ & + 2 \int_0^z \frac{du}{dz}(\zeta) \sinh [\Omega(z-\zeta)] d\zeta \\ & \left. + \frac{\kappa\sigma}{\kappa+\sigma} \int_0^z \frac{\bar{\rho}_L}{\bar{\rho}}(\zeta) \sinh [\Omega(z-\zeta)] d\zeta \right\} \end{aligned} \quad (15f)$$

These solutions depend on the following boundary conditions:

$$z = 0, \quad u' = 0$$

$$r = 1, \quad v' = 0$$

$$r = 0, \quad v' < \infty$$

To complete the analysis, the combustion terms must be considered in detail, and the boundary condition at the nozzle entrance (viz., the nozzle admittance condition) must be specified.

For an annular chamber the modification to the cylindrical chamber analysis imposed by the annular geometry enters through the solution for $\psi(r)$. The differential equation for $\psi(r)$ is the classic Bessel equation which results in the following general solution:

$$\psi_{vn}(r) = C_1 J_v(s_{vn} \cdot r) + C_2 Y_v(s_{vn} \cdot r) \quad (16)$$

where J_v is the Bessel function of the first kind, Y_v is the Bessel function of the second kind, and s_{vn} (where v specifies the order of the Bessel equation) is the transverse acoustic mode number. Specifically, this means that at all chamber walls

I, B, Technical Description (cont.)

$$\frac{d\psi_v}{dr} = 0 \quad (16a)$$

Applying this condition to (16) yields

$$\psi'_v = 0 = J'_v (s_{vn} \cdot r_c) + \frac{C_2}{C_1} Y'_v (s_{vn} \cdot r_c) \quad (17)$$

at the outer wall, $r_c = 1$, equation (17) reduces to

$$J'_v (s_{vn}) + \frac{C_2}{C_1} Y'_v (s_{vn}) = 0 . \quad (18)$$

For the cylindrical chamber case, equation (18) reduces to

$$J'_v (s_{vn}) = 0 \quad (19)$$

since B must be zero because Y'_v becomes infinite at $r = 0$. The solution of equation (19) serves to define the transverse acoustic mode number, s_{vn} , for cylindrical combustion chambers.

The annular chamber has its inner wall located in the range $0 < r_i < 1$. Therefore, for the inner wall, equation (17) is written:

$$J'_v (s_{vn} \cdot r) + \frac{C_2}{C_1} Y'_v (s_{vn} \cdot r) = 0, @ r = r_i \quad (20)$$

whereas at the outer wall, $r = 1$ and equation (18) is still applicable. Solution of (18) and (20) simultaneously yields

$$J'_v (s_{vn}) Y'_v (s_{vn} \cdot R) - J'_v (s_{vn} \cdot R) Y'_v (s_{vn}) = 0 \quad (21)$$

I, B, Technical Description (cont.)

The solution of equation (21) defines the transverse acoustic mode number, s_{vn} , for annular chambers. Fortunately, equation (21) has been solved in Reference (9) and the values of s_{vn} are listed as a function of R , where $R = r_i/r_o$, on Table II.

Thus the use of an annular chamber will alter the frequencies of the transverse modes. The extent of the alteration is illustrated in Figure 9. In addition, radial injection distribution effects will be minimized by the use of the annular chamber so that in most cases the distribution coefficients A_{vn} , B_{vn} , and C_{vn} can be assumed to be unity.

TABLE II

BESSEL FUNCTION VALUE $(s_{vn})_{ann}$ FOR TANGENTIAL MODES IN ANNULAR CHAMBERS

Annular Chamber Geometry		Tangential Modes					
(Radius)	Inner (Radius) Outer	1T	2T	3T	4T	5T	6T
0.910	$(s_{vn})_{ann} = 1.04802$	2.09602	3.14401	4.19197	5.23989	6.28778	
0.833		1.092	2.1846	3.27672	4.368	5.4588	6.5496
0.667		1.209	2.412	3.61	4.80	5.98	7.14
0.500		1.35	2.68	3.98	5.18	6.34	7.45
0.400		1.41	2.85	4.10	5.27	6.40	7.5
0.333		1.54	2.91	4.17	5.31	6.42	7.5
0.286		1.60	2.99	4.18	5.31	6.42	7.5
0.250		1.64	3.00	4.18	5.31	6.42	7.5
0.222		1.67	3.02	4.18	5.31	6.42	7.5
0.200		1.70	3.025	4.18	5.31	6.42	7.5

NOTE: 1. Figure 9 gives the frequency ratio viz. $\frac{(s_{vn})_{annular}}{(s_{vn})_{cylindrical}}$ for different chamber geometries.

2. Calculation of annular chamber tangential frequencies

$$\left[f^* = \frac{C_o^* (s_{vn})_{annular}^{12}}{2\pi r_c^*} \right]$$

Reference: Bridge and Angrist, "Math. of Computation, 16, 78," April 1962.

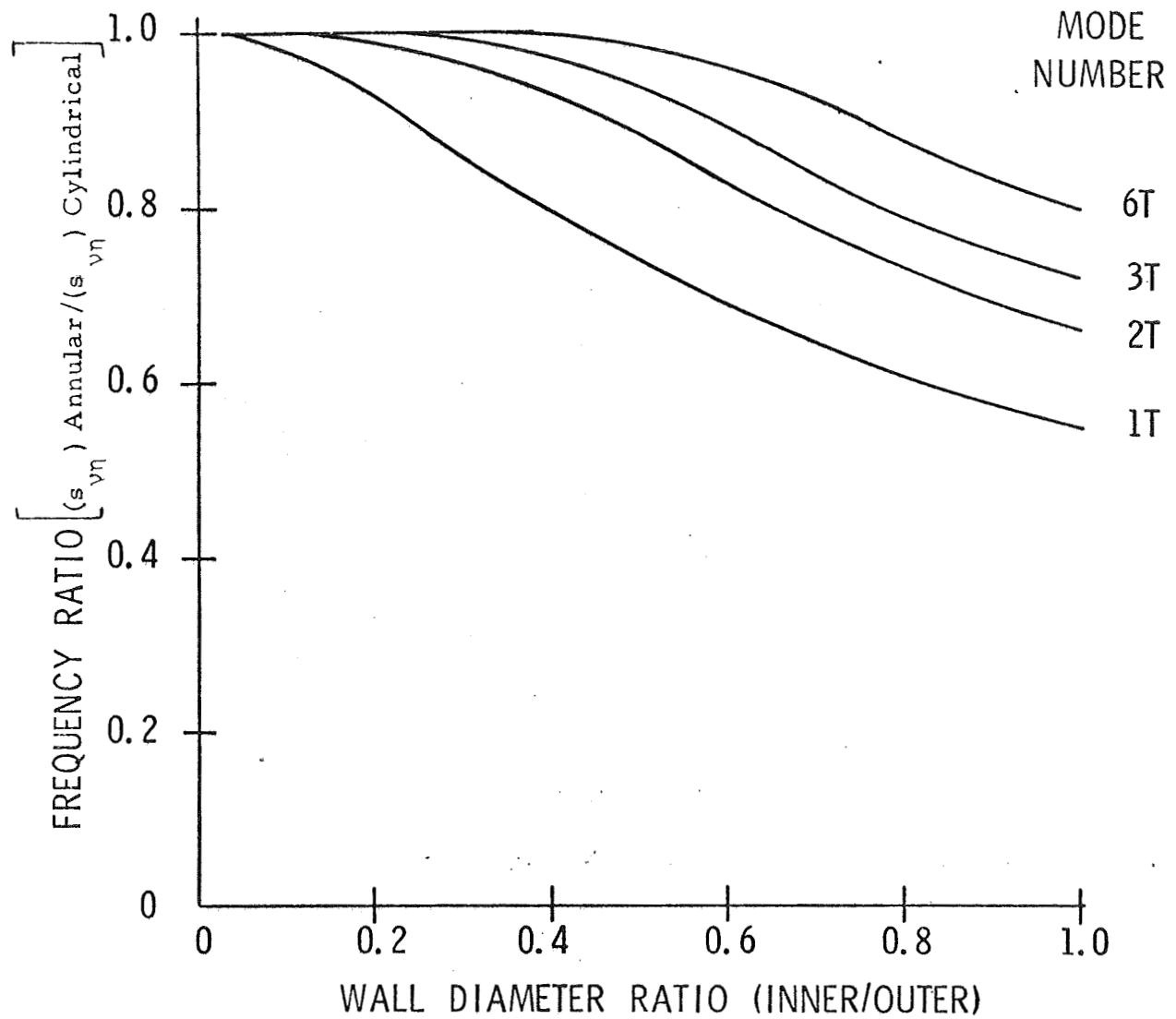


Figure 9 -- Tangential Mode Acoustic Frequencies for Annular Chambers

I, B, Technical Description (cont.)

(4) Combustion Response

(a) General Formulation

In Equation 11a combustion terms are written.

It is necessary now to provide a mathematical formulation for the combustion terms in the flow equations in terms of the chamber conditions. As discussed previously our quantitative understanding of the actual combustion processes is not sufficient to provide a mathematical model. Fortunately the heuristic formulation based on the sensitive time lag concept seems to provide a good representation of the actual combustion response. The relation between time lag and burning rate is immediately found by considering that the fraction of propellant burning at a certain station in a time interval dt must have been injected during the interval $d(t - \tau_T)$. If, then \dot{m}_b and \dot{m}_i are the corresponding burning and injection rates we must have

$$\dot{m}_b dt = \dot{m}_i d(t - \tau_T)$$

In steady-state τ_T does not vary with time, and hence, if the injection rate is unaffected by the oscillations

$$\bar{\dot{m}}_b = \bar{\dot{m}}_i$$

From these two relations we obtain the fractional perturbation of the burning rate in the form

$$\frac{\dot{m}'_b}{\bar{\dot{m}}_b} = \frac{\dot{m}_b - \bar{\dot{m}}_b}{\bar{\dot{m}}_b} = - \frac{\partial \tau_T}{\partial t} = \frac{-d\tau}{dt} \quad (22)$$

I, B, Technical Description (cont.)

where, in accordance with the definition of sensitive time lag, the variation of τ_T with time is entirely due to the variation of τ , and where τ has been assumed to be the same for all propellant elements, and hence independent of the space coordinates.

Turning to the evaluation of $d\tau/dt$, a satisfactory mathematical description is obtained if one imagines that during the sensitive time lag certain preparatory processes, which need not be more precisely defined, take place at a rate depending on the local, instantaneous values of quantities representing the state and the motion of the gas and droplets. When these preparatory processes, integrated over the duration of the sensitive time lag, reach a certain fixed level, the conversion into hot gases takes place abruptly. It is clear, then, that when the state and the motion conditions vary, also the duration of the sensitive (and hence, the total) time lag will vary, resulting in a variable rate of gas production.

The quantitative formulation follows at once. If the rate of the preparatory processes is given by a function $f(p, T, v, \dots)$ of the pertinent values of the pressure, temperature, any representative velocity v (for instance the radial gas velocity) and possibly other quantities representing the conditions in the chamber, the sensitive time lag τ for an element burning at time t will be given by the equation

$$\int_{t-\tau}^t f(p, T, v, \dots) dt_1 = \text{const.}$$

where t_1 represents the burning time. Here the values of p, T, v, \dots must be evaluated not only at time t_1 , but also at the position where the particular propellant element finds itself at that time. Since the above relation must be satisfied also in steady operation, indicating the steady-state quantities with a superimposed bar we must have

I, B, Technical Description (cont.)

$$\int_{t-\tau}^t f(p, T, v, \dots) dt_1 = \int_{t-\tau}^t \bar{f}(\bar{p}, \bar{T}, \bar{v}, \dots) dt_1 . \quad (23)$$

Now we introduce the perturbations, such that

$$p = \bar{p} + p', T = \bar{T} + T', v = \bar{v} + v' \dots$$

and expand the rate function in a Taylor series

$$f(p, T, v, \dots) = \bar{f} + \bar{f}_p p' + \bar{f}_T T' + \bar{f}_v v' + \dots$$

where $\bar{f} = f(\bar{p}, \bar{T}, \bar{v}, \dots)$ and similarly for the partial derivatives \bar{f}_p , \bar{f}_T , \bar{f}_v of f with respect to the subscripts. Observe that, under the small perturbations assumption, the Taylor series must be stopped after the first order terms.

If it is assumed that the temperature is a function only of the pressure (for instance, through the isentropic defining relation) $T' = p' (dT/dp)$. Then, defining the nondimensional interaction indices n , l , \dots as

$$n = \frac{\bar{f}_p + \bar{f}_T (dT/dp)}{\bar{f}}, \quad l = \frac{\bar{f}_v}{\bar{f}}, \quad \dots \quad (24)$$

$$f(p, T, v, \dots) = \bar{f} (1 + n p' + l v' + \dots)$$

and Equation (23) can be written in the form

I, B, Technical Description (cont.)

$$\int_{t-\tau}^{t-\bar{\tau}} \bar{f} (1 + np' + 1v' + \dots) dt_1 + \int_{t-\bar{\tau}}^t \bar{f} (1 + np' + 1v' + \dots) dt_1 \\ = \int_{t-\tau}^t \bar{f} dt_1$$

Here the integration interval at the L.H.S. of Equation (23) has been split into two parts. The first interval, from $t - \tau$ to $t - \bar{\tau}$ is of duration $\bar{\tau} - \tau$ and hence of the order of the perturbation of the time lag. Hence, compared with the other two integrals, the first integral is of the order of a perturbation. As a result in its evaluation one can disregard in the integrand the terms containing the perturbations which, in view of the small perturbation assumption, would result in a negligible second order contribution. Then, simplifying, the above equation becomes

$$\int_{t-\tau}^t \bar{f} dt_1 = \int_{t-\bar{\tau}}^t \bar{f} (np' + 1v' + \dots) dt_1$$

In the combustion zone \bar{p} is approximately constant, and if v is the radial gas velocity, so that $\bar{v} = 0$ then $\bar{f}(\bar{p}, \bar{v})$ is a constant, and so are n and l .

Then we obtain simply

$$\bar{\tau} - \tau = n \int_{t-\bar{\tau}}^t p' dt_1 + l \int_{t-\bar{\tau}}^t v' dt_1 + \dots$$

or, differentiating with respect to t

I, B, Technical Description (cont.)

$$-\frac{d\tau}{dt} = n \left[p'(t) - p'(t - \bar{\tau}) \right] + l \left[v'(t) - v'(t - \bar{\tau}) \right] + \dots \quad (25)$$

Again, it must be specified that while $p'(t)$ is evaluated at the conversion instant t at the location where the conversion takes place, $p'(t - \bar{\tau})$ must be evaluated not only at time $t - \bar{\tau}$, but also at the location where the propellant was at that time. However, the displacement of the propellant during the time $\bar{\tau}$ produces an effect of second order in the expression (25). As a reasonable approximation, therefore, both $p'(t)$ and $p'(t - \bar{\tau})$ can be evaluated at the station when the conversion into burned gases takes place. And, of course, the same applies to the velocity effect in Equation (25), and to other possible effects.

In Equation (25) only the pressure sensitivity and the radial velocity sensitivity are explicitly considered. Concerning the last it must be added that other components of the gas velocity can be treated in exactly the same fashion. If one is interested, for instance, in the effect of the transverse non-uniformity of the gas composition, then also the tangential velocity component is relevant, and correspondingly another velocity sensitive term must appear in Equation (25), which becomes, in the absence of other interactions

$$\begin{aligned} -\frac{d\tau}{dt} = & n \left[p'(t) - p'(t - \bar{\tau}) \right] + l_r \left[v'(t) - v'(t - \bar{\tau}) \right] \\ & + l_\theta \left[w'(t) - w'(t - \bar{\tau}) \right] \end{aligned} \quad (26)$$

It must be observed that, actually, when only the effects of the nonuniform gas composition on the burning rate are sought, what counts is the displacement of the gases with respect to the droplets,

I, B, Technical Description (cont.)

rather than the relative velocity. This can be formalized by writing, for instance, instead of (26),

$$\begin{aligned} -\frac{d\tau}{dt} = n & \left[p'(t) - p'(\bar{\tau}) \right] + m_r \left[\delta'_r(t) - \delta'_r(\bar{\tau}) \right] \\ & + m_\theta \left[\delta'_\theta(t) - \delta'_\theta(\bar{\tau}) \right] \end{aligned} \quad (27)$$

where m_r and m_θ are two displacement indices relative to the radial and tangential displacements δ_r , δ_θ respectively. The two formulations (26) and (27) are closely correlated, because of the relations existing between velocities and displacements.

If the time dependence of the perturbations in Equations (26) and (27) is taken to be $\exp(st)$, the combined effect is:

$$-\frac{d\tau}{dt} = -(\rho p' + R_v v' + T_v w') \text{ or } -(\rho p' + R_\delta \delta'_r + T_\delta \delta'_\theta) \quad (28)$$

where the quantities defined by

$$\frac{\rho}{n} = \frac{R}{I_r} = \frac{T}{I_\theta} = \frac{R_\delta}{m_r} = \frac{T_\delta}{m_\theta} = 1 - e^{-\sigma\bar{\tau}}, \quad (\sigma = \lambda + i\omega) \quad (29)$$

are, in view of (22), to be interpreted as feedback factors. In this case the relation between velocities and displacements is simply $v' = \sigma \delta'_r$, $w' = \sigma \delta'_\theta$ so that the same expression can be used for $-\frac{d\tau}{dt}$ for velocity or displacement effects if R_δ is equivalent to σR and T_δ is equivalent to σT .

(b) Velocity Sensitive Combustion

It is desirable to take a closer look at the dynamic aspects of velocity sensitive combustion. The most significant

I, B, Technical Description (cont.)

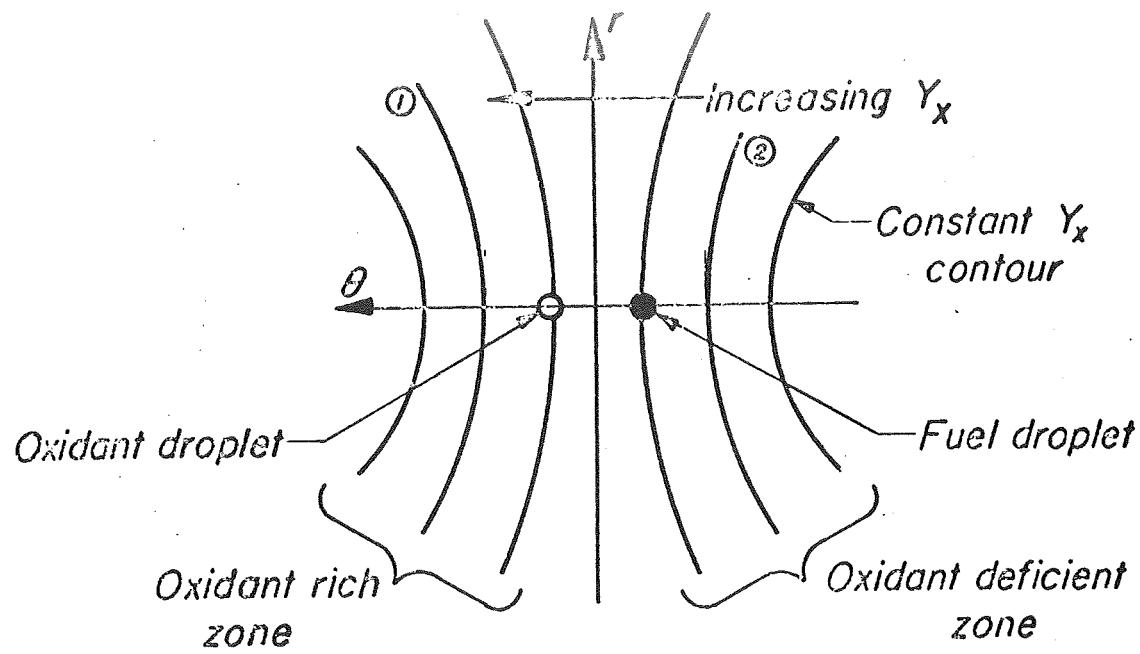
velocity effects are those resulting from the radial and tangential components of the gas velocity perturbation. In the case of purely transverse modes, the longitudinal velocity perturbation component is always much smaller than the transverse components. In addition, the longitudinal component vanishes at the injector face and has its smallest magnitude in the early combustion zone, the region which appears to have the greatest significance for transverse modes. It is possible that in certain combustion chambers the axial spreading of the combustion will result in sizable longitudinal velocity oscillations for higher order longitudinal or combined transverse-longitudinal modes. However, in such cases the pressure perturbation will become correspondingly small in that region, thus, the decreased pressure effect will cancel the increased velocity effect. In the present analysis, therefore, only the effects of the transverse velocity oscillations will be considered in the combustion response.

Of the various intermediate processes occurring during the combustion of liquid bipropellants, those most sensitive to velocity are the vaporization of the liquid droplets and the mixing of the vaporized propellants that must precede chemical reaction. The theoretical study of unsteady vaporization by Wieber and Mickelsen (Ref. 10) indicates that the evaporation rate is dependent on the absolute magnitude of the relative velocity between droplet and gas; therefore, the vaporization velocity effect is seen to be essentially nonlinear, and cannot be treated within the framework of a linearized theory. On the other hand, the mixing of the propellants by the oscillating velocities may be linearized, and gives rise to important modifications of the stability behavior of a combustor. Although no detailed description of such a complex phenomenon is now possible, the following discussion illustrates one process by which the burning rate may be caused to oscillate by an oscillating transverse gas velocity.

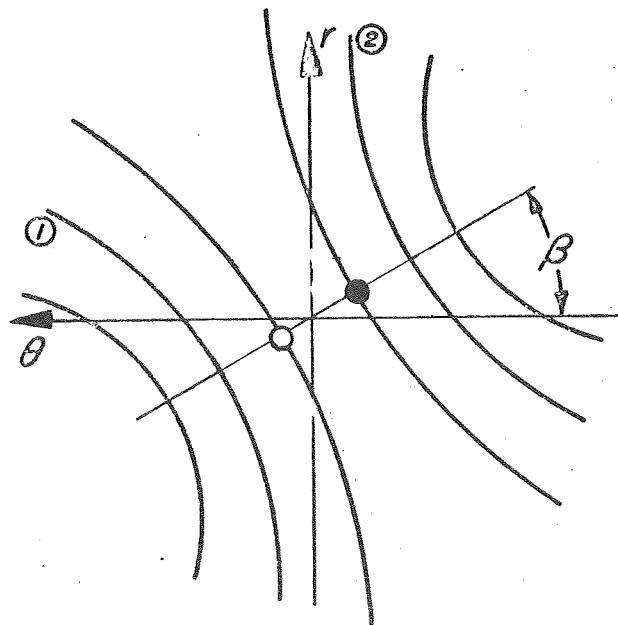
I, B, Technical Description (cont.)

Consider first the mixture of gaseous combustion products, vaporized propellants (oxidizer and fuel), and liquid propellant droplets at some axial station downstream from a fuel-on-oxidizer impinging doublet injector element. Since liquid mixing is imperfect, some stratification will exist in the mixture. For concreteness, assume that the line of centers of the doublet is aligned tangentially (i.e., normal to a radius). Then the stratification is almost entirely in the tangential direction, as shown schematically in Figure 10 by the lines of constant mass fraction of vaporized oxidizer in the mixture Y_x . The exact shape of the constant Y_x contours will be dependent on the injector design, operating conditions, and propellant characteristics. Because of the turbulence in the combustion chamber, the stratification pattern shown represents only a mean condition.

As a droplet evaporates, the vapor diffuses away and must mix with the other vaporized propellant in the propellant proportions for chemical reaction. In a rocket combustor, the transport and mixing are most likely to be carried out by turbulence rather than by molecular diffusion. The overall burning rate of a fuel-rich droplet will, therefore, be a function of the amount of oxidizer vapor near the droplet. In the presence of small, periodic tangential gas velocity oscillations ($w_e^{1\omega t}$) the gaseous mixture will be displaced relative to the droplets, causing oscillations of the local mass fractions of both oxidizer and fuel. Since a fuel droplet is in an oxidant-deficient region, a velocity perturbation which increases the oxidizer fraction in the vicinity of the droplet will increase the contribution of that droplet to the overall burning rate. The opposite is true for an oxidizer-rich droplet subject to the same perturbation, since an oxidizer fraction increase corresponds to a fuel fraction decrease. Thus, the effects of the same velocity perturbation on the two droplets will tend to cancel, unless the propellants have significantly different vaporization rates. In the latter case, at any axial station, there will be a greater number of droplets of the less-volatile propellant, and summation



(a) Spray produced by tangentially oriented injector spud



(b) Spray produced by rotated spud

Figure 10 -- Sprays Produced by Various Orientations of the Injector Spud

I, B, Technical Description (cont.)

of the velocity effect over all of the droplets in the spray will result in a net contribution to the burning rate. This contribution will clearly depend on the amplitude of the velocity as well as its direction. For small perturbations, and for the doublet spray shown in Figure 10a, the burning rate contribution can be written in the form

$$f' = l w' e^{i \omega t}$$

where l is a velocity interaction index analogous to the pressure interaction index defined by Crocco. In the case of an arbitrarily oriented spray, such as shown in Figure 10b, the burning rate perturbation due to velocity effects becomes

$$f' = (l_r v' + l_\theta w') e^{i \omega t} \quad (30)$$

so that, in general, two velocity indices are necessary.

It is clear that this linearized expression will not be valid for all types of injection patterns. For example, approximately linear effects can be expected with a fuel-on-oxidizer doublet and for a like-on-like pattern if the spacing between unlike fans is sufficiently small. However, for large spacings, nonlinear velocity effects must be taken into consideration.

At present, the magnitudes of the velocity indices cannot be calculated because of the lack of quantitative knowledge of the processes involved in liquid propellant combustion under turbulent conditions.

I, B, Technical Description (cont.)

It is also possible to formulate the above discussion in terms of displacement interaction indices. Letting the radial and transverse components of the displacements be $\delta'_r e^{i\omega t}$ and $\delta'_\theta e^{i\omega t}$, the net combustion process rate perturbation can be written

$$f' = (m_r \delta'_r + m_\theta \delta'_\theta) e^{i\omega t} \quad (31)$$

It is clear that $m_r = i\omega l_r$ $m_\theta = i\omega l_\theta$. Thus, the displacement indices present at 90° phase shift with respect to the velocity indices.

The analysis of the effects of velocity (or displacement) sensitivity on the stability of a combustor is considerably simplified by assuming that the velocity effects occur during the same time interval (the sensitive time lag) as the pressure effects. In this case, the burning rate perturbation becomes

$$Q' = \bar{Q} (P_p' + R_v' + T_w') \quad (32)$$

where

$$P = n (1 - e^{-\sigma\tau})$$

$$R = l_r (1 - e^{-\sigma\tau})$$

$$T = l_\theta (1 - e^{-\sigma\tau})$$

In equation (32), additional simplifications have been introduced by assuming that all propellant elements have equal mean sensitive time lags, and that the space lag associated with the sensitive time lag is a negligible fraction of the wave length. In general, of course, the mean sensitive time lag varies from one propellant element to another. Crocco and Cheng have shown that this nonuniformity of the sensitive time lag leads to increased stability of the combustor. Therefore, the assumption of a uniform time lag produces a conservative stability prediction.

I, B, Technical Description (cont.)

It would be possible to generalize the burning rate expression to allow for different time lags for pressure and velocity effects. However, both mathematical and physical considerations indicate the desirability of the simpler formulation.

(c) Approximate Treatment of Nonlinear Combustion Response

Nonlinearities associated with oscillatory combustion chamber operation can derive from two sources: (1) the fluid mechanical behavior of the gases in the chamber, and (2) the dynamics of the combustion process. It is clear that significant interactions between the two kinds can also occur. The studies of Priem and Guentert have shown that combustion process nonlinearities can be important even for oscillation amplitudes less than 20% of the mean chamber pressure. Thus, it is worthwhile to consider nonlinearity of the combustion response while retaining the linearized fluid mechanical analysis with its attendant simplification.

To insert the nonlinear combustion dynamics into the framework of the linear theory, some method of equivalent linearization must be used. The method selected in this analysis is the "describing function" method.

When a sinusoidal signal is input to a nonlinear element, the output will not, in general, be sinusoidal. Fourier analysis of the output will reveal many frequency components, among which is one (the fundamental) that corresponds to the frequency of the input signal.

I, B, Technical Description (cont.)

For the analysis of stability, only the fundamental frequency component is required, as shown by Reardon (Ref 8). An equivalent linear transfer function for the nonlinear element can be defined as the ratio of the fundamental component of the output to the input. Thus, if

$$I(t) = I e^{i\omega_f t}$$

is the input, and

$$O(t) = O_1(\omega_f) e^{i\omega_f t} + \sum_{j \neq 1} O_j(\omega_f) e^{ij\omega_f t} \quad (33)$$

is the output, the equivalent linear transfer function is

$$TF = \frac{O_1(\omega_f)}{I}$$

For nonlinearities that can be treated by this method, linear behavior is obtained for limiting values of the input (e.g., $I \rightarrow 0$ or $I \rightarrow \infty$). It is convenient to define a "describing function" F as

$$F(\omega) = TF / (TF)_{LIM} \quad (34)$$

where $(TF)_{LIM}$ is the limiting linear transfer function. Thus, a linear analysis can be extended to include isolated nonlinear effects by replacing the linear transfer function of the nonlinear element by $F(\omega)$. $(TF)_{LIM}$.

In applying this approach to the combustion instability problem, it is assumed that the only significant nonlinearities

I, B, Technical Description (cont.)

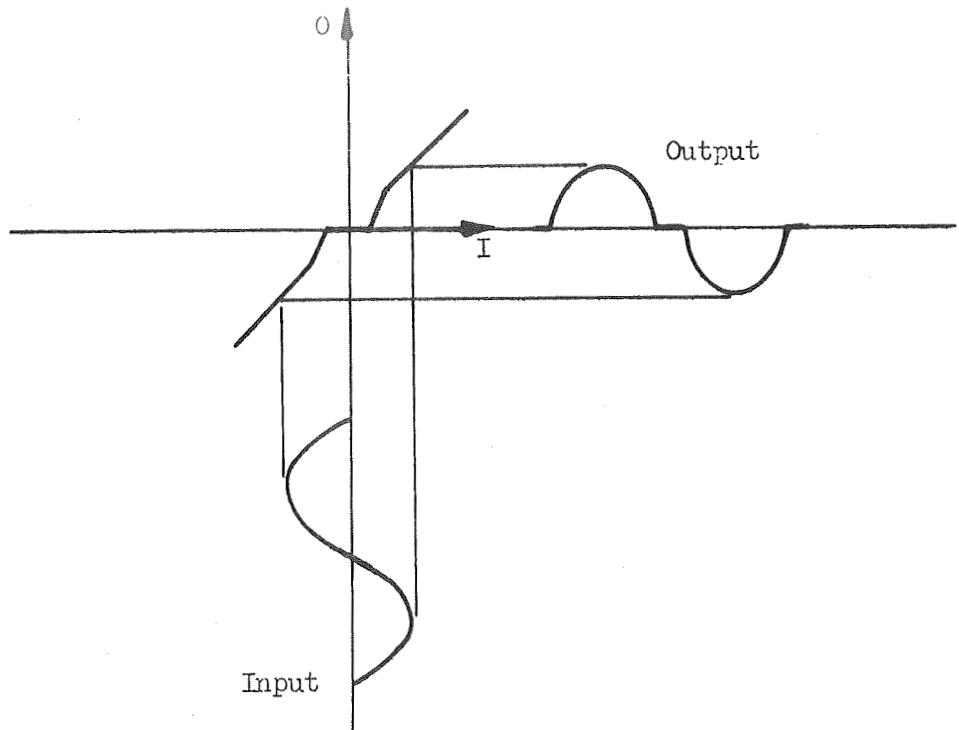
are those associated with the response of the combustion process to pressure and velocity perturbations. Three describing functions are required, corresponding to the combustion response to pressure, radial velocity, and tangential velocity perturbations. Thus, the combustion rate perturbation becomes

$$Q' = \bar{Q} \left[F_P(p') \rho_p' + F_R(v') Rv' + F_T(w') T_w' \right] \quad (35)$$

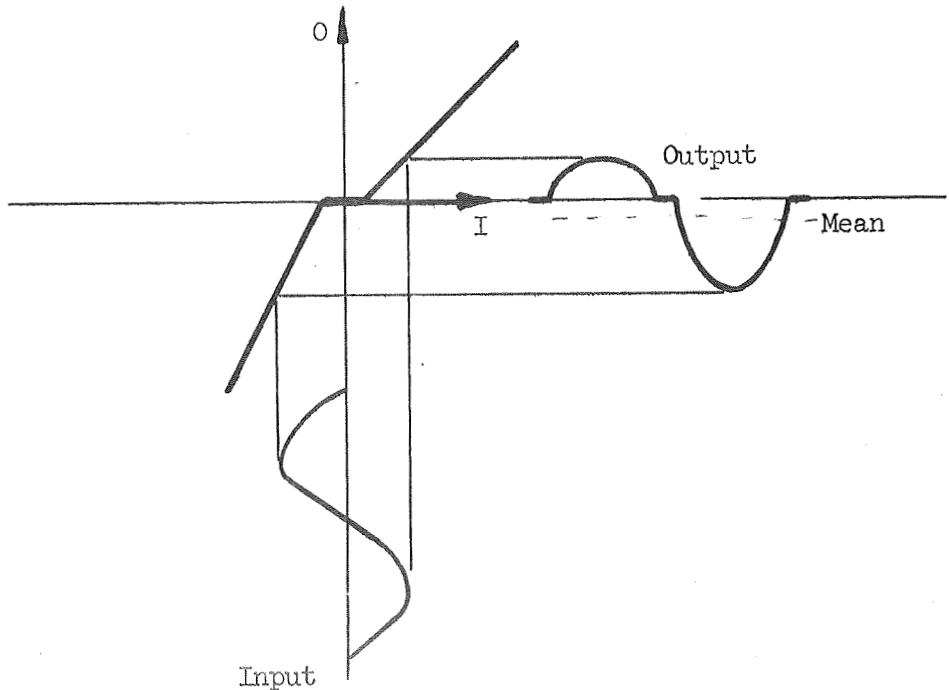
In the above expression, the dependence of the describing functions on the perturbation (input) amplitude is shown explicitly. This dependence on amplitude introduces complications into the solution of the perturbation equations. In general, the input amplitude is a function of the axial, as well as the transverse, space coordinate. To obtain a solution, it is necessary to introduce the additional simplification of neglecting the axial variation of perturbation amplitude in the evaluation of the describing function. For purely transverse modes, this is not an unreasonable approximation, and it breaks down significantly only for higher-order longitudinal modes. The error made by using the perturbation amplitudes at the injector face will be small.

To calculate the describing functions, it is necessary to know the shape of the combustion response to each perturbation. Since it is assumed that the effects are independent of each other, the burning rate perturbation can be written

$$\frac{Q'}{\bar{Q}} = \phi_p(p') + \phi_R(v') + \phi_T(w')$$



(a) Response Function with Odd-Symmetry



(b) Asymmetric Response Function

Figure 11 -- Examples of Nonlinear Response Functions

I, B, Technical Description (cont.)

The procedure for calculating each describing function is the same; therefore, it is necessary only to discuss one, say, the pressure-effect describing function.

The input perturbation is $p' = P_0 \cos \chi$ where $\chi = \omega t$ and, from Fourier analysis the fundamental term of the output series is

$$\phi_p(P_0) = \frac{1}{\pi} \int_{C-\pi}^{C+\pi} \phi_p(P_0 \cos \chi) e^{-ix} d\chi$$

Thus, the describing function is given by

$$F_p = \frac{1}{\pi P_0 (\text{TF})_{\text{LIM}}} \int_{C-\pi}^{C+\pi} \phi_p(P_0 \cos \chi) e^{-ix} d\chi \quad (36)$$

In the expressions above, C is an arbitrary constant, and $(\text{TF})_{\text{LIM}}$ is a suitable normalizing factor, such that $F \rightarrow 1$ for equivalent linear operation. The choice of $(\text{TF})_{\text{LIM}}$ depends on the characteristics of each nonlinear response function, and a general rule does not appear feasible.

The describing function method applies well to nonlinearities with odd symmetry (Figure 11a). It is not applicable to response functions with even symmetry, such as the velocity effect on vaporization, since there is no contribution to the fundamental term of the Fourier series. An intermediate case is that of asymmetric response function (Figure 11b). In this case, there will be a significant contribution to the fundamental oscillation, but a change in the mean burning rate as well. This change in the mean burning rate occurs only during the sensitive portion of the total time lag and so will have a negligible influence on the steady state solution.

I, B, Technical Description (cont.)

In general, the describing function is complex; that is, the nonlinear combustion response introduces a phase shift as well as an amplitude change. However, for response functions with odd symmetry, the fundamental component of the output is in phase with the input, so that the describing function is real.

(5) Effect of Non-Uniform Injection

The non-uniformity of mass injection in the r and θ direction can be characterized by a burning rate distribution function $\mu(r, \theta)$ which is the ratio of the local injection density to the mean injection density so that

$$\pi = \int_0^1 \int_0^{2\pi} \mu r dr d\theta.$$

When μ is multiplied by \bar{Q} in equations 13b terms on the right hand side are known functions of r and θ as well as Z . The solution of this type of inhomogeneous differential equation can be expressed as a Bessel-Fourier series as follows:

$$P_1 = (A_{v\eta} P_{av\eta} + B_{v\eta} P_{bv\eta} + C_{v\eta} P_{cv\eta} + P_d) \Psi_{v\eta} \theta_v + \sum_{\substack{p \neq v \\ q \neq \eta}} (A_{pq} P_{apq} + B_{pq} P_{bpq} + C_{pq} P_{cpq}) \Psi_{pq} \theta_p$$

where the subscript a indicates pressure effects (associated with P) b radial velocity effects (associated with R), c tangential velocity effects (associated with T) and d damping effects (which are independent of r and θ).

I, B, Technical Description (cont.)

When the orthogonality property of the functions Ψ and θ is used on the system characteristic equation the coefficients A_{vn} , B_{vn} and C_{vn} are found to be:

$$\begin{aligned}
 A_{vn} &= \frac{\int_0^1 \int_0^{2\pi} \mu(r, \theta) \Psi_{vn}^2 \theta_v \theta_v^* r dr d\theta}{\int_0^1 \int_0^{2\pi} \Psi_{vn}^2 \theta_v \theta_v^* r dr d\theta} \\
 B_{vn} &= \frac{\int_0^1 \int_0^{2\pi} \mu(r, \theta) \frac{d\Psi_{vn}}{dr} \Psi_{vn} \theta_v \theta_v^* r dr d\theta}{\int_0^1 \int_0^{2\pi} \Psi_{vn}^2 \theta_v \theta_v^* r dr d\theta} \\
 C_{vn} &= \frac{\int_0^1 \int_0^{2\pi} \mu(r, \theta) \Psi_{vn}^2(r, \theta) \frac{d\theta_v}{d\theta} \theta_v^* dr d\theta}{\int_0^1 \int_0^{2\pi} \Psi_{vn}^2 \theta_v \theta_v^* r dr d\theta}
 \end{aligned} \tag{37}$$

In section I,B,7 it is seen how these coefficients affect the characteristic equation. It should be noted that if the energy addition follows a non-linear relationship a describing function must also be included in the above coefficients.

I, B, Technical Description (cont.)

(6) Nozzle Admittance

In any rocket combustion instability analysis, it is desirable to apply a boundary condition at the nozzle entrance to describe the effect of the nozzle upon wave motion in the combustion chamber. In a linearized analysis, this boundary condition is written in the form of an admittance relation; that is, a linear relation between the perturbations of two thermodynamic properties and of the velocity components. The coefficients in this relation are termed admittance coefficients and are calculated by means of an analysis of the oscillatory flow in the nozzle. In this section, the analysis and numerical integration which lead to the determination of these coefficients are discussed.

The divergent portion of the supercritical nozzle need not be analyzed; all that is pertinent is the subsonic flow in the convergent portion since any disturbances to the supersonic flow cannot propagate upstream through the throat. Therefore, disturbances in the subsonic portion of the nozzle and in the chamber are neither affected nor caused by disturbances in the supersonic region. (The opposite, however, is not true.)

To date, two types of nozzles have been analyzed: axisymmetric designs and two-dimensional designs. The axisymmetric case is presently the one of the most practical significance and is the one to be discussed here. The two-dimensional case applies to thin annular chambers and to certain experimental configurations. The analyses of the two cases are similar; details of both are given in References 11 and 12.

The unperturbed, or steady-state, flow is considered to be one-dimensional in order to simplify the analysis. The perturbed flow, however, may be three-dimensional. The combustion process is

I, B, Technical Description (cont.)

assumed to be completed before the flow enters the nozzle so that there are no source terms in the differential equations of motion. The equations do allow for the occurrence of entropy waves and vorticity waves in the nozzle due to the combustion chamber.

The three-dimensional coordinate system (Figure 12) employs the values of the velocity potential ϕ and the stream function ψ of the unperturbed flow in addition to the azimuthal angle, with

$$\bar{q} = \frac{\partial \phi}{\partial s}$$

$$r \rho \bar{q} = \frac{\partial \psi}{\partial n}$$

where s is the streamline direction and n is the direction normal to the streamline. Since the value of the stream function is a constant at the nozzle walls where the boundary conditions are applied, separation of variables is allowed.

Under the usual assumption of small-amplitude oscillations, linear partial differential equations are obtained that govern the perturbations. These equations are separated under the assumption that the nozzle is sufficiently long that the cosine of the semi-angle of convergence may be approximated by unity. The time and azimuthal dependencies are given by sinusoidal functions. The radial dependencies are given in terms of Bessel functions of the first kind and their derivatives. The axial dependencies are related to the solution to a certain second-order linear ordinary differential equation with complex-variable coefficients which can only be obtained in exact form by numerical integration.

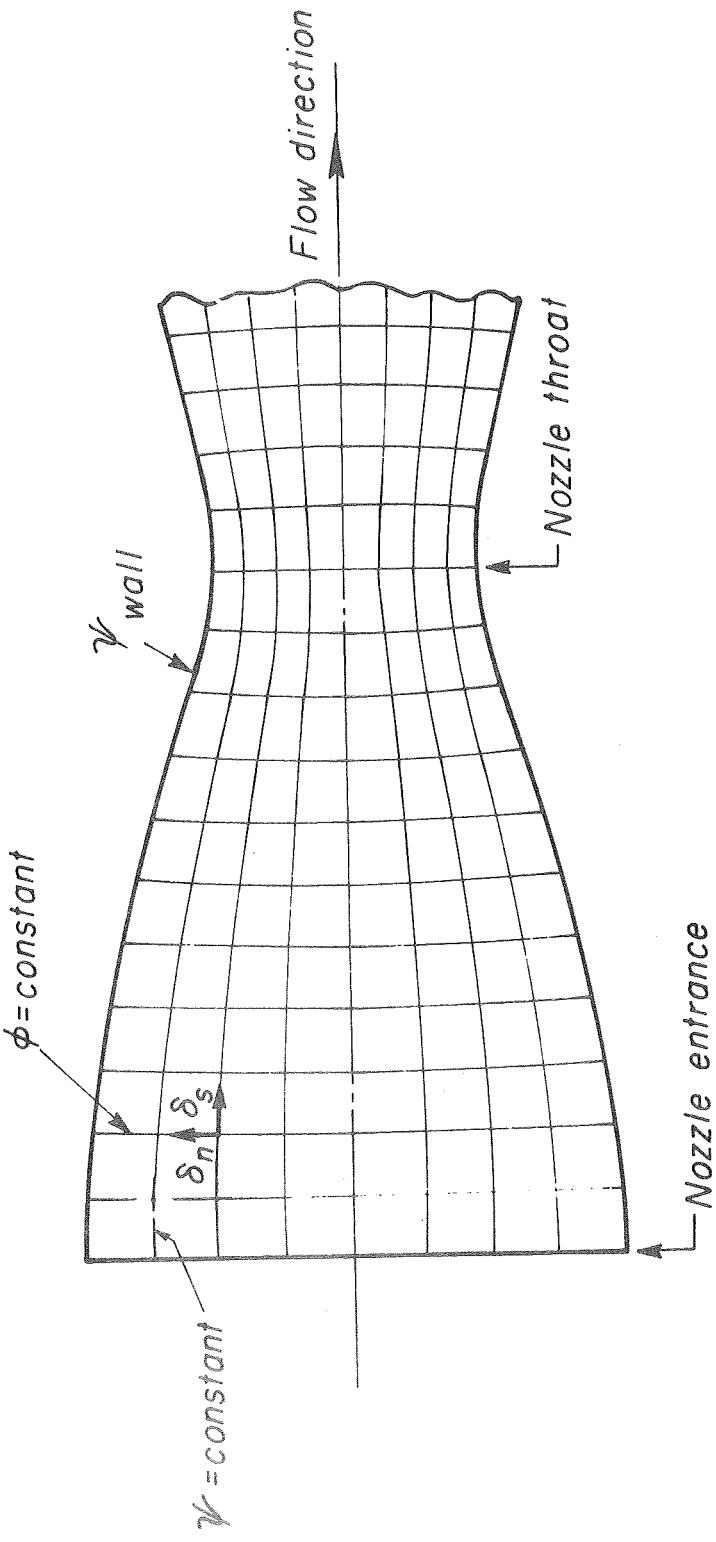


Figure 12 -- Exhaust Nozzle Coordinate System

I, B, Technical Description (cont.)

This second order differential equation is singular at the throat; one of the homogeneous solutions will be regular there and the other one will be singular. The singular solution is cast away. This procedure has been demonstrated to be equivalent to disallowing perturbations to propagate upstream from the supersonic portion of the nozzle (Ref 6).

It has been shown that the admittance coefficients are functions of the solutions to certain first order equations that are obtained by reduction of the original second order equation. So, while it would be necessary to integrate the second-order equation in order to determine the variation of the flow properties, it is not necessary for the purpose of determining the admittance coefficients. Since the interest lies in the prediction of global stability characteristics and not in the details of the flow itself, only the equations immediately needed to determine the admittance coefficient will be presented. The derivations and additional analyses may be found in Reference 11.

The admittance coefficients for a given geometry are determined as functions of the axial coordinate or, equivalently, of the local mean-flow Mach number. This implies that, when the admittance coefficient at the nozzle entrance is desired, the axial coordinate at the entrance or the entrance Mach number must be known before the admittance coefficients can be determined.

The linear admittance condition is given by

$$\gamma U + AP + \gamma \beta s_{vn} V + \gamma CS = 0 \quad (38)$$

I, B, Technical Description (cont.)

where U, P, V, and S are the axial dependencies of the nondimensional perturbations of axial velocity, pressure, radial velocity, and entropy, respectively.

The annular nozzle analysis used in this program is based on Reference 11. It contains certain inconsistencies which should be aired. The current analysis is an approximation to an annular nozzle analysis which is expected to be exact for a certain case.

The cylindrical nozzle analysis postulates the existence of streamlines and a velocity potential. The equations of motion are written in terms of stream functions and velocity potentials. The limits of integration in the radial direction must be written in terms of these streamlines. For a conventional nozzle these limits are the nozzle centerline and the outer wall which are both streamlines. To make an annular analysis from the conventional nozzle analysis with a minimum of fuss a different streamline can be chosen for the inner boundary. A new corresponding value of s_{vn} can also be determined. It is clear that once the outer boundary is chosen the number of possible inner boundaries is severely limited to one which is a constant fraction of the outer radius.

The nozzle admittance analysis requires a table of the square of the velocity versus the velocity potential. For a general annular nozzle inner and outer contour this can be calculated by first calculating area ratios versus distance then velocities versus distance and the velocity potential from velocity and distances. As this program is written the table of velocity squared versus velocity potential is calculated for a very general annular nozzle configuration. It should be clear from the discussion above that the configuration for which the admittance is obtained is not in general the configuration assumed.

I, B, Technical Description (cont.)

Basic changes to the nozzle admittance analysis are needed to rectify this limitation.

(7) Characteristic Equation

Solution of the perturbation equations gives the pressure perturbation in the form of a Bessel-Fourier series:

$$p' = P_{\infty} [P_{vn} (z) \psi_{vn} (r) \theta_v (\theta) + \sum_p \sum_q P_{pq} (z) \psi_{pf} (r) \theta_p (\theta)]$$

$\begin{matrix} p \neq v \\ q \neq n \end{matrix}$

In this expression the indices v and n refer to the fundamental term, that is, to the oscillatory mode under consideration. The other terms in the series account for the distortion introduced by flow, injection distribution, velocity effects, and nonlinear combustion response. For values of the indices p, q different from v, n , each term in the series includes an integration constant. However, the integration constant for the fundamental term can be shown to be of order M^3 , and so can be neglected in the present analysis. The constant P_{∞} represents the perturbation amplitude level; in this linearized analysis, the amplitude has no effect on the stability solution.

Since the perturbation solution is obtained in the form of a series, the nozzle admittance boundary condition must be applied term by term. For each $p, q \neq v, n$, the nozzle boundary condition can be used to determine the integration constant. Application of the remaining condition,

$$\gamma U_{vn} (z_e) + AP_{vn} (z_e) + BS_{vn} \gamma V_{vn} (z_e) + CS_{vn} (z_e) = 0 \quad (39)$$

results in an eigenvalue problem. That is, this equation is the characteristic equation for the eigenvalues $\sigma = \lambda + i\omega$. For a given combustor geometry

I, B, Technical Description (cont.)

and for a given value of the combustion parameters n , τ , l_r and l_θ , the characteristic equation can, in principle, be used to determine the frequency of oscillation ω and the growth rate λ of the perturbation amplitude.

However, since the coefficients of the characteristic equation are function of the variable σ , it is more convenient to regard σ as one of the independent variables. Considerable simplification results if $\lambda = 0$, that is, $\sigma = i\omega$, which is interpreted physically as an oscillation, the amplitude of which neither grows nor decays with time. The neutral condition is clearly the boundary between stable and unstable operation, and is sometimes referred to as the stability limit.

For neutral oscillations, regarding the frequency as an independent variable, the characteristic equation becomes a relation between the combustion parameters. Since the equation is complex, two of the combustion parameters can be determined in terms of the other two. It is natural to select the sensitive time lag τ and the pressure interaction index n as the dependent variables, because these parameters are significant to all modes of oscillation. Following this procedure, the characteristic equation can be written in the form:

$$n(1 - e^{-i\omega\tau}) = \frac{h(\omega)}{A_{vn} + \frac{i}{\gamma\omega}(B_{vn}\frac{l_r}{n} + C_{vn}\frac{l_\theta}{n})} = \hat{h}_r + i\hat{h}_i . \quad (40)$$

The solution is

$$n(\omega, \frac{l_r}{n}, \frac{l_\theta}{n}) = \frac{\hat{h}_r^2 + \hat{h}_i^2}{2\hat{h}_r} \quad (41)$$

I, B, Technical Description (cont.)

$$\tau(\omega, \frac{1}{n}, \frac{1}{n}) = \tan^{-1} \left(\frac{\frac{\sim h_i}{\sim h_r}}{n - \frac{\sim h_r}{\omega}} \right) \quad (42)$$

where τ is determined to within an additive constant $\frac{2\pi}{\omega}$.

A typical solution for $n(\omega)$ and $\tau(\omega)$ for assumed values of the velocity indices is shown in Figure 13. This solution applies at the stability limits, where $\lambda = 0$. It can be seen that for any value of τ only one value of n is consistent with neutral oscillations. For the same τ , a larger n corresponds to instability ($\lambda > 0$) and a smaller n to stability ($\lambda < 0$). In the case of transverse modes, for values of n in the range of interest (< 2), the frequency varies over a very narrow range, and is very nearly equal to the corresponding acoustic frequency. For longitudinal modes, both the frequency range and the departure from the acoustic-mode frequency are somewhat larger. The narrow frequency range result is related directly to the fact that high frequency instability involves the interaction of the combustion chamber. The chamber acoustics are somewhat modified by the presence of the exhaust nozzle and the mean gas flow, but a good approximation of the resonant frequencies can be made without reference to the combustion effects.

(8) Longitudinal Mode Analysis

The preceding discussion is valid generally for any mode but applies more specifically for the transverse mode analysis of this program. The analysis of longitudinal modes is simplified considerably, without losing the essential features, by assuming that the combustion is concentrated at a single axial station, ξ_1 . If the steady-state velocity profile $\bar{u}(Z)$ is given, a combustion front location can be defined by:

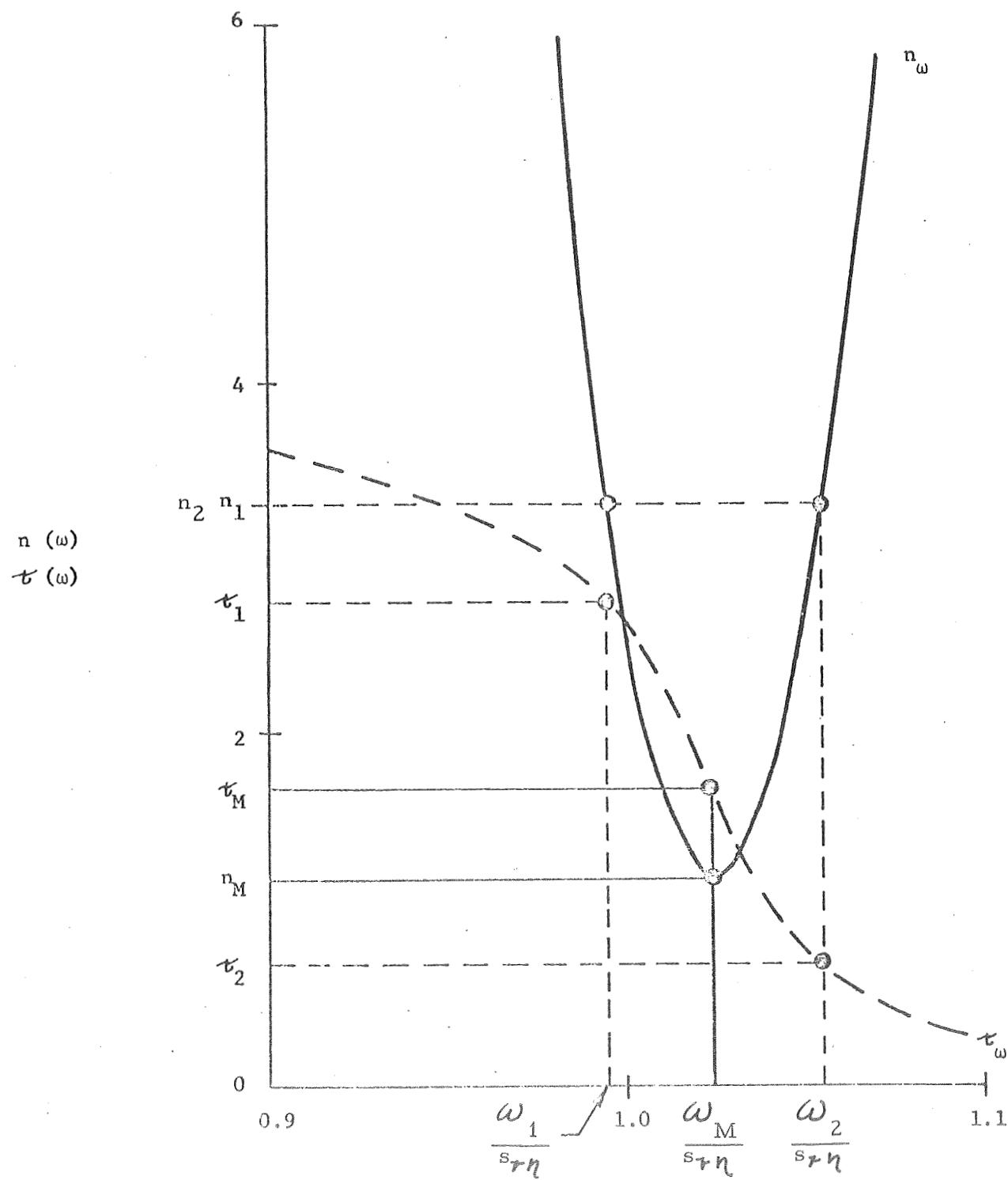


Figure 13 -- Typical Solutions of $n(\omega)$ and $\tau(\omega)$

I, B, Technical Description (cont.)

$$\xi_1 = 1 - \frac{1}{\bar{u}_e} \int_0^1 \bar{u}(z) dz$$

where $\bar{u}_e = \bar{u}(z = 1)$ is the gas velocity at the nozzle entrance.

In this analysis the combustion chamber is separated into two regions by the combustion front. Between the injector and the front (Region "0" where $0 \leq z \leq \xi_1$) there is no mean gas velocity. Liquid propellant droplets, assumed to have negligible volume compared to the total volume by Region "0", travel through the gases and burst instantaneously into gaseous products at the combustion front. The (dimensionless) liquid velocity \bar{u}_{lo} is assumed to be small, so that its square is negligible, even though the gas velocity in Region "1" is not restricted.

Downstream of the combustion front, in Region "1", the steady-state gas velocity is constant and equal to the nozzle entrance velocity. The gases in Region "0" and Region "1" are assumed to have the same stagnation properties. Assuming that any kinetic energy lost by the droplets while traveling through Region "0" is transferred into thermal energy of the droplets, and neglecting heat transfer and viscous effects, the combustion front appears as a planar mass source, and the stagnation enthalpy is constant in Regions "0" and "1".

The steady state equations in Region "0" yield:

$$\bar{P} = 1, \bar{T} = 1, \bar{\rho} = 1$$

I, B, Technical Description (cont.)

In Region "1" these equation give:

$$\bar{p} = \frac{1}{1 - \frac{\gamma \bar{u}_e (\bar{u}_L - \bar{u}_e)}{1 - \frac{\gamma-1}{2} \bar{u}_e^2}}$$

$$\bar{T} = 1 - \frac{\gamma-1}{2} \bar{u}_e^2$$

$$\bar{\rho} = \frac{1}{1 - \frac{\gamma-1}{2} \bar{u}_e^2 - \gamma \bar{u}_e (\bar{u}_L - \bar{u}_e)}$$

The liquid velocity in Region "0" is given by:

$$\bar{u}_L = \bar{u}_{Lo} - \kappa Z$$

The unsteady equations, with pressure and density related by assuming constant entropy reduce to:

$$\sigma \rho' + \frac{\partial u'}{\partial Z} = 0$$

$$\sigma u' + \frac{1}{\gamma} \frac{\partial p'}{\partial Z} = 0 \quad (0 \leq Z \leq \xi_1)$$

$$p' = \gamma \rho'$$

I, B, Technical Description (cont.)

Region "1"

$$\sigma \rho' + \bar{u}_e \frac{\partial \rho'}{\partial Z} + \bar{\rho} \frac{\partial u'}{\partial Z} = 0$$

$$\sigma \bar{\rho} u' + \bar{\rho} \bar{u}_e \frac{\partial u'}{\partial Z} + \frac{1}{\gamma} \frac{\partial p'}{\partial Z} = 0 \quad (\xi < z \leq 1)$$

$$p' = \gamma \bar{T} \rho'$$

These equations have the general periodic solutions

Region "0"

$$u' = C_{ro} e^{-\sigma Z} + C_{so} e^{-\sigma Z} \quad (0 \leq z \leq \xi_1)$$

$$p' = C_{ro} e^{-\sigma Z} - C_{so} e^{-\sigma Z}$$

Region "1"

$$u' = C_{rl} e^{-a_{rl} \sigma Z} + C_{sl} e^{-a_{sl} \sigma Z} \quad (\xi_1 < z \leq 1)$$

$$p' = \frac{\bar{p}}{C} C_{rl} e^{-a_{rl} \sigma Z} - C_{sl} e^{-a_{sl} \sigma Z}$$

I, B, Technical Description (cont.)

where

$$a_{rl} = \frac{1}{\bar{C} + \bar{u}} \quad \text{and} \quad a_{sl} = - \frac{1}{\bar{C} - \bar{u}}$$

The coefficients C_{ro} , C_{so} , C_{rl} , C_{sl} must be determined by the boundary conditions. Two of these boundary conditions are that $u' = 0$ at $Z = 0$ and the nozzle admittance condition:

$$\frac{u'}{p'} = \frac{\bar{u}_e}{\gamma_p^-} \alpha_N \quad (Z = 1)$$

where α is the longitudinal nozzle admittance coefficient and is in general complex.

The remaining two boundary conditions are the matching conditions across the combustion front. These are obtained by writing the mass and momentum conservation equations across the combustion front under oscillatory conditions assuming the burning rate perturbation, Q' , is given by:

$$Q' = \bar{Q}_n (1 - e^{-\sigma\tau}).$$

The details of this procedure are given in Ref. 1. Once these coefficients are obtained a characteristic equation can be written in terms of the parameters n , τ and σ . The neutral stability boundaries can then be obtained using the same procedure as that used for a transverse mode.

I, Problem (cont.)

C. EQUATIONS

1. Program A - Longitudinal Mode Analysis

Input = $M(Z^*)$, \bar{M}_e , \bar{C}_o^* , κ , γ , \bar{u}_{L0}^* , L_c^* , α_N

$$\xi_1 = 1 - \frac{\int_0^{L_c^*} M(Z^*) dZ^*}{\bar{M}_e L_c^*}$$

$$\bar{c} = \left[1 - \frac{\gamma-1}{2} \bar{M}_e^2 \right]^{1/2}$$

$$\phi_1 = \frac{2\omega \bar{c}}{\bar{c}^2 - \bar{M}_e^2} (1 - \xi_1)$$

$$\bar{u}_{L0} = \frac{\bar{u}_{L0}^*}{\bar{C}_o^*}$$

$$\bar{u}_L = \bar{u}_{L0} - \kappa \xi_1$$

$$\xi_L = \frac{\bar{M}_e}{\bar{u}_L} \frac{1}{1 - \frac{\gamma-1}{2} \bar{M}_e^2 - \gamma \bar{M}_e^2 (\kappa - 1)}$$

$$\theta_1 = 2\omega \xi_1$$

I, C, Equations (cont.)

$$B = \frac{1 + \frac{\bar{M}_e}{c} \alpha_N}{1 - \frac{\bar{M}_e}{c} \alpha_N}$$

$$C = 1 + B e^{i\phi_1}$$

$$D = 1 - B e^{i\phi_1}$$

$$E = 1 - e^{-i\theta_1}$$

$$F = 1 + e^{-i\theta_1}$$

$$\begin{aligned} I_1 + iJ &= \frac{F}{\gamma} (\bar{M}_e C - \bar{c} D) + \left[\left(\frac{1 - \frac{\gamma-1}{2} \frac{\bar{M}_e^2}{c}}{\gamma} + \frac{\bar{M}_e^2}{\gamma} \right) \left(1 + \frac{\xi_L \kappa}{\omega} \right) \right. \\ &\quad \left. - \frac{2 \bar{M}_e^2 \gamma \kappa}{\left(1 - \frac{\gamma-1}{2} \bar{M}_e^2 - \gamma \bar{M}_e^2 (\kappa - 1) \right) \omega} \right] CE + ED + \frac{2 \bar{M}_e \bar{c} \gamma \kappa}{\left(1 - \gamma \bar{M}_e^2 (\kappa - 1) \right) \omega} \\ &\quad - \left(\frac{2 \bar{M}_e \bar{c}}{\gamma} \right) \left(1 + \frac{\xi_L \kappa}{\omega} \right) \end{aligned}$$

$$K_1 + iL = F \left[\left(\frac{1 - \frac{\gamma-1}{2} \frac{\bar{M}_e^2}{c}}{\gamma} + \frac{\bar{M}_e^2}{\gamma} \right) C - \frac{2 \bar{M}_e \bar{c}}{\gamma} D \right]$$

$$M_1 + iN = \frac{I_1 + iJ}{K_1 + iL}$$

I, C, Equations (cont.)

$$T_1 = \frac{M_1^2 + N^2}{2 M_1}$$

$$\delta_m = \tan^{-1} \left(\frac{N}{T_1 - M_1} \right)$$

$$\delta = \frac{\delta_m}{\omega}$$

$$\tau = \frac{\delta_L *}{\bar{C}_o *}$$

$$n = \frac{T_1}{\bar{u}_L^\gamma \left(1 + \xi_L - \frac{1}{1 - \frac{\gamma-1}{2} \bar{M}_e^2 - \gamma \bar{M}_e^{2(\kappa-1)}} \right)}$$

Evaluate n and τ over a range of ω .

I, C, Equations (cont.)

2. Program B Transverse Mode Analysis

Input = s_{vn} , γ , $D_1(Z)$, r_c^* , L_c^* , C_o^* , \bar{u}_{Lo}^* , κ , \bar{u}_e , $\frac{1_R}{n}$, $\frac{1_\theta}{n}$, E

$$\bar{u} = \frac{D_1 \bar{u}_e}{D_1(Z=L_c)}$$

$$\text{solve } \frac{d \bar{u}_L}{dZ} = -\frac{\kappa[\bar{u} - \bar{u}_L]}{\bar{u}_L} \text{ for } \bar{u}_L$$

$$\bar{\rho} = [1 + \frac{\gamma-1}{2} \bar{u}_e^2]^{-\frac{1}{\gamma-1}}$$

$$\rho_L = [\bar{u}_e (1 + \frac{\gamma-1}{2} \bar{u}_e^2)^{-\frac{1}{\gamma-1}} - \frac{\bar{\rho} \bar{u}}{\bar{u}_L}]$$

$$\bar{Q} = \frac{[(1-\gamma \bar{u}^2) \bar{\rho} \frac{d\bar{u}}{dZ} - \gamma \bar{u} \bar{\rho}_L \kappa (\bar{u} - \bar{u}_L)]}{1 + \gamma \bar{u} (\bar{u} - \bar{u}_L)}$$

$$\Omega = (s_{vn}^2 - \omega^2)^{1/2}$$

$$Y_1 = (\gamma-1) \int_0^{L_c} \bar{Q} \cosh [\Omega(L_c - Z)] dZ + \int_0^{L_c} 2 \frac{d\bar{u}}{dZ} \cosh [\Omega(L_c - Z)] dZ$$

$$+ \frac{(\omega + i\kappa)\kappa\omega}{\kappa^2 + \omega^2} \int_0^{L_c} \frac{\rho_L}{\bar{\rho}} \cosh [\Omega(L_c - Z)] dZ$$

$$Y_2 = -\frac{s_{vn} E}{\omega} \cosh (\Omega L_c) - \frac{i\Omega}{\omega \sinh (\Omega L_c)}$$

I, C, Equations (cont.)

$$Y_2 = - \frac{s_{vn} E}{\omega} \cosh (\Omega L_c) - \frac{i \Omega}{\omega \sinh(\Omega L_c)} - \frac{i \Omega}{\omega} \sinh (\Omega L_c)$$

$$Y_3 = \frac{E s_{vn}}{\Omega} \frac{\kappa^2 \omega}{\kappa^2 + \omega^2} \int_0^{L_c} \frac{\rho_L}{\rho} \sinh [\Omega (L_c - z)] dz$$

$$- \frac{i E s_{vn}}{\Omega} \left[(\gamma - 1) \int_0^{L_c} \bar{Q} \sinh [\Omega (L_c - z)] dz \right.$$

$$+ \int_0^{L_c} 2 \frac{d\bar{u}}{dz} \sinh [\Omega (L_c - z)] dz$$

$$\left. + \frac{\omega^2 \kappa}{\kappa^2 + \omega^2} \int_0^{L_c} \frac{\bar{\rho}_L}{\bar{\rho}} \sinh [\Omega (L_c - z)] dz \right]$$

$$Y_6 = \frac{i E s_{vn}}{\Omega} \int_0^{L_c} \bar{Q} \sinh [\Omega (L_c - z)] dz$$

$$+ \int_0^{L_c} \bar{Q} \cosh [\Omega (L_c - z)] dz$$

$$h = \frac{Y_1 + Y_2 + Y_3}{Y_6}$$

evaluate h over a range of ω

I, C, Equations (cont.)

3. Program C - Nozzle Admittance

Nozzle admittance is calculated for an axisymmetric conventional or annular nozzle with an inner wall radius r_i and outer wall radius r_o . These radii are functions of axial distance Z from the nozzle throat which are defined as follows:

$$r_o^*(Z^*) = R_{ATO}^* + R_{CTO}^* - \sqrt{R_{CTO}^{*2} - Z^{*2}} , \quad 0 \leq Z^* \leq Z_{1o}^*$$

$$\text{where } Z_{1o}^* = R_{CTO}^* \sin \alpha_o$$

$$r_o^*(Z^*) = R_{ST1o}^* + \frac{Z^* - Z_{1o}^*}{Z_{2o}^* - Z_{1o}^*} (R_{ST2o}^* - R_{ST1o}^*), \quad Z_{1o}^* < Z^* \leq Z_{2o}^*$$

$$\text{where } R_{ST1o}^* = R_{ATO}^* + R_{CTO}^* (1 - \cos \alpha_o)$$

$$Z_{2o}^* = Z_{1o}^* + (R_{ST2o}^* - R_{ST1o}^*) \cot \alpha_o$$

$$R_{ST2o}^* = R_{ACo}^* - R_{CCo}^* (1 - \cos \alpha_o)$$

$$r_o^*(Z^*) = R_{ACo}^* - R_{CCo}^* + \sqrt{R_{CCo}^{*2} - (Z_{3o}^* - Z^*)^2} , \quad Z_{2o}^* < Z^* \leq Z_{3o}^*$$

$$\text{where } Z_{3o}^* = Z_{2o}^* + R_{CCo}^* \sin \alpha_o$$

I, C, Equations (cont.)

$$r_o^*(Z^*) = R_{ACo}^* \quad , \quad Z_{3o}^* \leq Z^*$$

$$r_i^*(Z^*) = R_{ATi}^* + R_{CTi}^* - \sqrt{R_{CTi}^{*2} - Z^{*2}} \quad , \quad 0 \leq Z^* \leq Z_{1i}^*$$

$$R_{CTi}^* > 0$$

$$r_i^*(Z) = R_{ATi}^* + R_{CTi}^* + \sqrt{R_{CTi}^{*2} - Z^{*2}} \quad , \quad 0 \leq Z^* \leq Z_{2i}^*$$

$$R_{CTo}^* < 0$$

$$r_i^*(Z^*) = 0 \quad , \quad R_{ATi}^* = 0$$

$$R_{ACi}^* = 0$$

$$\text{where } Z_{1i}^* = R_{CTi}^* \sin \alpha_i$$

$$r_i^*(Z^*) = R_{ST1i}^* + \frac{Z^* - Z_{1i}^*}{Z_{2i}^* - Z_{1i}^*} (R_{ST2i}^* - R_{ST1i}^*) \quad Z_{1i}^* < Z^* \leq Z_{2i}^*$$

$$\text{where } R_{ST1i}^* = R_{ATi}^* + R_{CTi}^* (1 - \cos \alpha_i)$$

$$Z_{2i}^* = Z_{1i}^* + (R_{ST2i}^* - R_{ST1i}^*) \cot \alpha_i$$

$$R_{ST2i}^* = R_{ACi}^* - R_{CCi}^* (1 - \cos \alpha_i)$$

I, C, Equations (cont.)

$$r_i^*(Z^*) = R_{ACi}^* - R_{CCi}^* + \sqrt{R_{CCi}^{*2} - (z_{3i}^* - Z^*)^2} \quad , \quad z_{2i}^* < Z^* \leq z_{3i}^*$$

$$R_{CCi}^* > 0$$

$$r_i^*(Z^*) = R_{ACi}^* - \sqrt{R_{CCi}^{*2} - (z_{3i}^* - Z^*)^2} \quad , \quad z_{2i}^* < Z^* \leq z_{3i}^*$$

$$R_{CCi}^* < 0$$

$$\text{where } z_{3i}^* = z_{2i}^* + R_{CCi}^* \sin \alpha_i$$

R_{ATO}^* , R_{ATi}^* , R_{CTo}^* , R_{CTi}^* , R_{ACo}^* , R_{ACi}^* , R_{CCo}^* , R_{CCi}^* , α_o and α_i are input data defined by Figures 14 and 15.

From the nozzle radius calculate the nozzle area a^* .

$$a^*(Z^*) = \pi [r_o^{*2}(Z^*) - r_i^{*2}(Z^*)]$$

Mach number, $M(Z)$, can be obtained by creating a table of M versus a^* from the equation.

$$\frac{a^*(Z)}{a^*(Z=0)} = \frac{1}{M(Z^*)} \left[\left(\frac{2}{\gamma+1} \right) \left(1 + \frac{\gamma-1}{2} M^2(Z^*) \right) \right]^{\frac{\gamma+1}{2(\gamma-1)}}$$

The velocity divided by the speed of sound at the throat, \bar{q} , (commonly called M^*) is given by

$$\bar{q}(Z)^2 = \frac{\frac{\gamma+1}{2} M^2(Z^*)}{1 + \frac{\gamma-1}{2} M^2(Z^*)}$$

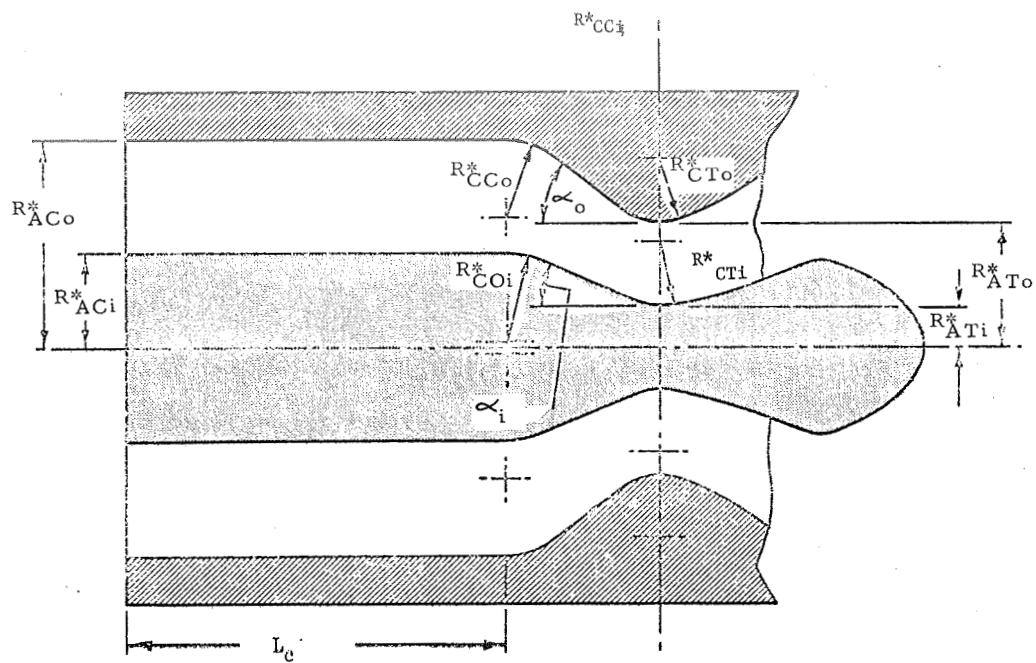


Figure 14 -- Computer Input Parameters -- Annular Chamber

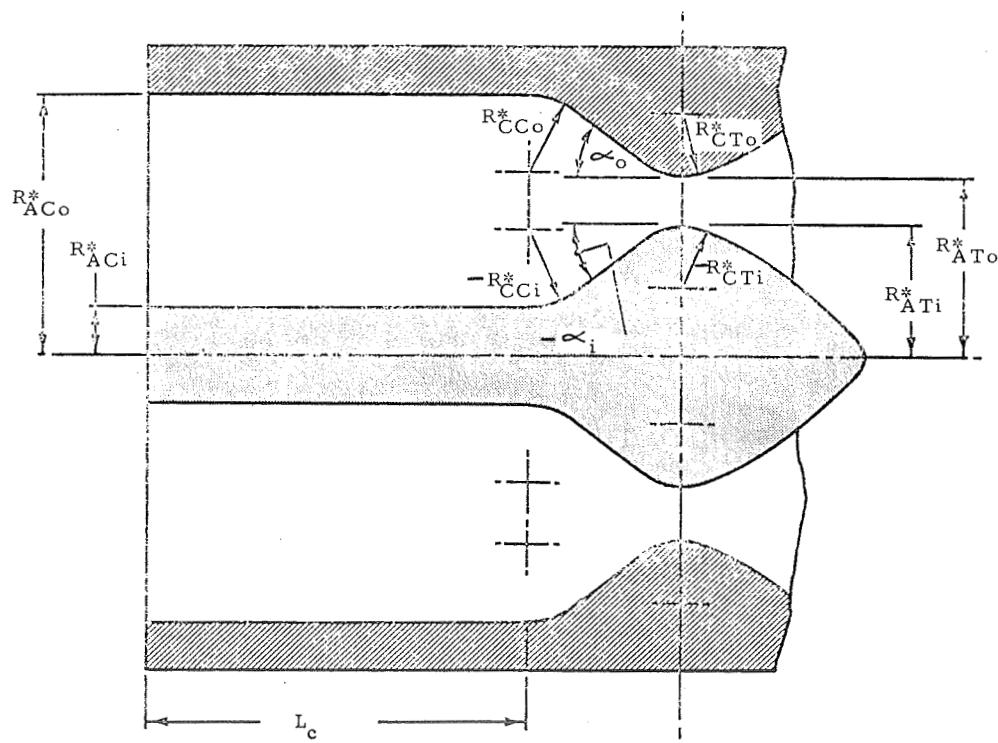


Figure 15 -- Computer Input Parameters -- Annular Chamber

I, C, Equations (cont.)

The velocity potential, which is the independent variable for the equations of motion in the nozzle, is given by

$$\hat{\phi}(Z^*) = \frac{2K}{R_{AT}^o} \int_0^Z \bar{q}(Z^*) dZ^* \quad (43)$$

Auxiliary functions $\hat{\zeta}$, $\hat{\xi}^{(1)}$, $\hat{\xi}^{(2)}$, f_3 which are required to define the admittance coefficients in the nozzle are given by the following differential equations

$$b \left(\frac{d\hat{\zeta}}{d\hat{\phi}} + \hat{\zeta}^2 \right) = (g + ih) \hat{\zeta} - (j + i k)$$

$$\begin{aligned} \frac{d}{d\hat{\phi}} \left[(1 - \bar{q}^2) \hat{\xi}^{(1)} \right] &= - \left[\hat{\zeta} - i \omega \left(\frac{1}{2\bar{q}^2} + \frac{2}{(\gamma+1)(1-\bar{q}^2)} \right) \right] (1-\bar{q}^2) \hat{\xi}^{(1)} \\ &\quad + \frac{2}{\gamma+1} \frac{\hat{s}_{vn}^2}{4} \frac{\bar{c}^{\frac{2}{\gamma-1}}}{\bar{q}} \end{aligned}$$

$$\begin{aligned} \frac{d}{d\hat{\phi}} \left[(-\bar{q})^2 \hat{\xi}^{(2)} \right] &= - \left[\hat{\zeta} - i \omega \left(\frac{1}{2\bar{q}^2} + \frac{2}{(\gamma+1)(1-\bar{q}^2)} \right) \right] (1-\bar{q}^2) \hat{\xi}^{(2)} \\ &\quad + \frac{2}{\gamma+1} \left[\frac{df_3}{d\hat{\phi}} + \frac{\hat{s}_{vn}^2 \bar{c}^{\frac{2}{\gamma-1}}}{2i\omega} \left(\frac{1-\bar{q}^2}{2\bar{q}^2} + \frac{\bar{c}^2}{\bar{q}^2} f_3 \right) \right] \end{aligned}$$

$$\frac{d}{d\hat{\phi}} (\bar{c}^2 f_3) - \frac{i\hat{\omega}}{2\bar{q}^2} (\bar{c}^2 f_3) = \frac{1}{2} \frac{d\bar{q}^2}{d\hat{\phi}}$$

where $b = \bar{q}^2 (\bar{c}^2 - \bar{q}^2)$

I, C, Equations (cont.)

$$g = \frac{\gamma+1}{2} \frac{(\bar{q})^2}{\bar{c}^2} \frac{d(\bar{q})^2}{d\phi}$$

$$h = \hat{\omega}(\bar{q})$$

$$j = \frac{\hat{\omega}^2}{4} - \frac{\bar{q}(\bar{c})}{4} \frac{2}{\gamma-1} (\hat{s}_{v\eta})^2$$

$$k = \frac{\gamma-1}{4} \frac{(\bar{q})^2}{\bar{c}^2} \frac{d(\bar{q})^2}{d\phi} \hat{\omega}$$

$$\hat{\omega} = \omega/K \quad (44)$$

$$\hat{s}_{v\eta} = s_{v\eta}/\hat{K} \quad (45)$$

$$\hat{K} = \left(\frac{d\bar{q}}{dz} \right)_{z=i} = R_{ATo}^* \left[\frac{2}{\gamma+1} \left(\frac{R_{ATo}^*}{R_{CTo}^*} - \frac{R_{ATi}^*}{R_{CTi}^*} \right) \middle/ \left(R_{ATo}^{*2} - R_{ATi}^{*2} \right) \right]^{1/2}$$

The initial values of the auxiliary functions are given as follows:

$$\hat{\xi}^{(1)}(0) = 0$$

$$\hat{\xi}^{(2)}(0) = 0$$

$$f_3(0) = 0$$

$$\hat{\zeta}(0) = \hat{\alpha}_0 + i \hat{\beta}_0$$

I, C, Equations (cont.)

$$\text{where } \hat{\alpha}_o = \frac{\frac{\gamma+1}{2} \frac{\hat{\omega}^2 - \hat{s}_{vn}^2}{4} - \frac{\gamma-1}{4} \hat{\omega}^2}{\hat{\omega}^2 + \left(\frac{\gamma+1}{2}\right)^2}$$

$$\hat{\beta}_o = -\frac{\frac{\gamma^2-1}{8} + \frac{\hat{\omega}^2 - (\hat{s}_{vn})^2}{4}}{\hat{\omega}^2 + \left(\frac{\gamma+1}{2}\right)^2}$$

The equation for $\hat{\zeta}$ is singular at $Z = 0$ so in the region of the throat $\hat{\zeta}$ is defined from its derivative at the throat

$$\left. \frac{d\hat{\zeta}}{d\phi} \right|_{Z=0} = \alpha_i + i \beta_1$$

$$\text{where } \alpha_1 = \frac{1}{\left(\frac{\gamma+1}{2}\right)^2 + \hat{\omega}^2} \left\{ \alpha_o \left[\left(\frac{\gamma+1}{2}\right)^3 + \hat{\omega}^2 \right] \right.$$

$$- \frac{\gamma+1}{2} \beta_o \left[1 - \frac{\gamma+1}{2} \hat{\omega} \right]$$

$$+ \frac{\gamma^2-1}{8} \left(\hat{\omega}^2 - \hat{s}_{vn}^2 \right) + \left(\frac{\gamma+1}{2} \right)^2 \left(\alpha_o^2 - \beta_o^2 \right)$$

$$\left. + 2 \left(\frac{\gamma+1}{2} \right) \hat{\omega} \alpha_o \beta_o \right\}$$

I, C, Equations (cont.)

$$\beta_1 = \frac{\frac{1}{2}}{\left(\frac{\gamma+1}{2}\right)^2 + \hat{\omega}^2} \left\{ \frac{(\gamma+1)(3-\gamma)}{4} \hat{\omega} \alpha_o + \beta_o \left[\left(\frac{\gamma+1}{2}\right)^3 + \hat{\omega}^2 \right] + \frac{\gamma-1}{8} \hat{\omega} \left[\left(\frac{\gamma+1}{2}\right)^2 - (\hat{s}_{vn})^2 \right] - \frac{\gamma+1}{2} \hat{\omega} (\alpha_o^2 - \beta_o^2) + 2 \left(\frac{\gamma+1}{2}\right)^2 \alpha_o \beta_o \right\}$$

The nozzle admittance coefficients can be defined from the auxiliary functions at the desired value of Z.

$$A = \frac{\left(\frac{2}{\gamma+1}\right)^{1/2} \bar{q} \bar{c}^2 \left(\hat{\xi}^{(1)} \bar{c}^2 - \hat{\zeta}\right)}{\bar{q}^2 \left(\hat{\xi}^{(1)} \bar{c}^2 - \hat{\zeta}\right) - i \frac{\hat{\omega}}{2}} \quad \frac{\frac{\gamma}{\gamma-1}}{2\bar{c}^2} \quad (46)$$

$$B = \frac{i\hat{\omega}}{\bar{q}^2} \sqrt{\frac{\bar{q}}{\bar{c}}} \frac{\frac{2}{\gamma-1}}{\frac{\hat{\xi}^{(1)} \bar{c}^2 - \hat{\zeta}}{\bar{q}^2} - i \frac{\hat{\omega}}{2}} \quad (47)$$

$$C = \frac{\left(\frac{2}{\gamma+1}\right)^{\frac{1}{2}} \bar{q} \bar{c}^2 \left(f_3 \hat{\zeta} + \frac{1-\bar{q}^2}{2} \hat{\xi}^{(1)} - i \frac{\hat{\omega}}{2} \hat{\xi}^{(2)}\right)}{\bar{q}^2 \left(\hat{\xi}^{(1)} \bar{c}^2 - \hat{\zeta}\right) - i \frac{\hat{\omega}}{2}} \quad (48)$$

I, C, Equations (cont.)

$$\alpha = - \frac{A}{\bar{M}} (z_3) \quad (49)$$

$$E = Af' + iB \quad (50)$$

$$f' = \frac{\hat{\omega}}{\hat{s}_{vn} \left(\frac{\gamma+1}{2} \right)^{1/2} \left[q \left(\frac{\gamma+1}{2} - (q)^2 \frac{\gamma-1}{2} \right)^{1/2} \right]} \quad 1/2$$

I, C, Equations (cont.)

4. Program DTake h from Program B

$$\tilde{h}_T = \frac{h}{A_{v\eta} + i \left(\frac{B_{v\eta}}{\gamma\omega} \frac{1_R}{n} + \frac{C_{v\eta}}{\gamma\omega} \frac{1_\theta}{n} \right)}$$

5. Program E

For standing mode

$$A_{v\eta} = \frac{\int_0^{2\pi} \int_0^1 \mu(r, \theta) F_P(r, \theta) J_v^2(s_{v\eta} r) \cos^2 v\theta r dr d\theta}{\int_0^{2\pi} \int_0^1 J_v^2(s_{v\eta} r) \cos^2 v\theta r dr d\theta} \quad (51)$$

$$B_{v\eta} = \frac{\int_0^{2\pi} \int_0^1 \mu(r, \theta) F_R(\omega, r, \theta) J_v'(s_{v\eta} r) J(s_{v\eta} r) \cos^2 v\theta r dr d\theta}{\int_0^{2\pi} \int_0^1 J_v^2(s_{v\eta} r) \cos^2 v\theta r dr d\theta} \quad (52)$$

$$C_{v\eta} = - \frac{\int_0^{2\pi} \int_0^1 \mu(r, \theta) \frac{F_T(r, \theta, \omega)}{r} J_v^2(s_{v\eta} r) v \sin v\theta \cos v\theta r dr d\theta}{\int_0^{2\pi} \int_0^1 J_v^2(s_{v\eta} r) \cos^2 v\theta r dr d\theta} \quad (53)$$

for a spinning mode replace

$$A_{v\eta} = \frac{A_{v\eta}}{2}$$

$$B_{v\eta} = \frac{B_{v\eta}}{2}$$

$$C_{v\eta} = \frac{i C_{v\eta}}{2}$$

I, C, Equations (cont.)

$$\mu(r, \theta) = \frac{\sigma(r, \theta)}{\sigma_{ave}} \quad (54)$$

$\sigma(r, \theta)$ is the injection density (weight flow per unit area)

σ_{ave} is the total weight flow divided by the total injector area

6. Program F

$$n(1 - e^{-i\omega\tau}) = h_T$$

7. Program I

For non-linear combustion response, input tables of burning rate versus pressure, radial velocity, and tangential velocity, ϕ_p , ϕ_R , ϕ_t . Additional data needed are: P_{oo} (amplitude of pressure oscillation being considered divided by the mean chamber pressure) TFLP, TFLR, and TFLT (the linear transfer functions for equivalent linear operation associated with the pressure, radial velocity and tangential velocity dependent nonlinear element.) A describing function is calculated at each point on the injector.

$$f_p(r, \theta) = \frac{1}{\pi P_o (TF_{LP})} \int_{-\pi}^{\pi} \phi_p(\omega\tau, r, \theta) \cos(\omega\tau) d(\omega\tau) \quad (55)$$

where

$$\phi_p(\omega\tau, r, \theta) = \phi_p(p')$$

$$p' = P_o \cos \omega\tau$$

$$P_o = |P_{oo} J_v(s_{vn} r) \cos v \theta|$$

$$F_R(r, \theta, \omega) = \frac{1}{\pi V_o (TF_{LR})} \int_{-\pi}^{\pi} \phi_R(\omega\tau, r, \theta) \cos(\omega\tau) d(\omega\tau)$$

I, C, Equations (cont.)

where

$$\phi_R(\omega\tau, r, \theta) = \phi_R(v')$$

$$v' = V_o \cos \omega\tau$$

$$V_o = |V_{oo} \left[\frac{v J_v(s_{vn} r) - s_{vn} J_{v+1}(s_{vn} r)}{r} \right] \cos v\theta|$$

$$V_{oo} = \frac{P_{oo}}{\gamma\omega}$$

$$f_T(r, \theta, \omega) = \frac{1}{\pi W_o(TF_{LT})} \int_{-\pi}^{\pi} \phi_T(\omega\tau, r, \theta) \cos(\omega\tau) d(\omega\tau)$$

where

$$\phi_T(\omega\tau, r, \theta) = \phi_T(w')$$

$$w' = W_o \cos \omega\tau$$

$$W_o = \left| \frac{V_{oo} J_v(s_{vn} r) v \sin v\theta}{r} \right|$$

8. Program J, Injected Mass Distribution Effects

This program calculates mass flow distribution $\mu(r, \theta)$ used in the program for calculating the A_{vn} , B_{vn} and C_{vn} . It also calculates useful design parameters such as pressure drops, injection velocities, mixture ratios, and flow areas. Input consists of type and location of elements, description of each element type in terms of orifice diameters and number of orifices, and overall information including propellant densities, orifice discharge coefficients, amount of film cooling, injector radius, total flow rates and total mixture ratio.

First the total orifice area, A_T , for each propellant is calculated:

$$A_T = \sum_i 0.7853891 d_i^2$$

I, C, Equations (cont.)

Then the area of the film coolant orifices, A_{FCT} , is calculated

$$A_{FCT} = \sum_i 0.7853891 d_{FC_i}^2$$

Total flows of oxidizer and fuel are then calculated. The equations used depend on how the information on the film coolant is input.

If percent film coolant is given; P_{ffc} , percent fuel film coolant; P_{xfc} percent oxidizer film coolant, the total fuel flow rate in injector matrix, W_{fT} , is given by:

$$W_{fT} = \frac{W_T}{MR+1} (1 - P_{ffc})$$

The total oxidizer flow rate in the injector matrix, W_{XT} , is given by:

$$W_{XT} = W_T - \frac{W_T}{MR+1} (1 - P_{xfc})$$

If the number and size of the film cooling orifices are given in terms of the fuel hole area in the matrix A_F , oxidizer hole area in the matrix A_X , fuel film coolant hole area A_{FFC} , and oxidizer film coolant area A_{XFC} .

$$W_{fT} = \frac{W_T}{MR+1} \frac{A_{FT}}{A_{FT} + A_{FFC}}$$

$$W_{XT} = W_T - \frac{W_T}{MR+1} \frac{A_{XT}}{A_{XT} + A_{XFC}}$$

The total weight flow per element is given by:

$$W_{Ei} = \frac{A_{Fi}}{A_{FT}} W_{fT} + \frac{A_{xi}}{A_{XT}} W_{XT}$$

I, C, Equations (cont.)

W_{Ei} is used in Program E as follows:

$$\frac{W_{Ei}}{W_T} \quad XM \quad XN = \mu_i \text{ for each element.}$$

See equations 51 to 53.

This program also calculates injector pressure drop ΔP :

$$\Delta P = \frac{W^2}{C_d^2 A^2} \frac{144}{g \cdot 64.4}$$

where C_d is the orifice discharge coefficient, A is the orifice area, W is the orifice flow rate and ρ is the propellant density. Injection velocity V is calculated from ΔP .

$$V = \frac{(144)(64.4) \Delta P}{\rho g}$$

I, Problem (cont.)

D. DEFINITION OF TERMS

$a^*(z^*)$	Area of annular nozzle
A_{Fi}	Area of the i th fuel element, in. ²
A_{xi}	Area of the i th oxidizer element, in. ²
A_{XFC}	Total area of oxidizer film coolant orifices, in. ²
A_{FFC}	Total area of fuel film coolant orifices, in. ²
A_{XT}	Total area of oxidizer orifices excluding film coolant, in. ²
A_{FT}	Total area of fuel orifices excluding film coolant, in. ²
A_{FCT}	Total film coolant area, in. ²
A_T	Total orifice area, in. ²
A_{vn}	Factor measuring the effect of nonuniform injection on stability (see Equation 37)
b	Variable used in nozzle analysis
B	Term used in longitudinal analysis
B_{vn}	Factor measuring the effect of nonuniform injection on stability (see Equation 37)
c	Speed of sound nondimensionalized by the stagnation speed of sound in the chamber analysis or the throat speed of sound in the nozzle analysis
C	Term used in longitudinal analysis
C_d	Injector orifice discharge coefficient
C_o^*	Dimensional stagnation gas speed of sound in feet per second
C_{th}^*	Dimensional speed of sound at the nozzle throat in feet per second
C_1, C_2	Constants in radial dependent factor of pressure in an annular chamber
C_{vn}	Factor measuring the effect of nonuniform injection on stability (see Equation 37) Complex $C_{vnR} + i C_{vnI}$
d_i	Diameter of the i th orifice
d_{FCi}	Diameter of the i th film in coolant orifice
D	Term used in longitudinal analysis
$D_1(z)$	Combustion distribution used in transverse analysis

I, D, Definition of Terms (cont.)

e	Base the natural logarithms
E	Term used in longitudinal analysis
f*	Dimensional frequency in Hertz
f_3	Auxiliary function in nozzle analysis, complex
f_p	$= \frac{\partial f}{\partial p}$
f_T	$= \frac{\partial f}{\partial T}$
f_v	$= \frac{\partial f}{\partial v}$
$f()$	Rate of preparatory processes before burning
f'	A nozzle frequency defined by Equation 50
F	Term used in longitudinal analysis
$F(\omega)$	Describing function defined by Equation 34
F_p	Describing function for pressure oscillations
F_R	Describing function for velocity oscillations in the radial direction
F_T	Describing function for velocity oscillations in the tangential direction
\hat{g}	Variable used in nozzle analysis
\hat{h}	Variable used in nozzle analysis
h	Part of characteristic equation which includes all acoustic effects (Equation 40) can also be viewed as a chamber admittance complex number $h = h_r + i h_i$
h_i	Imaginary part of h
h_r	Real part of h
\tilde{h}	Includes acoustic and nonuniform injection effects in the characteristic equation (see Equation 40)
\tilde{h}_i	Imaginary part of \tilde{h}
\tilde{h}_r	Real part of \tilde{h}
h_s	Total enthalpy of gas nondimensionalized by $R^* T_o^*$
i	Unit imaginary number $\sqrt{-1}$
I	Input to a nonlinear element
I_1	Term used in longitudinal analysis

I, D, Definition of Terms (cont.)

j	Variable used in nozzle analysis
J	Term used in the longitudinal analysis
$J_v()$	Bessel function of the first kind of order v
$J'_v()$	Derivative with respect to the argument of the Bessel function of the first kind of order v
k	Variable used in nozzle analysis
\hat{K}	Velocity gradient at the throat nondimensional (see Equation 45)
K	Factor involving droplet drag on frequency defined in Equation 11
K_1	Term used in longitudinal analysis
l_r	Velocity interaction index measuring the amount of interaction between gas velocity in the radial direction and the burning rate
l_θ	Velocity interaction index measuring the amount of interaction between gas velocity in the tangential direction and the burning rate
L	Term used in longitudinal analysis
L_c^*	Chamber length, in.
\dot{m}_b	Mass burning rate
\dot{m}_i	Mass injection rate
m_r	Displacement interaction index measuring the amount of interaction between gas displacement in the radial direction and the burning rate
m_θ	Displacement interaction index measuring the amount of interaction between gas displacement in the tangential direction and the burning rate
M	Mach number
M_1	Term used in longitudinal analysis
M_e	Mach number at nozzle entrance
MR	Mixture ratio
n	Pressure interaction index measuring the amount of interaction between pressure oscillations and burning rate oscillations
n_{min}	Minimum value of the pressure interaction index for a particular mode
N	Term used in the longitudinal analysis

I, D, Definition of Terms (cont.)

0	Output of a nonlinear element
0_1	Component of output of a nonlinear element at the input frequency ω_f
0_j	Component of output of a nonlinear element of a frequency $j\omega_f$: $j = 2, 3, 4$, etc.
p	Pressure nondimensionalized by the stagnation gas pressure
p_0	Zeroth order solution for pressure. Defined by Equations 12 and 13a
p_1	First order solution for pressure defined by Equations 12 and 13b
P	Z dependent factor in pressure perturbation
P_o	Amplitude of pressure oscillation
P_{oo}	Constant coefficient measuring amplitude of pressure defined in Equation 15a
P_{ffc}	Percent fuel film coolant
P_{xfc}	Percent oxidizer film coolant
q^*	Velocity nondimensionalized by the stagnation gas speed of sound, C_o^* in chamber. In the nozzle it is nondimensionalized by the speed of sound at the throat
Q	Burning rate per unit volume nondimensionalized by $\frac{p_o^* C_o^*}{r_c^*}$ or $\frac{p_o^* C_o^*}{L_c^*}$ for transverse or longitudinal modes.
r	Coordinate in the radial direction. Nondimensionalized by the chamber radius r_c^*
r_c^*	Dimensional chamber radius in inches
r_d^*	Droplet radius in feet
r_i^*	Inner radius of an annular chamber in feet
r_o^*	Outer radius of an annular chamber in feet
R^*	Gas constant
R	Ratio of inner radius and outer radius of an annular nozzle
R_{ACi}^*	Radius of inner contour of an annular chamber at the chamber entrance in inches (see Figures 14,15)
R_{ACo}^*	Radius of outer contour of an annular chamber at the chamber entrance in inches (see Figures 14,15)

I, D, Definition of Terms (cont.)

R_{ATi}^*	Radius of the throat of the inner contour of an annular nozzle in inches (see figure)
R_{ATo}^*	Radius of the throat of the outer contour of an annular nozzle in inches (see figure)
R_{CCi}^*	Radius of curvature at the chamber entrance of the inner contour of an annular nozzle in inches (see Figure)
R_{CCo}^*	Radius of curvature at the chamber entrance of the outer contour of an annular nozzle in inches (see Figure)
R_{Ci}^*	Radius of curvature at the throat of an inner contour of an annular nozzle in inches (see Figure)
R_{CTo}^*	Radius of curvature at the throat of the outer contour of an annular nozzle in inches (see Figure)
R_{STli}^*	Radius of inner contour of annular nozzle at transition between throat curvature and tangent in inches $r_i^* (Z_{li}^*)$
R_{STlo}^*	Radius of outer contour of annular nozzle at transition between throat curvature and tangent in inches $r_o^* (Z_{10}^*)$
R_{ST2i}^*	Radius of inner contour of annular nozzle at transition between chamber curvature and tangent in inches $r_i^* (Z_{2i}^*)$
R_{ST2o}^*	Radius of outer contour of annular nozzle at transition between chamber curvature and tangent in inches $r_o^* (Z_{20}^*)$
S	Z dependent factor in entropy perturbation
s_{vn}	Mode number for a transverse mode defined by Equations 19 thru 21 tabulated for a cylindrical chamber on page
\hat{s}_{vn}	Mode number used in nozzle analysis (see Equation 45)
t	time nondimensional as r_i
T	Temperature nondimensionalized by T_o^*
T_1	Term in longitudinal analysis
T_o^*	Stagnation gas temperature
TF	Equivalent linear transfer function (see Equation 33)
$(TF)_{LIM}$	Limiting linear transfer function
u	Gas velocity in the axial direction nondimensionalized by C_o^*
\bar{u}_e	Mean value of the gas velocity at the nozzle entrance nondimensionalized by the stagnation gas speed of sound
u_L	Axial velocity of liquid drops
\bar{u}_{Lo}^*	Liquid injection velocity, ft/sec (see Equation 56)
U	Z dependent factor in axial velocity perturbation

I, D, Definition of Terms (cont.)

v	Gas velocity in the radial direction nondimensionalized by C_o^*
V_o	Amplitude of radial velocity oscillation
V_{oo}	Constant coefficient measuring the amplitude of radial velocity
V	Z dependent factor is radial velocity perturbation
w	Gas velocity in the tangential direction nondimensionalized by C_o^*
W_o	Amplitude of tangential velocity oscillation
W_T	Total propellant weight _f flow rate, lb/sec
W_{FT}	Total fuel flow rate excluding film coolant, lb/sec
W_{XT}	Total oxidizer flow rate excluding film coolant, lb/sec
W_{Ei}	Flow rate of the i th element, lb/sec
$Y_v()$	Bessel function of the second kind of order v
$Y'_v()$	Derivative with respect to the argument of the Bessel function of the second kind of order v
Y_x	Mass fraction of vaporized oxidizer
Y_1, Y_2, Y_3, Y_6	Variables used in transverse analysis
Z	Length along the chamber axis nondimensionalized by the chamber length L^* for a longitudinal mode or by the chamber radius r_c^* for a transverse mode
Z_e	At nozzle entrance
Z_{li}^*	Axial distance from throat to first transition from curve to tangent for inner contour of an annular nozzle in feet
Z_{lo}^*	Axial distance from throat to first transition from curve to tangent for outer contour of an annular nozzle in feet
Z_{2i}^*	Axial distance from throat to second transition from tangent to curve for inner contour of an annular nozzle in feet
Z_{2o}^*	Axial distance from throat to second transition from tangent to curve for outer contour of an annular nozzle in feet
Z_{3i}^*	Axial distance from throat to transition from chamber to nozzle of the inner contour of an annular nozzle in feet
Z_{3o}^*	Axial distance from throat to transition from chamber to nozzle in feet

I, D, Definition of Terms (cont.)

α_N	Longitudinal nozzle admittance coefficient (see Equation 49)
α_o	Convergence angle of outer contour of an annular nozzle (see Figure 14)
α_i	Convergence angle of inner contour of an annular nozzle (see Figure 14)
α_1	Real part of derivative of ζ at throat
α_o	Real part of ζ at throat
β	Angle of orientation relative to the θ coordinate. See Figure 10
β_1	Imaginary part of derivative of ζ at throat
β_N	Longitudinal admittance coefficient for entropy, complex, $\beta_N = \beta_{N_r} + i \beta_{N_i}$
β_o	Imaginary part of ζ at throat
γ	Ratio of specific heats
Γ	Z dependent factor in the first order solution for pressure defined by Equation 15
δ_r	Displacement of gas in the radial direction due to pressure oscillations
δ_θ	Displacement of gas in the tangential direction due to pressure oscillations
δ	Term used in longitudinal analysis
δ_m	Term used in longitudinal analysis
ΔP	Injector pressure drop, $lb/in.^2$
ζ	Variable in Z direction used in various integrals
ζ^\wedge	Auxiliary function in nozzle analysis complex
η	Index numbering the zeros in the derivative of the Bessel function
θ	Coordinate in the tangential direction
θ_1	Term used in longitudinal analysis
θ_F	Fuel angle of injection measured from Z axis
θ_x	Oxidizer angle of injection measured from Z axis
θ	θ dependent factor in the solution for pressure defined in Equation 15
θ^*	Complex conjugate of θ
κ	Momentum interchange coefficient between droplets and gas $* = \frac{9}{2} \frac{\mu^*}{r_d^{*2} \rho_L^*}$ nondimensionalized by $\frac{C_o^*}{r_d^*}$ or $\frac{C_o^*}{L_c^*}$ for transverse or longitudinal modes

I, D, Definition of Terms (cont.)

λ	Real part of complex frequency σ
μ	Burning rate distribution function = $\frac{\sigma}{\sigma_{\text{mean}}}$
μ^*	Viscosity in lb-sec/ft ²
v	Order of the Bessel function which indicates the number of cycles of pressure oscillation when traversing in the tangential direction at a fixed radius, axial length and time
v_F	Fuel injection velocity, ft/sec
v_x	Oxidizer injection velocity ft/sec
ξ	Factor involving droplet drag, frequency and liquid inertance defined in Equation 11
ξ_1	Distance from injector to concentrated combustion front nondimensionalized by chamber length
ξ_L	Term used in longitudinal analysis
$\xi(1)$	Auxiliary function in nozzle analysis, complex
$\xi(2)$	Auxiliary function in nozzle analysis, complex
ρ	Density of chamber gases nondimensionalized by the stagnation gas density ρ_o^*
ρ_L^*	Density of liquid droplets, lb-sec ² /ft ⁴
σ	Complex frequency nondimensionalized as the reciprocal of τ_i
σ	Injection density
σ_{mean}	Mean injection density
τ_i	Portion of time lag which is insensitive to pressure oscillations nondimensionalized by $\frac{L_c^*}{C_o^*}$ for a longitudinal mode and $\frac{C}{C_o^*}$ for a transverse mode
τ	Mean sensitive time lag nondimensional as τ_i
τ_T	Total time delay between injection of propellant and burning of that same propellant nondimensional as τ_i
τ^*	Sensitive time lag in milliseconds
ϕ	Velocity potential in the exhaust nozzle
ϕ_P	Function relating input pressure to the combustion to the output (burning rate)

I, D, Definition of Terms (cont.)

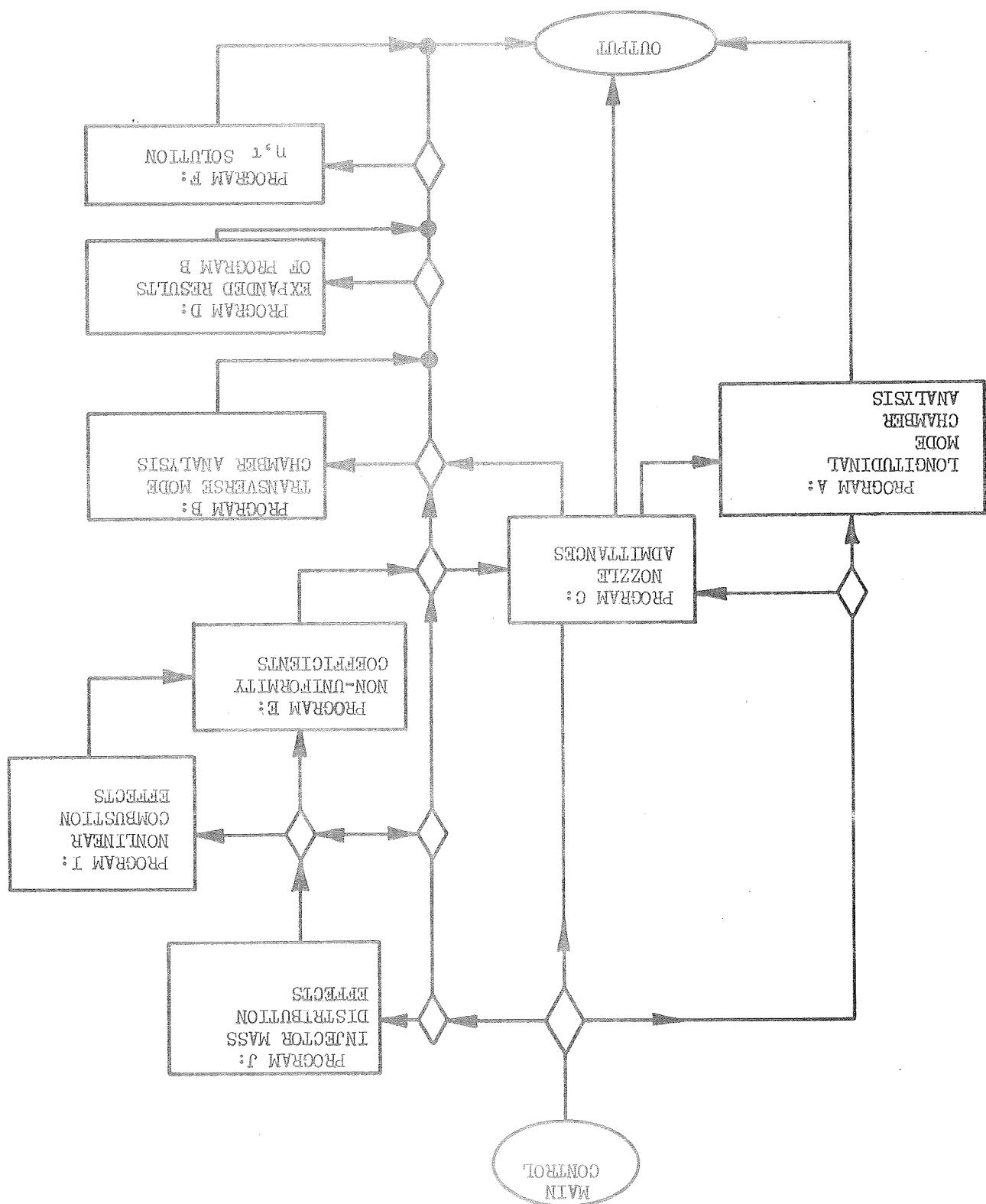
ϕ_R	Function relating input radial velocity to the combustion to the output (burning rate)
ϕ_T	Function relating input tangential velocity to the combustion to the output (burning rate)
ϕ_1	Term used in longitudinal analysis
X	ωt
ψ	Stream function in the exhaust nozzle
Ψ	r dependent factor in the solution for pressure defined by Equation 15
ω	Imaginary part of complex Laplace variable σ
	For a transverse mode in chamber $\omega = \frac{2 f^* r^* c}{C_o^* 12}$
	For a longitudinal mode in chamber $\omega = \frac{2 f^* L^* c}{C_o^* 12}$
	For the nozzle $\omega = \frac{2 f^* R_{AT}^* c}{C_{th}^* 12}$
ω_f	Frequency of input signal to a nonlinear element
$\hat{\omega}$	Nondimensional frequency used in nozzle analysis (see Equation 44)
Ω	$(s_{vn}^2 - \omega^2)^{1/2}$
A	Nozzle admittance coefficient (see Equation 38). Complex number $A = A_r + i A_i$
B	Nozzle admittance coefficient (see Equation 38). Complex number $B = B_r + i B_i$
C	Nozzle admittance coefficient (see Equation 38). Complex number $C = C_r + i C_i$
E	Combined nozzle admittance coefficient defined by Equation 50. Complex number $E_r + i E_i$
P	Pressure sensitive combustion response define as $n(1-e^{-\sigma\tau})$
R	Radial velocity sensitive combustion response defined by $l_r(1-e^{-\sigma\tau})$
R_δ	Radial displacement sensitive combustion response defined by $m_r(1-e^{-\sigma\tau})$
T_δ	Tangential displacement sensitive combustion response defined by $m_\theta(1-e^{-\sigma\tau})$

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I, D, Definition of Terms (cont.)

- T Tangential velocity sensitive combustion response defined by
 $1_{\theta}(1-e^{-\sigma T})$
- $\bar{\cdot}$ A bar over a variable indicates it is a mean quantity and does not depend on time
- ' A prime on a variable indicates it is a perturbation quantity

FIGURE 16 -- General Flow Diagram of the Computer Program



I, Problem (cont.)

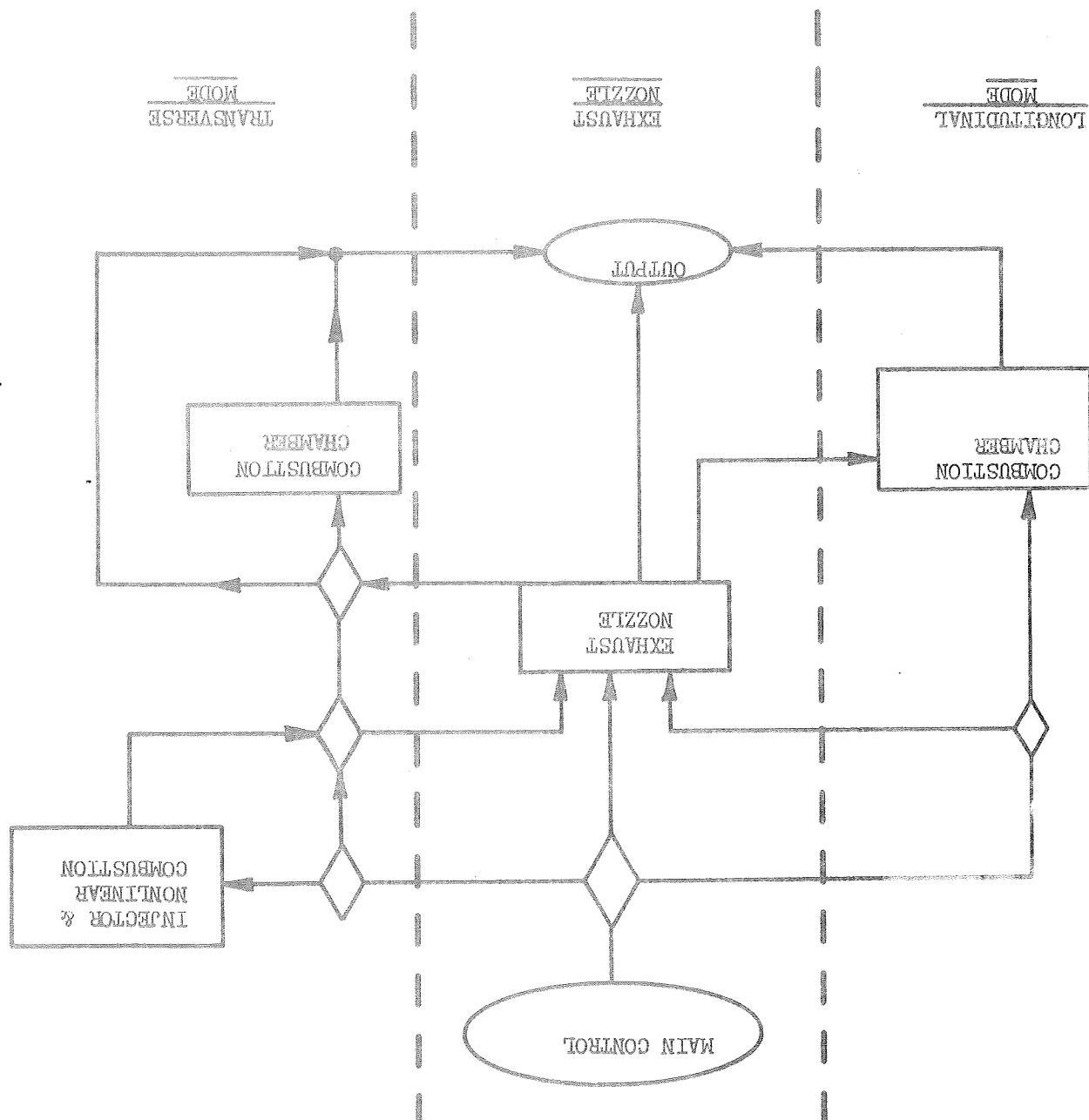
E. SPECIAL OPTIONS

The stability solution of any given liquid rocket engine must consider the three main portions of that engine: (1) the injector, (2) the combustion chamber, and (3) the exhaust nozzle. Furthermore, oscillatory conditions can exist along the longitudinal direction as well as the transverse (i.e., tangential and radial) directions. It is clear that these considerations serve as the basis for building the computer program.

The complete program consists of nine separate subprograms which may be used independently or in various combinations depending upon the data available and the information required by the designer. Figure 16 shows the interrelationships of the programs and the optional routes for proceeding with the calculation. The individual programs are:

- A. Longitudinal Mode Chamber Analysis, used to obtain n , τ stability mapping for longitudinal modes.
- B. Transverse Mode Chamber Analysis. For simplicity only the analysis is performed; the n , τ mapping is done later in Program F.
- C. Nozzle Admittance. Here the resistive effects of the nozzle are calculated for both longitudinal and transverse modes.
- D. Expansion of Results from Program B by interpolation and add nonuniformity and velocity effects.
- E. Injector Nonuniformity Coefficients. Calculates modulating coefficients for the effects resulting from uneven injection distribution and nonlinear combustion response.
- F. Stability Mapping (n , τ) for Transverse Modes
- G. Not in use
- H. High Combustion Chamber Mach Number Analysis (not operational)
- I. Nonlinear Combustion Response. Input to Program E.
- J. Injected Mass Distribution Effects

Figure 17 -- Overall Schematic of Computer Program



I, E, Special Options (cont.)

To assure that the proper subprograms are requested it is necessary to introduce a regulatory device that monitors the course of the entire program as it proceeds from one portion of the engine to another. This regulatory device is called MAIN CONTROL and serves to direct the flow of the solution in a consistent manner. Figure 16 illustrates the basic framework of the computer program. The diamond-shaped symbols can be considered as switches that are turned on if the particular item is to be analyzed by the program or turned off if the item is not needed. It is the function of MAIN CONTROL to turn these switches on or off according to the dictates of the problem.

It can be seen in Figure 17 that the program is divided into 3 parts: (1) longitudinal modes, (2) transverse modes, and (3) exhaust nozzle. The exhaust nozzle portion has been carried over from the program's early development when nozzle parametric studies were conducted.

The versatility of the program is illustrated in Figure 16 by the various flow-paths that can be constructed. For example, if the required injector and nozzle data were known beforehand, one could determine the transverse stability of the engine by merely running the combustion chamber program. If, on the other hand, all the data were unknown, proper use of MAIN CONTROL would initiate the injector, nozzle, and chamber programs. Therefore, the program is as suitable for parametric studies as it is for analysis of specific designs.

It can be seen that the transverse portion of the program is more detailed than the longitudinal portion. The injector requires programs, J, I, and E to evaluate the injector parameters that affect stability. The chamber analysis requires B, D, and F. It should be noted that program D is more of a convenience than a necessity while program F determines the solution of n and τ .

I, E, Special Options (cont.)

Following is an outline which will help determine which programs are to be run when evaluating an engine design.

I. Longitudinal Modes

A.* Is the nozzle admittance coefficient (α_N) known?

1. YES: Input this datum
2. NO: Run Program C

B. Run Program A

II. Transverse Modes

A.* Are the nozzle admittances (A, B, C) known?

1. YES: Input the data
2. NO: Run Program C

B.* Are the injector non-uniformity coefficients (A_{vn} , B_{vn} , C_{vn})** known?

1. YES: Input the data
2. NO: Run Program E

a. Is the mass distribution (μ) around the face known?

- (1) YES: Input the data
- (2) NO: Run Program J (Usual Case)

b.* Is the combustion response linear [F_P , F_R , $F_T = 1$]?

- (1) YES: DO NOT RUN PROGRAM I (Usual Case)
- (2) NO: RUN Program I

C. Do you want more than 10 points on the stability plane?

1. YES: Run Program D (RECOMMENDED)
2. NO: Do not run Program D

*Changes with mode (e.g., first tangential, second radial, etc.)

**If the injector has a uniform injection profile, $A_{vn} = B_{vn} = C_{vn} = 1.0$.

I, E, Special Options (cont.)

D. Do you want n, τ points?

1. YES: Run Program F
2. NO: Do not run Program F

If the instruction given is to "input the data", the proper L-numbers can be obtained from the section on input data.

I, E, Special Options (cont.)

In addition to evaluating specific designs parametric surveys can be run to evaluate the effect of particular portions of the program. The following outline may be helpful for this purpose:

I. NOZZLE EFFECTS: Run Program C

II. VARIATION OF NON-UNIFORMITY COEFFICIENTS WITH RESPECT TO:

a. Mass Distribution

- (1) Input the data (μ) to Program E
- (2) Run Programs J and E

b. Nonlinear combustion response

- (1) Input the data (F_p , F_R , F_T) to Program E
- (2) Run Programs I and E

c. Both mass distribution and nonlinear combustion response

- (1) Input the data (μ , F_p , F_R , F_T) to Program E
- (2) Run Programs E, I, and J as needed.

III. Variation of the stability zones with respect to:

a. Nozzle effects

- (1) Input the data (A , B , C)
- (2) Run Programs C and A or B, C, D, and F

b. Non-uniformity coefficients

- (1) Input the data ($A_{v\eta}$, $B_{v\eta}$, $C_{v\eta}$) and run B
- (2) Run B, D, E, and F

c. et al

No further extension of the parametric study outline is necessary. The ones that have been presented serve as a guide to the others. There are countless other variations that might be considered.

I, Problem (cont.)

F. NUMERICAL METHODS OF SOLUTION*

As seen in Section C the nozzle admittance coefficients are defined in terms of a system of non-linear differential equations which must be integrated from the throat to the nozzle entrance. These equations are integrated using Adams integration. Adams integration, as developed at Aerojet, uses several subroutines: ADSET, ADINT, ADCOR, ADRES and ADPAR. A description of Adams integration, which is reproduced from an Aerojet manual, follows:

PURPOSE

To integrate a system of N simultaneous first order differential equations.

RESTRICTIONS

N \leq 200

METHOD

Adam's method of integration as described in Computing Services Report #13, "Adam's Method of Integration of Differential Equations", by Dr. R. D. Glauz, is used. Accurate computation of functional values between integration steps is possible using partial step integration. The set of differential equations must be written as a system of first order equations in the form:

$$\frac{dy_1}{dx} = f_1(x, y_1, y_2, \dots, y_n)$$

$$\frac{dy_n}{dx} = f_n(x, y_1, y_2, \dots, y_n)$$

*Nomenclature in this section does not correspond to the rest of the report.

I, F, Numerical Methods of Solution (cont.)

USAGE

This subroutine has five separate entries:

1. The initial setup of the integration which specified number of equations and storage locations is done at the beginning of the program with the statement:

CALL ADSET (N, F, D, P, T, X, H, E)

with

N = number of first order differential equations to be integrated.

F = location of integrated y_1, y_2, y_n .

D = location of derivatives $\frac{dy_1}{dx}, \frac{dy_2}{dx}, \frac{dy_n}{dx}$

P = location of interpolated or partial step

$y_1^P, y_2^P, \dots, y_n^P$.

T = temporary storage having 8N cells

X = independent variable

H = integration step (initially set at approximate value)

E = location of desired accuracy, E (1) = accuracy of $y_1 \dots$

E (n) = accuracy of y_n . If E (I) = 0 then program sets

$E(I) = 10^{-8}$

I, F, Numerical Methods of Solution (cont.)

2. To integrate forward a single integration step use:

CALL ADINT

100 D(1) = ...

D(2) = ...

.

.

D(N) = ...

CALL ADCOR (& 100)

The ADINT entry will predict values of y_1, \dots, y_n at x^+ and the ADCOR corrects these values. After the CALL ADCOR statement one has available the values of y_1, y_2, y_n at the new value of x .

3. To obtain functional values y_1, \dots, y_n at a discontinuity or print point x_p use the statement:

CALL ADPAR (XP)

This will compute y_1^P, \dots, y_n^P and put these values in the P(N) array. This will not affect the values in F, D, T.

4. To restart the integration such as at a discontinuity:

CALL ADRES

This will zero out the difference table, compute new values for desired accuracy (e.g., if numbers in E have been changed) and set a flag to restart the integration.

The following two equations are the predictor and connector equations written in terms of the backward difference operator $\nabla_n = y_n(x_k) - y_n(x_{k-1})$:

$$y_n^P(x_{k+1}) = y_n(x_k) + H \left(1 + \frac{1}{2} \nabla + \frac{5}{12} \nabla^2 + \frac{3}{8} \nabla^3 + \frac{251}{720} \nabla^4 \right) \frac{dy_n(x_k)}{dx}$$

I, F, Numerical Methods of Solution (cont.)

$$y_n^c(x_{k+1}) = y_n(x_k) + H \left[\frac{251}{720} \frac{dy_n(x_{k+1})}{dx} + \left(\frac{469}{720} + \frac{109}{720} \nabla + \frac{49}{720} \nabla^2 + \frac{32}{720} \nabla^3 \right) \frac{dy_n(x_k)}{dx} \right]$$

In these equations the integration error is controlled by changing H, the integration step size. The table of backward differences is modified whenever the integration step is changed. This table of backward differences is also used to interpolate for intermediate values of the function by using a 4th order interpolating polynomial.

Also in the nozzle admittance calculation a table of velocity potential is calculated by integrating the steady state velocity profile (Equation 43). Simpson's one third rule is used to evaluate this integral. This method approximates the curve to be integrated by a parabola.

In calculating the sensitive time lag τ an inverse tangent function of a fraction is required (Eq. 42). The inverse tangent in the computer library picks an angle between plus ninety degrees and minus ninety degrees. The correct quadrant of τ is determined by the signs of the numerator and denominator of the fraction. Subroutine QUAD calculates the correct quadrant.

I, F, Numerical Methods of Solution (cont.)

Boole's Integration

The Boole's integration subroutine for evaluating a definite integral in program A uses two entries: INTGR, INTGS. This subroutine uses Boole's formula and Simpson's rule to find the integral of a function between known limits. Boole's formula is used to extrapolate two Simpson's rule values with $H = \Delta X$ and $2 \Delta X$ to obtain an answer for the integral which is more accurate than either of the two alone.

$$\int_a^b y \, dx = I_H = \frac{H}{3} \left[y(x_0) + 4y(x_1) + 2y(x_2) + 4y(x_3) + \dots - y(x_k) \right]$$

$$I_{\text{Boole}} = I_H = \Delta X + \frac{\frac{I_H = \Delta X}{15} - \frac{I_H = 2\Delta X}{15}}{15}$$

I, F, Numerical Methods of Solution (cont.)

Bessel Functions

The BESJ subroutine computes the J Bessel function for a given argument and integer order by using the recurrence relationship:

$$F_{n+1}(x) + F_{n-1}(x) = \left(\frac{2n}{x}\right) F_n(x)$$

The desired Bessel function is:

$$J_n(x) = \frac{F_n(x)}{\alpha}$$

where

$$\alpha = F_0(x) + 2 \sum_{M=1}^{M-2} F_{2m}(x)$$

M is initialized at M₀.

M₀ is the greater of M_A and M_B where:

$$M_A = [x+6] \quad \text{if } x < 5 \text{ and } M_A = [1.4x+60/x] \quad \text{if}$$

$$x \geq 5.$$

$$M_B = [n+x/4+2]$$

F_{M-2}, F_{M-3}, ..., F₂, F₁, F₀ is evaluated using the recurrence relationship above with F_M = 0 and F_{M-1} = 10⁻³⁰.

I, F, Numerical Methods of Solution (cont.)

α and $J_n(x)$ are then computed

The computation is repeated for $M+3$.

The values of $J_n(x)$ for M and $M+3$ are compared:

$$\text{If } | J_n(x)_M - J_n(x)_{M+3} | \leq \delta | J_n(x)_{M+3} |$$

this value is accepted as $J_n(x)$; if not, the computation is repeated by adding 3 to M and using this as a new value for M . If M reaches M_{MAX} before the desired accuracy is obtained, execution is terminated. M_{MAX} is defined as:

$$M_{MAX} = \begin{cases} [20 + 10x - \frac{x^2}{3}] & \text{for } x \leq 15 \\ [90 + x/2] & \text{for } x > 15 \end{cases}$$

The BESY subroutine computes the Y Bessel function for a given argument x and order n . The recurrence relation:

$$Y_{n+1}(x) = (\frac{2n}{x}) \cdot Y_n(x) - Y_{n-1}(x)$$

is used for this evaluation.

I, F, Numerical Methods of Solution (cont.)

For $x > 4$

$$Y_0(x) = \left(\frac{2}{\pi x} \right)^{1/2} \left[P_0(x) \sin \left(x - \frac{\pi}{4} \right) \right.$$

$$\left. + Q_0(x) \cos \left(x - \frac{\pi}{4} \right) \right]$$

$$Y_1(x) = \left(\frac{2}{\pi x} \right)^{1/2} \left[-P_1(x) \cos \left(x - \frac{\pi}{4} \right) \right.$$

$$\left. + Q_1(x) \sin \left(x - \frac{\pi}{4} \right) \right]$$

$P_0(x)$, $Q_0(x)$, $P_1(x)$, and $Q_1(x)$ are:

$$\begin{aligned} \frac{1}{\sqrt{2/\pi}} P_0 \left(\frac{4}{t} \right) = & 0.3989422793 - 0.0017530620t^2 \\ & + 0.0001734300t^4 - 0.0000487613t^6 \\ & + 0.0000173565t^8 - 0.0000037043t^{10} \end{aligned}$$

$$\begin{aligned} \frac{1}{t\sqrt{2/\pi}} Q_0 \left(\frac{4}{t} \right) = & -0.124669441 + 0.0004564324t^2 \\ & - 0.0000869791t^4 + 0.0000342468t^6 \\ & - 0.0000142078t^8 + 0.0000032312t^{10} \end{aligned}$$

$$\begin{aligned} \frac{1}{\sqrt{2/\pi}} P_1 \left(\frac{4}{t} \right) = & 0.3989422819 + 0.0029218256t^2 \\ & - 0.0002232030t^4 + 0.0000580759t^6 \\ & - 0.0000200920t^8 + 0.0000042414t^{10} \end{aligned}$$

I, F, Numerical Methods of Solution (cont.)

$$\frac{1}{t\sqrt{2/\pi}} Q_1\left(\frac{4}{t}\right) = 0.0374008364 - 0.0006390400t^2 + 0.0001064741t^4 - 0.0000398708t^6 + 0.0000162200t^8 - 0.0000036594t^{10}$$

where $t = \frac{4}{x}$

For $x \leq 4$

$$Y_0(x) = \frac{2}{\pi} \sum_{m=0}^{15} (-1)^m \left(\frac{x}{2}\right)^{2m} \frac{1}{(m!)^2}$$

$$\left[\log \frac{x}{2} + \gamma - H_m \right]$$

where

$$H_m = \sum_{r=1}^m \frac{1}{r} \text{ if } m \geq 1 \text{ or } = 0 \quad \text{if } m = 0$$

and $\gamma = \text{Euler's constant} = 0.5772156649$

$$Y_1(x) = -\frac{2}{\pi x} + \frac{2}{\pi} \sum_{m=1}^{16} (-1)^{m+1} \left(\frac{x}{2}\right)^{2m-1}$$

$$\frac{1}{m! (m-1)!} \cdot \left[\log \frac{x}{2} + \gamma - H_m + \frac{1}{2m} \right]$$

I, Problem (cont.)

G. TECHNICAL REFERENCES

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2. Reardon, F. H., Mc Bride, J. M., and Smith, A. J., Jr., Effect of Injection Distribution on Combustion Stability, AIAA Paper No. 65-613, AIAA Propulsion Joint Specialist Conference, Colorado Springs, Colorado, June 1965.
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6. Crocco, L., and Cheng, S. I., Theory of Combustion Instability in Liquid Propellant Rocket Motors, AGARDograph No. 8, Butterworths Scientific Pub., Ltd, London, 1956.
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10. Wieber, P. R., and Mickelsen, W., Effect of Transverse Acoustic Oscillations on the Vaporization of a Liquid-Fuel Droplet, NASA TN D-287, May 1960.
11. Crocco, L., and Sirignano, W. A., Behavior of Supercritical Nozzles Under Three Dimensional Oscillatory Conditions, AGARDograph 117, 1967.
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I, Problem (cont.)

H. RELATED PROJECTS

This program and its predecessors have been used to analyze many engines and proposed engines. The parts of the program concerned with velocity effects and non-linear response have not been used since not enough is known about either of these effects to define the parameters involved. These parts of the program are intended to be research tools.

The major programs on which this program has been used are the following: Gemini Stability Improvement Program (AF 04(695)-517) demonstrated the effect of nonuniform injection on combustion stability. A series of contracts (NAS8-4008, NAS8-11741, NAS8-20672) which were concerned with the stability characteristics of hydrogen-oxygen at high chamber pressures (500 to 2500 psi) used this program to help correlate stability data. The program was also used on Apollo (NAAI-M6J7XAA-400000A), M-1 (NAS3-2555) and Transtage (F04695-68-C-0297)

Report 20672-P2D

Section II, Programming

II, Programming

A. BLOCK DIAGRAM

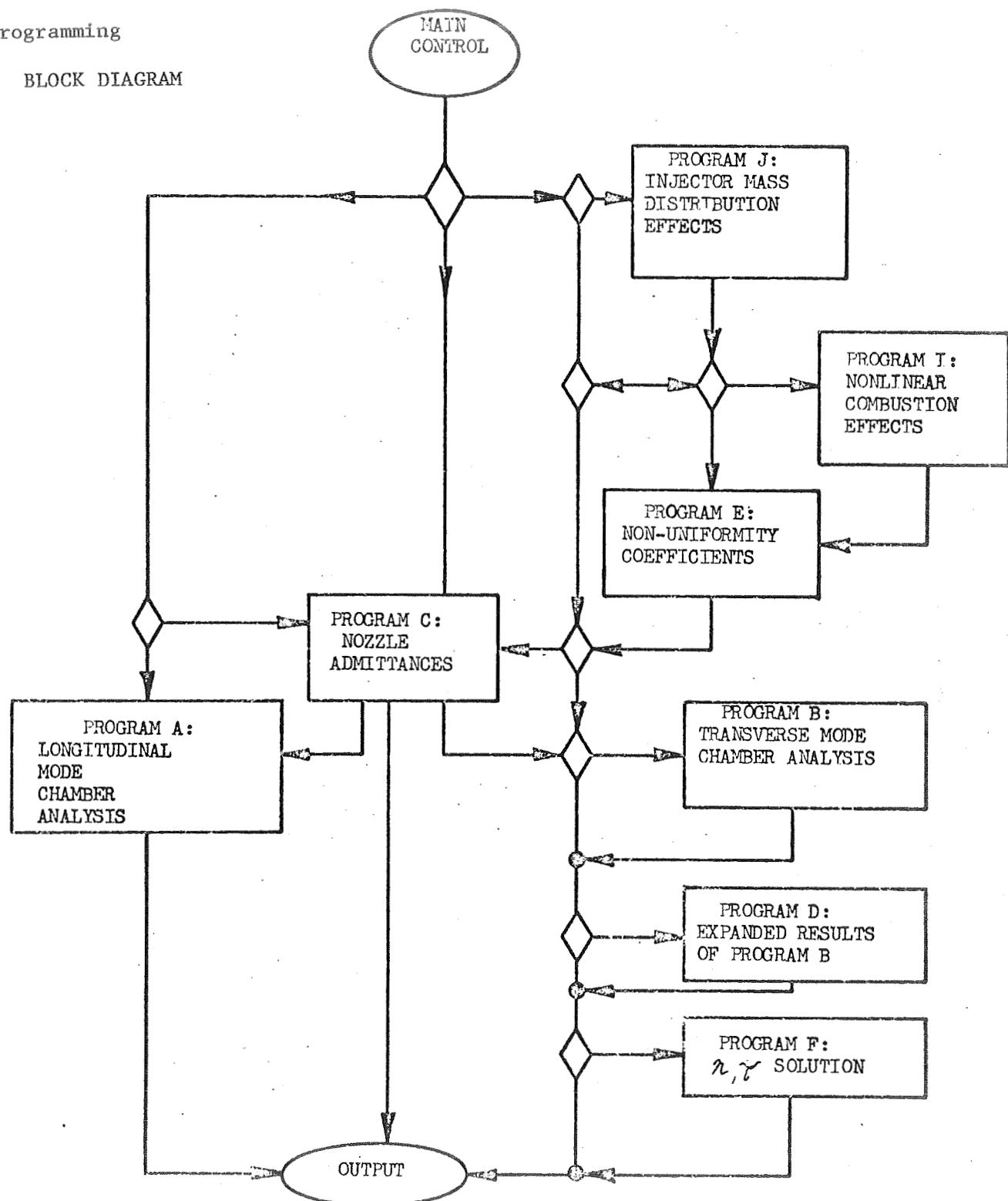


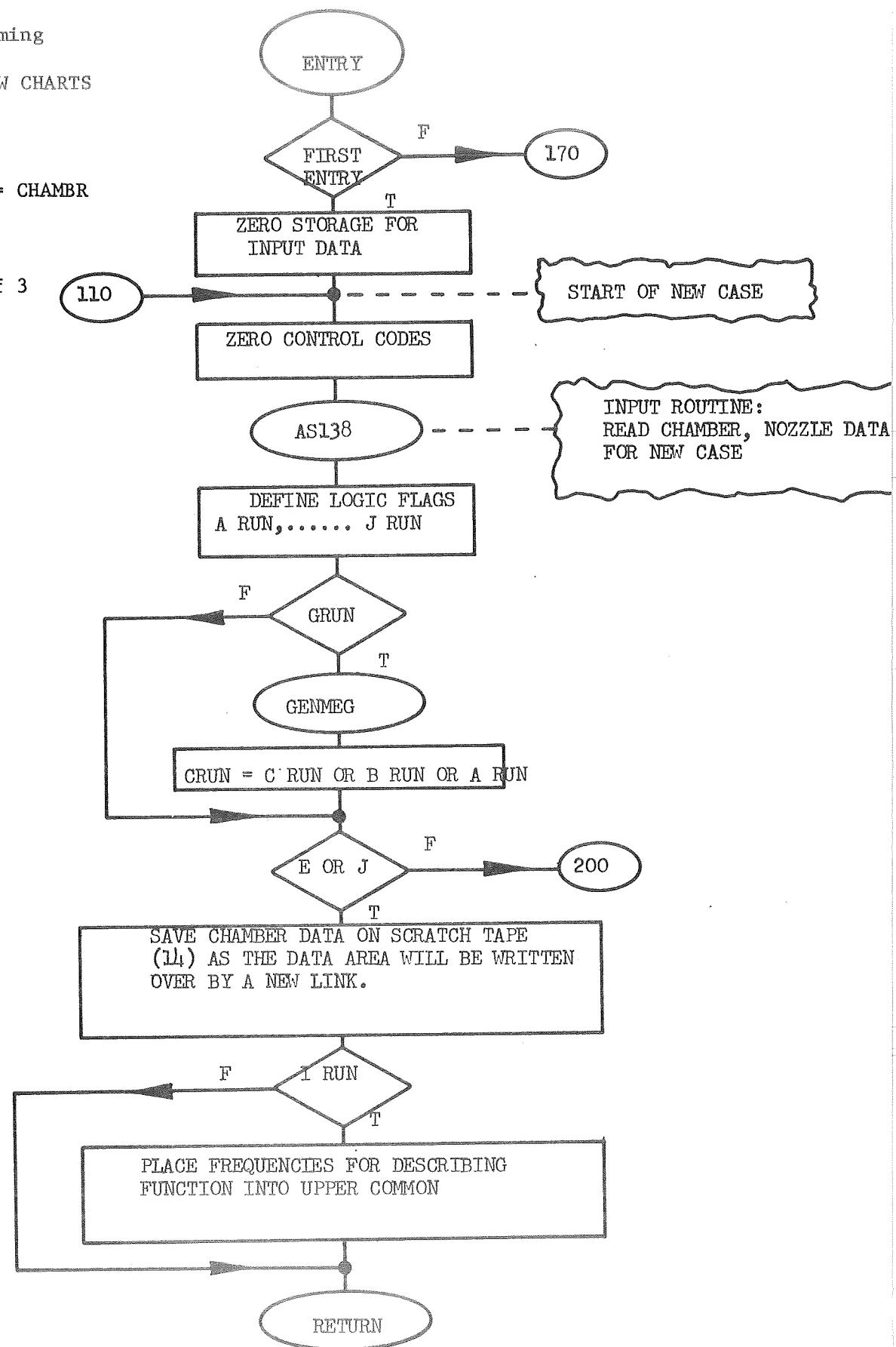
Figure 18 -- Block Diagram of Computer Program

II, Programming

B. FLOW CHARTS

ENTRY = CHAMBR

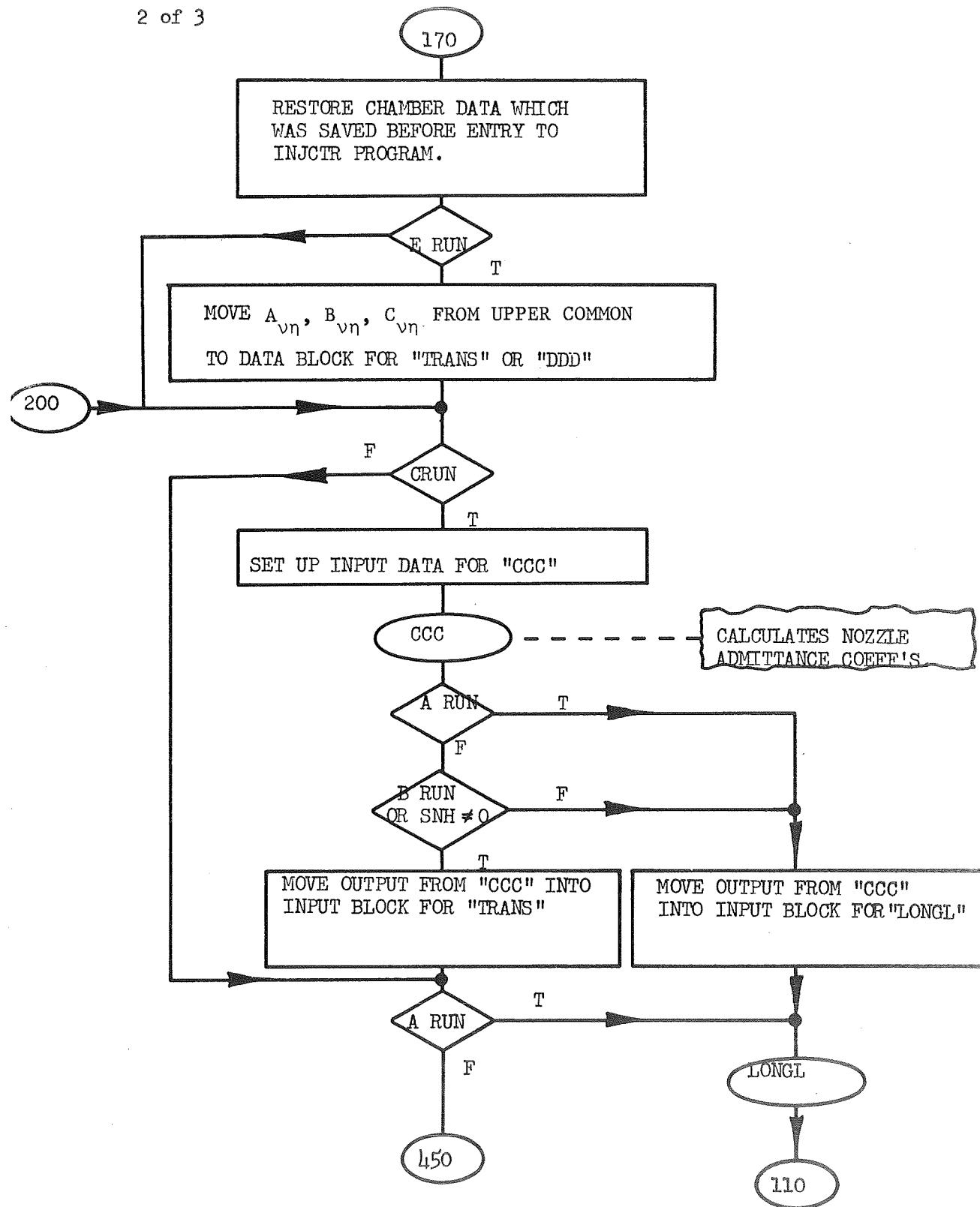
1 of 3



II, B, Flow Charts (cont.)

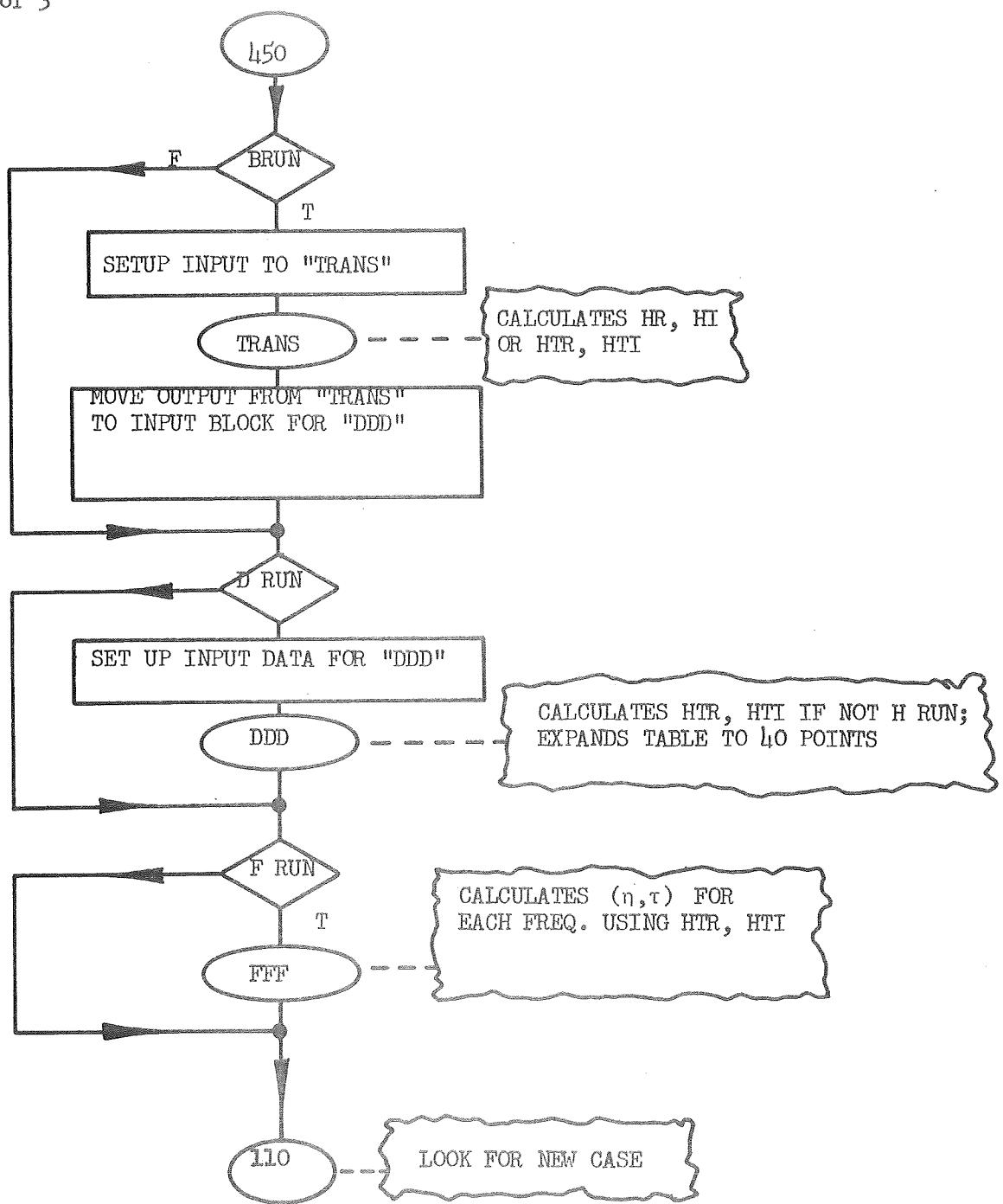
ENTRY = CHAMBER

2 of 3



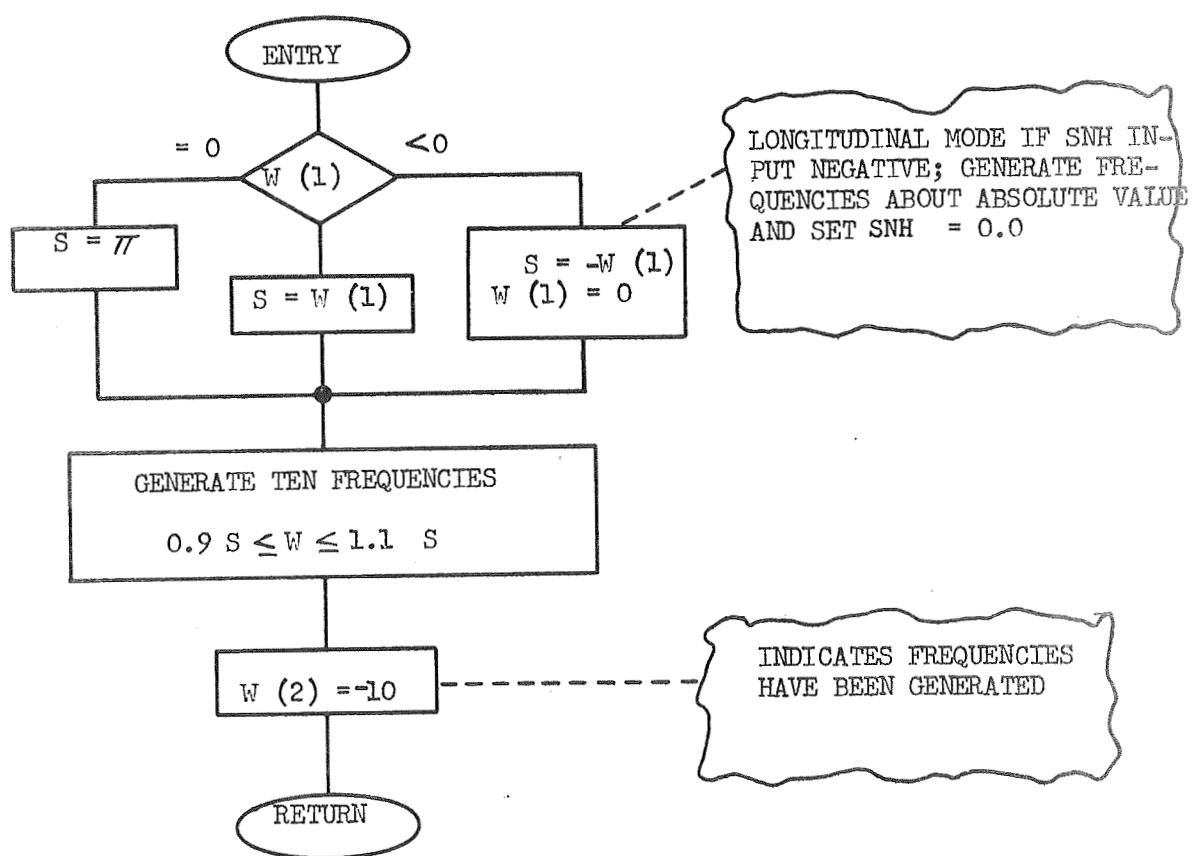
II, B, Flow Charts (cont.)

3 of 3



II, B, Flow Charts (cont.)

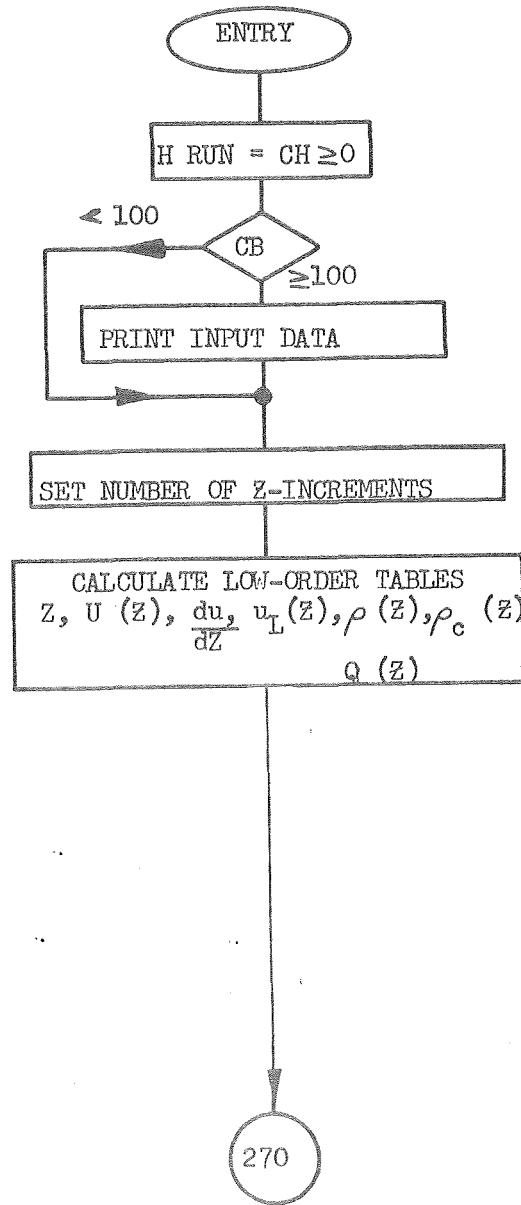
ENTRY = GEMMEG



II, B, Flow Charts (cont.)

ENTRY = TRANS

1 of 2

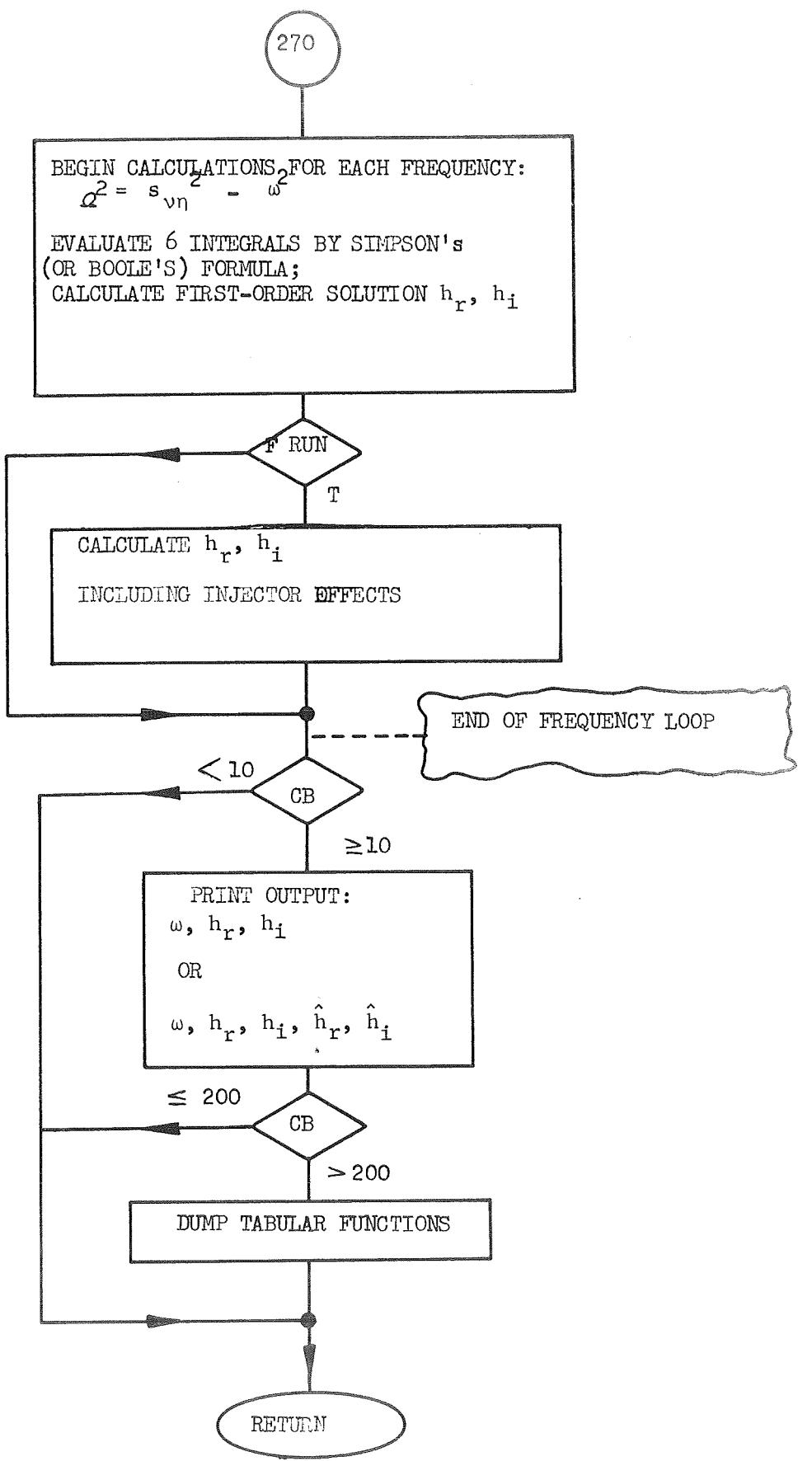


II, B, Flow Charts (cont.)

ENTRY = TRANS

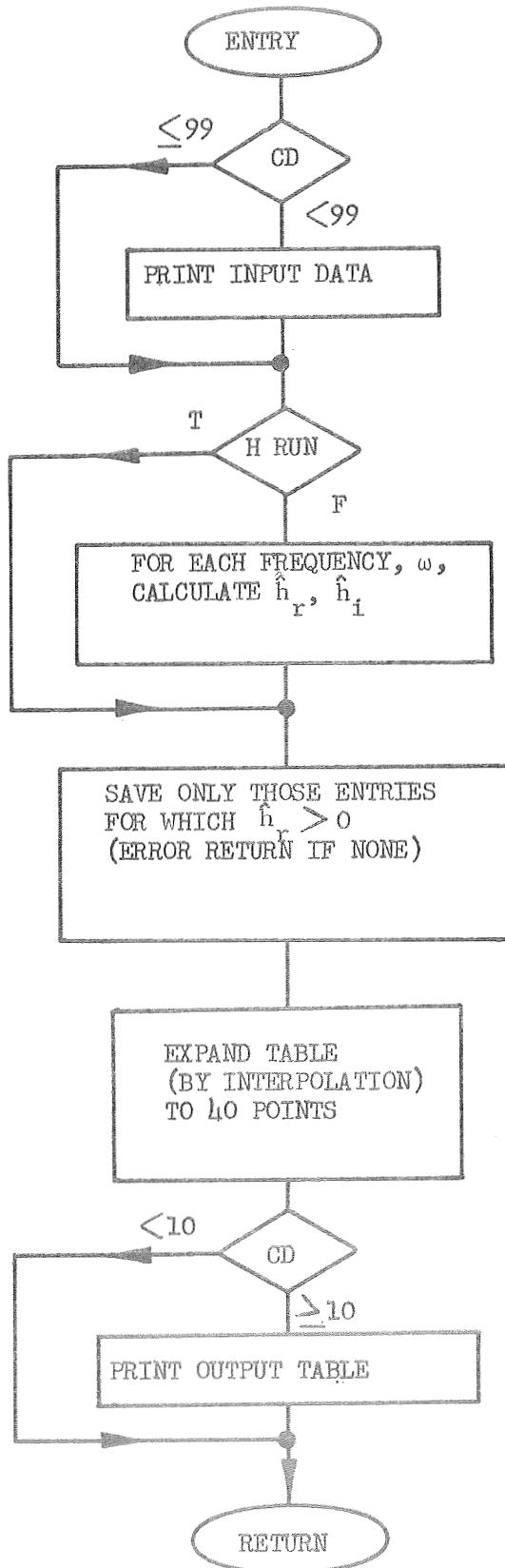
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2 of 2



II, B, Flow Charts (cont.)

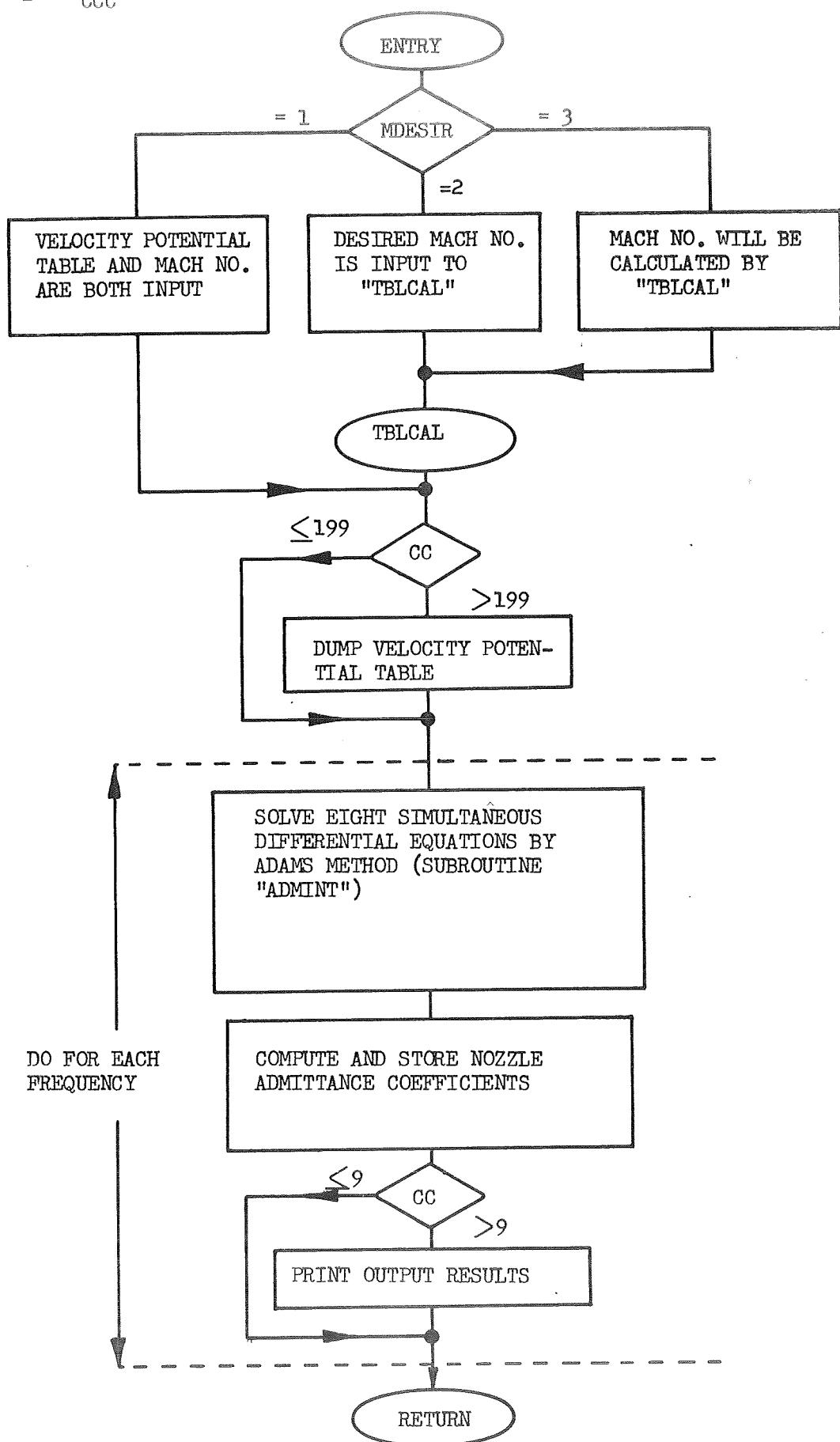
ENTRY = DDD



II, B, Flow Charts (cont.)

ENTRY = CCC

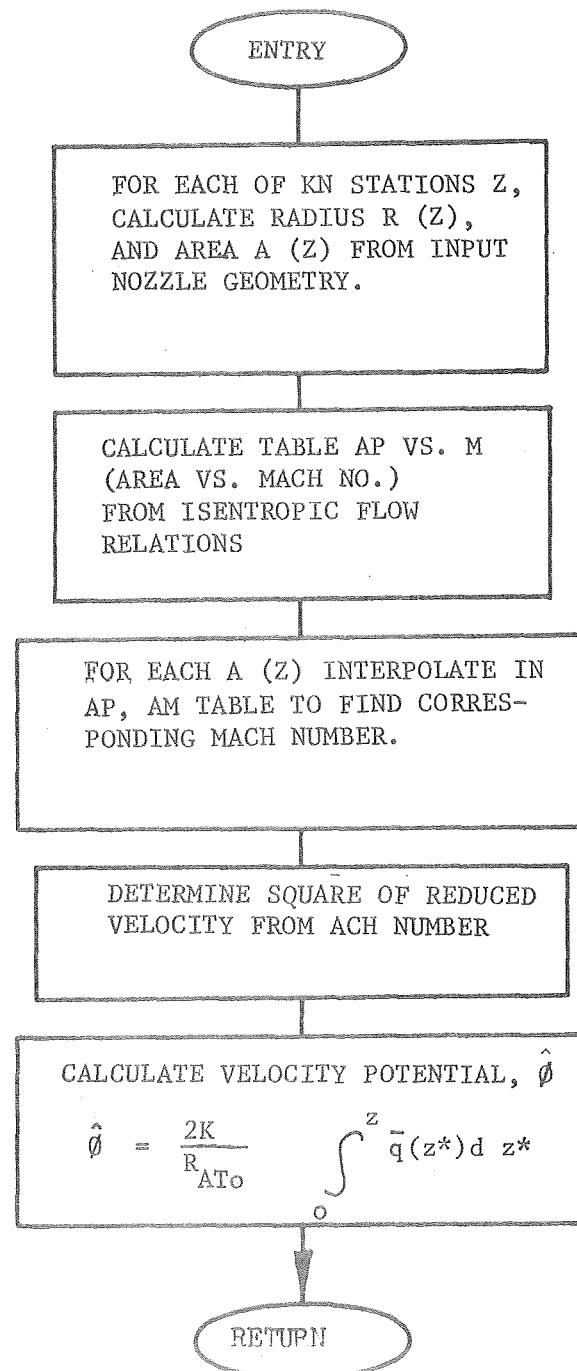
Report 20672-P2D



II, B, Flow Charts (cont.)

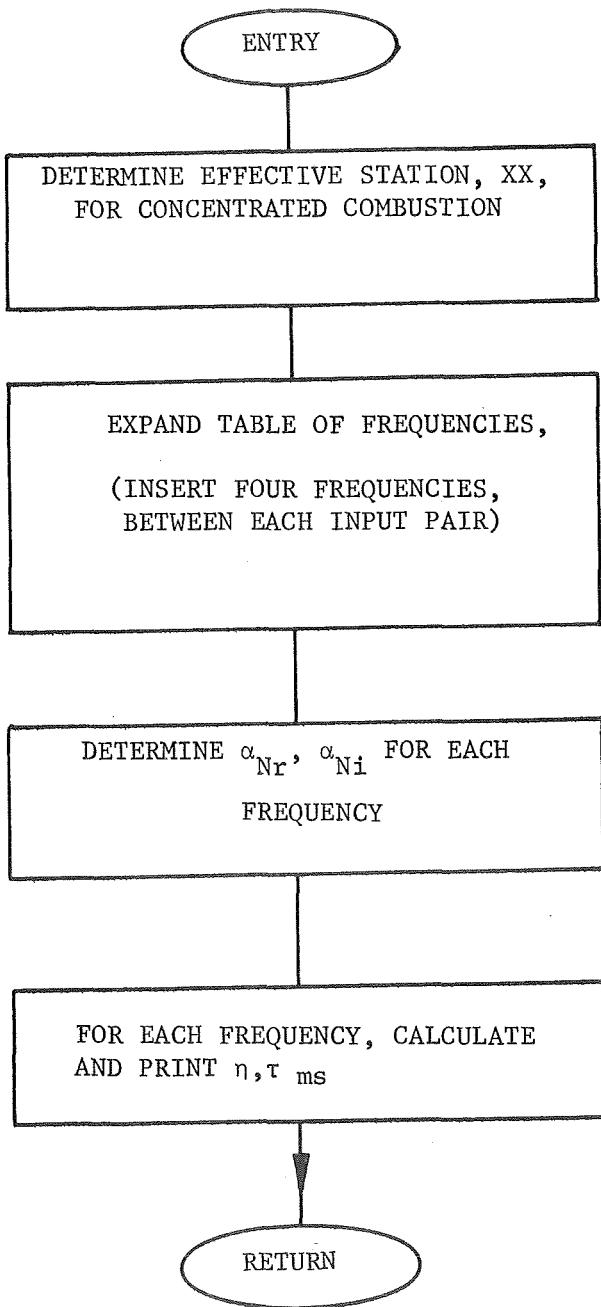
Report 20672-P2D

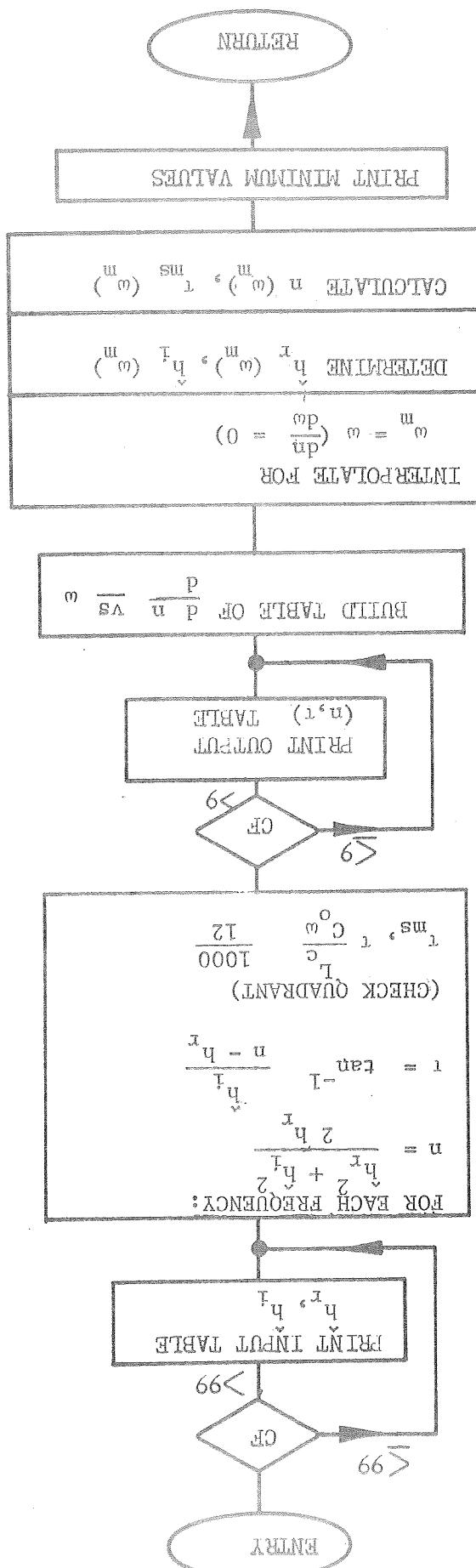
ENTRY = TBLCAL



ENTRY = LØNGI

Report 20672-P2D



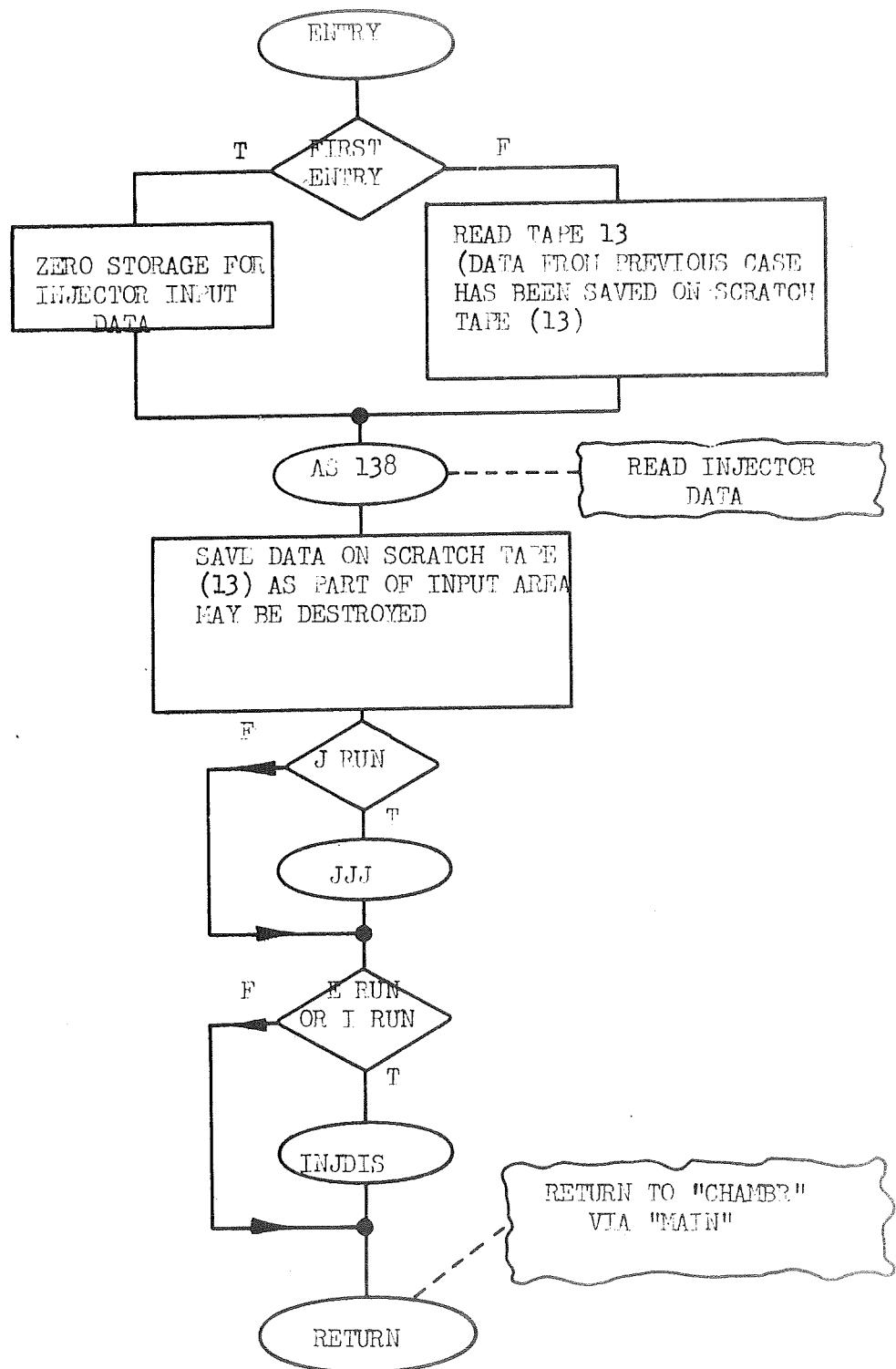


ENTRY = PPF

Report 20672-P2D

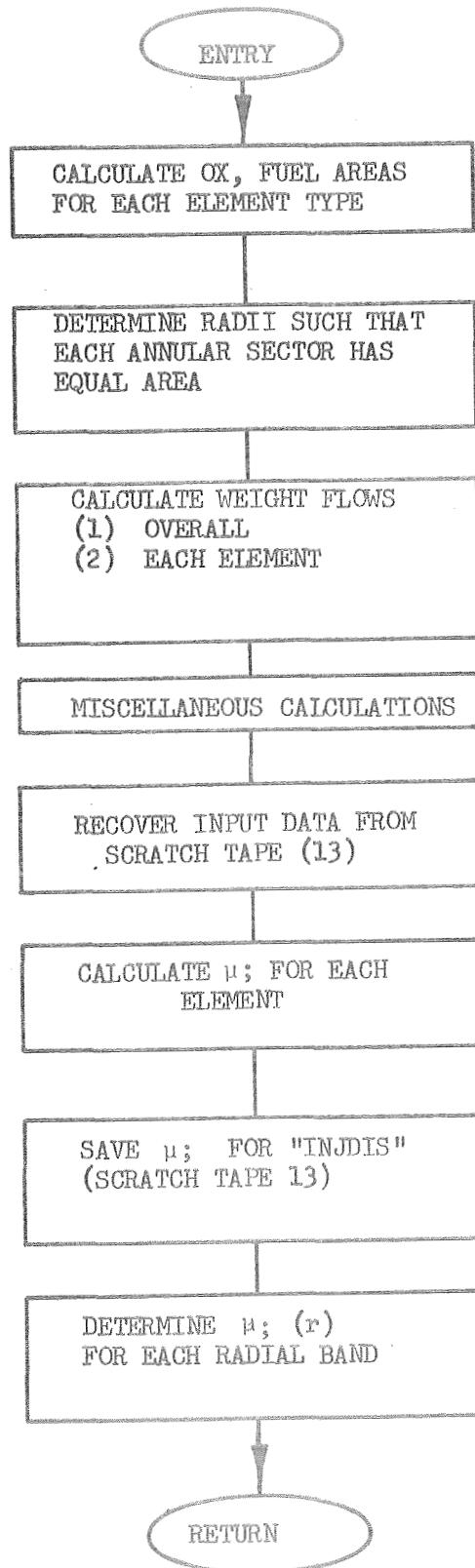
II, B, Flow Charts (cont.)

ENTRY = INJCTR

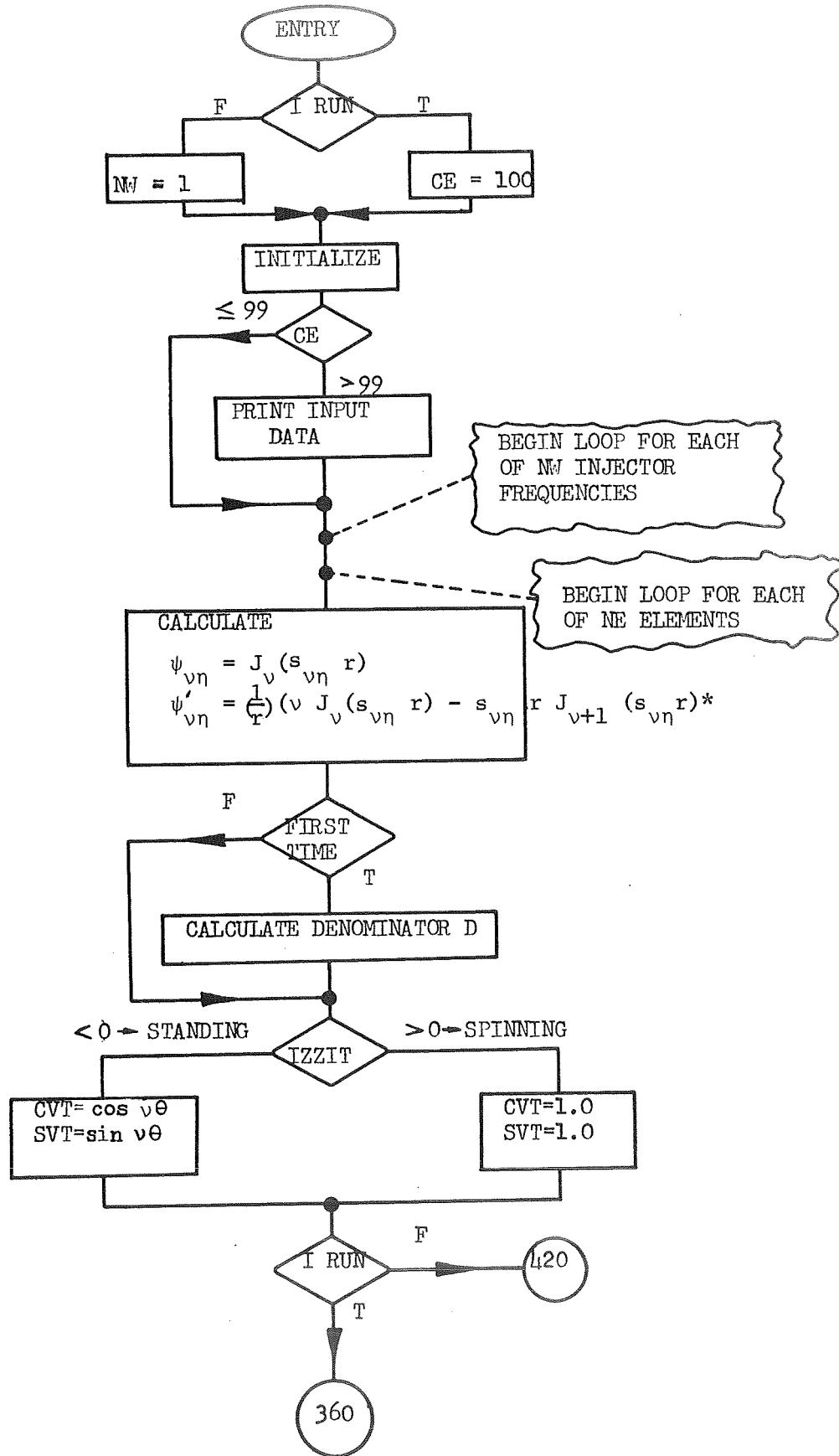


II, B, Flow Charts (cont.)

ENTRY = JJJ Report 20672-P2D

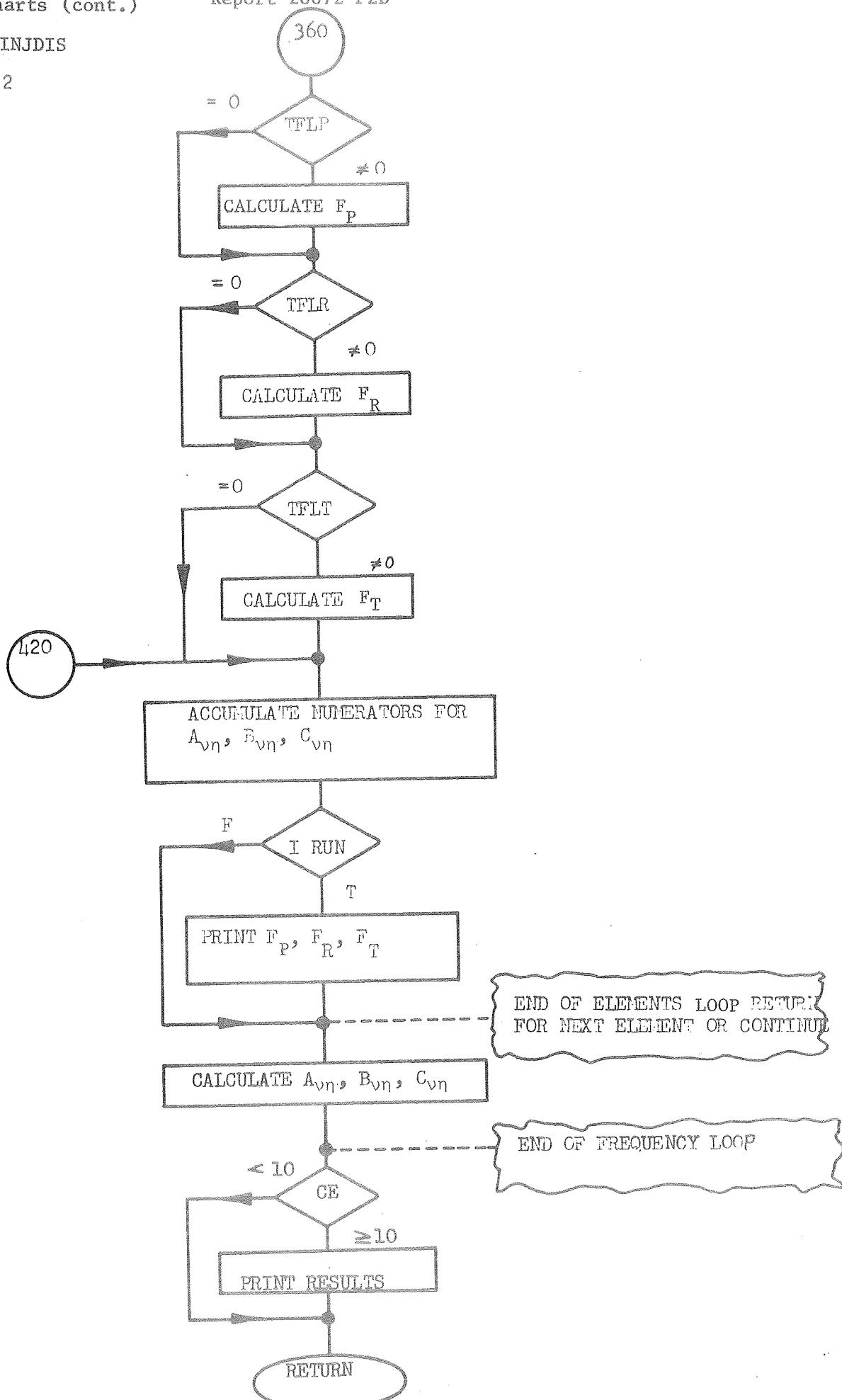


ENTRY = INJDIS



ENTRY = INJDIS

2 of 2



PROGRAM SUBROUTINES

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	BESJ(X,N,BJ,D,IER)	Calculates Function	212
	BESSEL(J,Y,V,X,K)	Calculates Function	214
	BESY(X,N,BY,IER)	Calculates Function	215

```
000001      COMMON /PROLOG/ LOGIK(50), SL1, SL2, EORJ
000002      LOGICAL LOGIK, SL1, SL2, EORJ
000003      C   10 CALL  CHAMPR
000004      C
000005      C   RETURNS FROM MAJOR PROGRAM IF AND ONLY IF AN INJECTOR PROGRAM
000006      C   IS TO BE CALLED... INJCTR DETERMINES WHICH, WRITES SCRATCH
000007      C   TAPE, AND CALLS PROPER ROUTINE.
000008      C
000009      C   CALL  INJCTR
000010      C
000011      C   GO TO 10
000012      C
000013      END
```

@ EIT SUBU1,1,690702, 33250

```
000001      BLOCK DATA
000002      C      COMMON /PROLOG/ LOGIK(SU), SL1, SL2, EOR
000003      C      LOGICAL LOGIK, SL1, SL2, EOR
000004      C      DATA SL1, SL2 / .FALSE., .FALSE. /
000005      C      END
000006
000007
```

```
BL0K 30
BL0K 40
BL0K 50
BL0K 60
BL0K 70
BL0K 80
BL0K 90
```

Report 20672-P2D

```
@ E_LT SUB002,1,690702, 33250  
000001  
000002  
000003  
000004  
000005  
000006  
      SUBROUTINE OUTASA(IZ,K)  
      DIMENSION A(12)  
      WRITE(6,10)(A(I),I=1,K)  
      10 FORMAT(1X,12A6)  
      RETURN  
      END  
      OUT    10  
      OUT    20  
      OUT    30  
      OUT    40  
      OUT    50  
      OUT    60
```

Report 20672-P2D

@ ELT SU3U3.1,690702, 33251

```
000001  
000002  
000003  
000004  
000005  
000006  
  
SUBROUTINE INASSR(A)  
DIMENSION A(12)  
READ(5,10)A  
10 FORMAT(12A6)  
RETURN  
END
```

```
1.0  
2.0  
3.0  
4.0  
5.0  
6.0  
  
IN  
IN  
IN  
IN  
IN  
IN
```

```

      SUBROUTINE INT(X,Y,X1,Y1,Y0)
      DIMENSION X(9),Y(9),XC(4),YC(4)
      EQUIVALENCE (XC(1),X1),(XC(2),X2),(XC(3),X3),(XC(4),X4),
     1,(YC(2),Y2),(YC(3),Y3),(YC(4),Y4)
      NA=1
      J=2
      B=X1
      IF(X(J).NE.0.,UR,Y(J).NE.0.) GO TO 90,NA
      IF(J.GT.2) GO TO 70
      YE=0.
      GO TO 180
      70   NB=1
      NB=J-1
      80   X1=X(J)
      X2=X(J-1)
      X3=X(J-2)
      Y1=Y(J)
      Y2=Y(J-1)
      Y3=Y(J-2)
      GO TO (150,170),NB
      90   IF(X(J)-B)>120,100,100
      100  IF(X(J).LE.2) GO TO 130
      110  NA=2
      120  J=J+1
      130  GO TO 20
      DO 140 J=1,3
      XC(J)=X(J)
      140  YC(J)=Y(J)
      150  D=X2-X1
      A1=B-X1
      A2=B-X2
      YE=A1*A2/2.0/D*( (Y3-Y2)/(X3-X2)-(Y2-Y1)/D)-A2*D*(Y1+A1/D)*Y2
      GO TO 180
      160  NB=2
      GO TO 80
      170  X4=X(J-5)
      Y4=Y(J-3)
      D=X3-X2
      A1=B-X2
      A2=B-X3
      X1.2=(Y2-Y1)/(X2-X1)
      XM2.3=(Y3-Y2)/D
      XM3.4=(Y4-Y3)/(X4-X3)
      YE=A1*A2**2/2.0/D**2*(XM1.2-XM2.3)+A2*A1**2/2.0/D**2*(XM3.4-XM2.3)-A2*D*(Y1+A1/D)*Y2
      180  Y0=YE
      RETURN
      END
      000046
      000047
      000048

```

```

@ ELT SUB05,1,690717, 33453

000001      SUBROUTINE INT4D(X,Y,X1,Y0,DY)           INT4D 10
000002      DIMENSION X(9),Y(9),XC(4),YC(4)         INT4D 20
000003      EQUIVALENCE (XC(1),X1),(XC(2),X2),(XC(3),X3),(XC(4),X4),(YC(1),Y1) INT4D 30
000004      ,(YC(2),Y2),(YC(3),Y3),(YC(4),Y4)        INT4D 40
000005      10  NA=1                               INT4D 60
000006      J=2                                INT4D 70
000007      B=XI
000008      20  IF(X(J).NE.0..OR.Y(J).NE.0.) GO TO (90,160),NA
000009      IF(J.GT.2) GO TO 70
000010      YF=0.
000011      GO TO 180
000012      70  NB=1                               *NEW
000013      *   *-1
000014      J=J-1
000015      80  X1=X(J)                          INT4D150
000016      X2=X(J-1)                          INT4D160
000017      X3=X(J-2)                          INT4D170
000018      Y1=Y(J)                           INT4D180
000019      Y2=Y(J-1)                          INT4D190
000020      Y3=Y(J-2)                          INT4D200
000021      GO TO (150,170),NB                  INT4D210
000022      90  IF(X(J)-B)120,100,100          INT4D230
000023      100 IF(J.LE.2) GO TO 130
000024      110 NA=2
000025      120 J=J+1                          INT4D260
000026      GO TO 20
000027      130 DO 140 J=1,3                 INT4D270
000028      XC(J)=X(J)                          INT4D280
000029      140 YC(J)=Y(J)                      INT4D290
000030      150 D=X2-X1                         INT4D300
000031      A1=B-X1                          INT4D310
000032      A2=B-X2                          INT4D320
000033      XM23=(Y3-Y2)/(X3-X2)            INT4D330
000034      XM12=(Y2-Y1)/(X2-X1)            INT4D340
000035      XM2B=(XM23-XM12)/2.0/D          INT4D350
000036      Y0=A1*A2*XM2B-A2*Y1/D+A1*Y2/D    INT4D360
000037      DY=XM2B*(A1+A2)+XM12             INT4D370
000038      GO TO 180
000039      160 NB=2
000040      GO TO 80
000041      170 X4=X(J-3)                      INT4D410
000042      Y4=Y(J-3)                          INT4D420
000043      D=X3-X2                          INT4D430
000044      A1=B-X2                          INT4D440
000045      A2=B-X3                          INT4D450
000046      XM12=(Y2-Y1)/(X2-X1)            INT4D460
000047      XM23=(Y3-Y2)/D                  INT4D470
000048      XM34=(Y4-Y3)/(X4-X3)            INT4D480
000049      AM2=A2*(XM12-XM23)            INT4D490
000050      AM1=A1*(XM34-XM23)            INT4D500
000051      Y0=(A1*A2/2.0/D*(AM2+AM1)-A2*Y2+A1*Y3)/D  INT4D510
000052      DY=(AM2*(2.0*A1+A2)+AM1*(2.0*A2+A1))/2.0/D**2+XM23  INT4D520
000053      180 RETURN
000054      END

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@ E_L1 SURU5,1,690807, 35835

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0000001      SUBROUTINE PAGE(LINES)
C          HEAD MOVED TO /PROLOG/ AND PAGE MODIFIED TO PRINT HEAD 25JUL 67
C          COMMON /PROLOG/ LOGIK(38), HEAD(12), SL1, SL2, EORJ
C          DIMENSION TODAY(2)
C          DATA KPG / 0 /
C
C          IF(LINES=60)20,16,10
10        L=2
          GO TO 60
20        K=LINES
          IF(K=60)30,30,50
30        L=K
40        RETURN
C
0000016      50        L=LINES+?
0000017      60        IF (KPG.EQ.0) GO TO 90
0000018      70        KPG = KPG + 1
0000019      80        FORMAT (1H1 3X 6HDATE 2A6, 12X 12A6, 11X 5HPAGE 15 )
0000020      90        WRITE (6,80) TODAY, HEAD, KPG
0000021      GO TO 40
0000022      TODAY(1)=6H
0000023      TODAY(2)=6H
0000024      CALL DATE (12,TODAY)
0000025      GO TO 70
0000026      END
0000027

```

PAGE 10
PAGE 20
PAGE 30
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PAGE 60
PAGE 70
PAGE 80
PAGE 90
PAGE 100
PAGE 110
PAGE 120
PAGE 130
PAGE 140
PAGE 150
PAGE 160
PAGE 170 *NEW
PAGE 190**-1
PAGE 200
PAGE 210
PAGE 220 *NEW
PAGE 230 *NEW

@ EL1 SUB07,1,691029; 50054

```

10 SUBROUTINE CHAMR
C   20 SEP 6 / MODIFIED FOR TABULAR INJECTOR COEFFICIENTS
C
C   LOGICAL LOGIK, ARUN, bRUN, iRUN, DRUN, ERUN, FRUN, GRUN, HRUN, IRUN,
C   LOGICAL SL1, SL2, EORJ
C
C   REAL MACH
C
C   COMMON / /
C   COMMON /PROLOG/ LOGIK(38), HEAD(12), SL1, SL2, EORJ
C   COMMON ABCDF/ DINP, STOW
C   COMMON EXTRA(100),
C   DIMENSION F1NP(4300),A(1),B(1),C(1),D(1)
C   DIMENSION X(133),Y(133),O(134),STOW(222),STODAT(4607)
C   DIMENSION ZZ(205)
C   DIMENSION S(1),DISTL(20),DISTM(20)
C   DIMENSION AMIT(90)
C   EQUIVALENCE ( EXTRA, I1NP, STODAT )
C
C   EQUIVALENCE
C   1 (LOGIK(1) , ARUN), (LOGIK(2) , BRUN), (LOGIK(3) , CRUN),
C   2 (LOGIK(4) , DRUN), (LOGIK(5) , ERUN), (LOGIK(6) , FRUN),
C   3 (LOGIK(7) , GRUN), (LOGIK(8) , HRUN), (LOGIK(9) , IRUN),
C   4 (LOGIK(10) , JRUN)
C
C   EQUIVALENCE (EXTRA(1),CA), (EXTRA(2),CB), (EXTRA(3),CC), (EXTRA(4),
C   1CD), (EXTRA(5),CE), (EXTRA(6),CF), (EXTRA(7),CG), (EXTRA(8),CH)
C
C   EQUIVALENCE (EXTRA(9),CI)
C   EQUIVALENCE (EINP(1),A), (DINP(3001),B), (DINP(3401),D),
C   1(DINP(3501),G), (DINP(3801),C), (EXTRA(21),NC), (B(4),UE)
C
C   EQUIVALENCE (DINP(601),AMIT), (DINP(2813),Q), (DINP(3501),X),
C   1 (DINP(365),Y)
C
C   EQUIVALENCE
C   1 (STOW(1),ZZ), (STOW(213),YH)
C   2 , (STOW(214),J), (STOW(215),NE), (STOW(216),YL), (STOW(217),KL)
C   3 , (STOW(218),N), (STOW(219),KER), (STOW(220),XH)
C   4 , (STOW(221),KQUAD), (STOW(222),XL)
C   5 , (EXTRA(51),DISIL), (EXTRA(71),DISTM)
C   6 , (EXTRA(10),CJ), (EXTRA(21),SNH), (EXTRA(12), MACH )
C   7 , (DINP(107),U1BAR)
C
C   *****
C   000031
C   000032
C   000033
C   000034
C   000035
C   000036
C   000037
C   000038
C   000039
C   000040
C   000041
C   000042
C   000043
C   000044
C   000045
C   000046
C   000047
C   000048
C   000049
C   000050
C   000051
C   000052
C   000053
C   000054
C   000055
C
C   10 FORMAT(1H0,6H
C   1 J // 3X,(10F6.0))
C   20 FORMAT(//,9X,10H***** THE FOLLOWING MAIN CONTROL DATA WILL BE USED IN THIS CASE *****
C   1ROL DATA ***** 245X.33HRATIO OF SPECIFIC HEAT (GAMMA) = ,F7.4,/,45X.224HDESIRED NACHAM 460
C   5CH NUMBER = ,E1?5.26H (=0 IF BEING CALCULATED) /,45X.17HCHAM 470
C   5MBER RADIUS = ,F7.3, 9H (INCHES),/,45X.17HCHAM LENGTH = ,F7.3CHAM 480
C   6. CH (INCHES),/,45X.17HSPEED OF SOUND = ,F10.3, 9H (FT/SEC),/,CHAM 490
C   745X.27HCHAM MODE DESCRIPTION = ,F8.5, 28H (=0 FOR LONGITUDINALCHAM 500
C   6 MODES),/,)
C   30 FORMAT(//,33X,4FH***** NACH DISTRIBUTION IN CHAMBER AS A FUNCTION OF CHAM 510
C   1 ,/,)
C   40 FORMAT(5FF20.5,/)
C   50 FORMAT(30X, 64H***** CHAMBER FREQUENCIES (WC) *****
C

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000056      1 LENGTH *****,//,11X,7HCHAMBER,15X,4HNACH,14X,7HCHAMBER,15X,4HMACHCHAM 560
000057      2,14X,7HCHAMBER,15X,4HMACH,/,12X,6HLENGTH,11X,12HDISTRIBUTION,11X, CHAM 570
000058      36HLENGTH,11X,12HDISTRIBUTION,11X,6HLENGTH,11X,12HDISTRIBUTION,/,) CHAM 580
000059      60 FORMAT(6(10X,F10.5))                                         CHAM 590
000060      C*****                                         CHAM 600
000061      C*****                                         CHAM 610
000062      C                                         CHAM 620
000063      IF ( SL2 )          GO TO 170                                         CHAM 630
000064      C                                         CHAM 640
000065      SL2 = .TRUE.                                         CHAM 650
000066      DO 70 I = 1, 4300                                         CHAM 660
000067      70   DINP (I) = 0.0                                         CHAM 670
000068      GO TO 110                                         CHAM 680
000069      C                                         CHAM 690
000070      C*****                                         CHAM 700
000071      C                                         CHAM 710
000072      80 WRITE (6,100)    NE                                         CHAM 720
000073      90 CALL EXIT                                         CHAM 730
000074      100 FORMAT (1H010X17HINPUT ERROR, NE = 13, 19H, HENCE TERMINATION ) CHAM 740
000075      C                                         CHAM 750
000076      C*****                                         CHAM 760
000077      C*****                                         CHAM 770
000078      C                                         CHAM 780
000079      110 KER = 0                                         CHAM 790
000080      CALL DVCHK (KCHK)                                         CHAM 800
000081      C                                         CHAM 810
000082      DO 120 I = 1, 10                                         CHAM 820
000083      120   DINP(I) = 0.0                                         CHAM 830
000084      CALL AS138 ( DINP(1), HEAD(1), NE )                                         CHAM 840
000085      IF ( NE .NE. 1 )  GO TO 80                                         CHAM 850
000086      ARUN = CA .NE. 0.0                                         CHAM 860
000087      BRUN = CB .NE. 0.0                                         CHAM 870
000088      CRUN = CC .NE. 0.0                                         CHAM 880
000089      DRUN = CD .NE. 0.0                                         CHAM 890
000090      ERUN = CE .NE. 0.0                                         CHAM 900
000091      FRUN = CF .NE. 0.0                                         CHAM 910
000092      IRUN = CI .NE. 0.0                                         CHAM 920
000093      JRUN = CJ .NE. 0.0                                         CHAM 930
000094      OGRUN =     DINP(22) .LE. 0.0                                         CHAM 940
000095      1      .AND. ( ARUN .OR. BRUN .OR. CRUN .OR. IRUN ) CHAM 950
000096      C                                         CHAM 960
000097      C   PRINT NEW MAIN CONTROL DATA                                         CHAM 970
000098      C*****                                         CHAM 980
000099      CALL PAGE ( 60 )                                         CHAM 990
000100      WRITE (6,10) ( DINP(I), I=1,10)                                         CHAM1000
000101      WRITE (6,20) DINP(11). MACH, DINP(14), DINP(15), DINP(16), SNH CHAM1010
000102      C*****                                         CHAM1020
000103      C   ARE FREQUENCIES TO BE CALCULATED... IF SO, CALCULATE AND PRINT. CHAM1030
000104      C*****                                         CHAM1040
000105      IF ( .NOT. GRUN )          GO TO 130                                         CHAM1050
000106      CALL GENMEG ( WC(1) )                                         CHAM1060
000107      IF ( BRUN .OR. ARUN )          CRUN = .TRUE.                                         CHAM1070
000108      IF ( CRUN )          CC = CC + 11.0                                         CHAM1080
000109      130 JOMEGA=ABS(EXTRA(22))+22.0001                                         CHAM1090
000110      WRITE (6,30)                                         CHAM1100
000111      WRITE (6,40)(EXTRA(I),I=23,JOMEGA)                                         CHAM1110
000112      WRITE (6,50)                                         CHAM1120
000113      WRITE (6,60)( DISTL(I), DISTM(I), DISTL(I+7), DISTM(I+7)CHAM1130
000114      1, DISTL(I+14), DISTM(I+14), I=1,6 ), DISTL(7), DISTM(7), CHAM1140

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Report 20672-P2D

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000174 ZZ(3)=EXTRA(16)
000175 DINP(3805)=EXTRA(14)
000176 DINP(3803)=NMHAF
000177 IF ( DINP(3809) .EQ. 0.0 )   D1NP(3809) = 131.0
000178 K = 0
000179 RATIO=DINP(3804)
000180 RACO=DINP(3805)
000181 RCCO=DINP(3806)
000182 RCTO=DINP(3807)
000183 RATIO=DINP(91)
000184 RCTI=DINP(92)
000185 RACI=DINP(93)
000186 RCCTI=DINP(94)
000187 IF(RCTI.EQ.0.) RCTI=1.
000188 GRAD=RATI*SORT(2./1.+EXTRA(11))*(RATO/RCTO-RATI)/RCTI/(RATO*
000189 1*RATO-RATI*RATI)
000190 ZAVE=SORT((1.+EXTRA(11))/2.)*RATO/GRAD
000191 ZZ(4)=ZAVE
000192 IF(EXTRA(21))270,260,270
000193 SN0Z = 0.0
000194 C *****
C USING HALF OF CHAMBER FREQUENCIES, CALCULATE NOZZLE FREQUENCIES
C FOR USE IN PROG C.
000195 C *****
000196 C *****
000197 C *****
000198 RORL = EXTRA(15)
000199 GO TO 280
000200 RORL = EXTRA(14)
000201 SN0Z = SNH(GRA)
000202 DO 290 I=1,NMHAF
000203 KN=(2*I)+1
000204 NN=4210+K
000205 DINP(NN)= ZAVE*WC(KN)/RORL
000206 DINP(NN+1)= SNOZ
000207 DINP(NN+2)= MACH
000208 K=K+3
000209 CONTINUE
000210 DINP(NN)=ZAVE*(WC(NOMEGL+2)/EXTRA(14))
000211 300 CALL CCC(C(1),Z7(1),WC(1),CC,KER)
000212 SET UP NOZZ AUM FOR A,B
000213 IF (KER) 31,330,310
000214 310 WRITE (6,320)
000215 320 FORMAT (1H0 3X39H ERROR PROGRAM C, ALL CASES TERMINATED )
000216 CALL CORE(C(1),420,CC)
000217 GO TO 90
000218 330 IF ( .NOT. ARUN )   GO TO 360
000219 C *****
000220 C MOVE OUTPUT FROM C INTO INPUT BLICK TU A
000221 C *****
000222 340 NP = C(3)
000223 IWO = 0
000224 350 I = 1, NP
000225 IWO = 1WO + 2
000226 AMIT(I) = ZZ(IWO)
000227 AMIT(I+30) = ZZ(IWO+1)
000228 AMIT(I+60) = ZZ(IWO+10)
000229 CONTINUE
000230 AMIT(NP+1) = 0.0
000231 AMIT(NP+31) = 0.0
000232 C *****
C ***** END TABLES

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Report 20672-P2D

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000233 AMIT(NP+61) = 0.0
000234 IF ( MACH .LE. 0.0 )  M1BAR = ZZ(205)
000235 GO TO 410
C   CHAM2220
000236   CHAM2230
000237   C   360 IF ( .NOT. BRUN .AND. SNH .EQ. 0.0 )  GO TO 340
000238   C   ***** MOVE OUTPUT FROM PROG C INTO INPUT BLOCK FOR PROG B.
000239   C   ***** DO 380 I=18,200
000240   DO 380 I=18,200
000241   CHAM2260
000242   B(1)=ZZ(I)
000243   B(4)=ZZ(205)
000244   CHAM2270
C   390 CONTINUE
000245   HRUN = (CH.GT. 0.0) .OR. BRUN .AND. (UE.GE.C.1) .AND.(CH.EQ.0.0)
000246   C   NOZZLE ADMITTANCE IS INPUT TO PROGS A, B.
000247   C   ***** CHAM2280
000248   C   ***** CHAM2290
000249   C   ***** CHAM2300
000250   C   ***** CHAM2310
000251   C   ***** CHAM2320
000252   C   ***** CHAM2330
000253   C   ***** CHAM2340
000254   C   ***** CHAM2350
000255   C   ***** CHAM2360
000256   C   ***** CHAM2370
000257   C   ***** CHAM2380
000258   C   ***** CHAM2390
000259   C   ***** CHAM2400
000260   C   ***** CHAM2410
000261   C   ***** CHAM2420
000262   C   ***** CHAM2430
000263   C   ***** CHAM2440
000264   C   ***** CHAM2450
000265   C   ***** CHAM2460
000266   C   ***** CHAM2470
000267   C   ***** CHAM2480
000268   C   ***** CHAM2490
000269   C   ***** CHAM2500
000270   C   ***** CHAM2510
000271   C   ***** CHAM2520
000272   C   ***** CHAM2530
000273   C   ***** CHAM2540
000274   C   ***** CHAM2550
000275   C   ***** CHAM2560
000276   C   ***** CHAM2570
000277   C   ***** CHAM2580
000278   C   ***** CHAM2590
000279   C   ***** CHAM2600
000280   C   ***** CHAM2610
000281   C   ***** CHAM2620
000282   C   ***** CHAM2630
000283   C   ***** CHAM2640
000284   C   ***** CHAM2650
000285   C   ***** CHAM2660
000286   C   ***** CHAM2670
000287   C   ***** CHAM2680
000288   C   ***** CHAM2690
000289   C   ***** CHAM2700
000290   C   ***** CHAM2710
000291   C   ***** CHAM2720
000292   C   ***** CHAM2730
000293   C   ***** CHAM2740
000294   C   ***** CHAM2750
000295   C   ***** CHAM2760
000296   C   ***** CHAM2770
000297   C   ***** CHAM2780
000298   C   ***** CHAM2790
000299   C   ***** CHAM2800
000290   CALL CORE(R(1),Z0,CB)
000291

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000292          GO TO 110
000293 C***** *****
000294      530 IF ( .NOT. DRUN )      GO TO 620
000295      540 DO 550 I=1,6
000296      X(I)=D(I)
000297      550 CONTINUE
000298      560 X(5)=EXTRA(11)
000299      DO 570 I = 9, 100
000300      570      X(I) = D(I)
000301      CALL DDD ( X(1), Y(1), CD, KER, ERR )
000302      IF ( ERR )           110,580,580
000303      580 IF ( KER )           610,590,610
000304      590 WRITE (6,600)
000305      600 FORMAT (1H0,40X,18H ERROR PROGRAM D )
000306      CALL CORE(X(1),100,CD)
000307      GO TO 110
000308      610 CONTINUE
000309      620 IF ( .NOT. FRUN )      GO TO 670
000310 C***** *****
000311 C      SET UP DATA FOR PROG F   (N, TAU )
000312 C***** *****
000313      630 Y(1)=EXTRA(14)
000314      Q(101) = EXTRA(15)/Y(1) * 12.0/6.2831853
000315      640 Y(2)=EXTRA(16)
000316      CALL FFF ( Y(1), Q(1), CF, KER, WC(1) )
000317      IF ( KER )           670,650,670
000318      650 WRITE (6,660)
000319      660 FORMAT (1H0,40X,18H ERROR PROGRAM F )
000320      CALL CORE(Y(1),100,CF)
000321      670 GO TO 110
000322 C
000323 C
000324 C***** *****
000325 C***** *****
000326 C***** *****
000327      END

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@ ELT SUB08,1,690702, 33259

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000001      SUBROUTINE GENMEG(W)                               WGEN 10
000002      C                                               WGEN 20
000003      C*****DIMENSION W(1)                                WGEN 30
000004      C                                               WGEN 40
000005      C                                               WGEN 50
000006      C   LONGITUDINAL WILL HAVE NEG SNH WHICH WILL BE SET TO ZERO BEFOR RETURWGEN 60
000007      C   IF SNH 0 LONGITIDUNIAL AND GENERATE + OR - 10 PERCENT OF PIE    WGEN 70
000008      C*****IF(W(1))40.50,10                                WGEN 80
000009      C*****W(3)=SNH-DELMEG                                WGEN 90
000010      C*****DO 30 I=4,12                                WGEN 100
000011      C   FOR TRANSVERSE GENERATE 10 VALUES AROUND SNH 9 PERCENT BELOW AND   WGEN 110
000012      C   11 PERCENT ABOVE                                WGEN 120
000013      C*****10 SNH=W(1)                                WGEN 130
000014      20 DELMEG=.1*SNH                                WGEN 140
000015      W(3)=SNH-DELMEG                                WGEN 150
000016      DELMEG=DELMEG/5.0                                WGEN 160
000017      W(3)=W(3)+DELMEG                                WGEN 170
000018      W(3)=W(3)+DELMEG                                WGEN 180
000019      DO 30 I=4,12                                WGEN 190
000020      W(I)=W(I-1)+DELMEG                                WGEN 200
000021      30 CONTINUE                                WGEN 210
000022      C*****C NEGITIVE 10 INDICATES TO PROGRAM THAT FREQUENCES ARE GENERATED INTERNWGEN 220
000023      C*****C IF NEG GENERATE + OR - 10 PERCENT OF POSITIVE INITIAL GUESS    WGEN 230
000024      C*****C IF NEG GENERATE + OR - 10 PERCENT OF POSITIVE INITIAL GUESS    WGEN 240
000025      W(2)=-10.0                                WGEN 250
000026      RETURN                                WGEN 260
000027      C*****C IF NEG GENERATE + OR - 10 PERCENT OF POSITIVE INITIAL GUESS    WGEN 270
000028      C   IF NEG GENERATE + OR - 10 PERCENT OF POSITIVE INITIAL GUESS    WGEN 280
000029      C*****C IF NEG GENERATE + OR - 10 PERCENT OF POSITIVE INITIAL GUESS    WGEN 290
000030      40 SNH=-W(1)                                WGEN 300
000031      W(1)=0.0                                WGEN 310
000032      GO TO 20                                WGEN 320
000033      50 SNH=3.141592                                WGEN 330
000034      GO TO 20                                WGEN 340
000035      END                                WGEN 350

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ELT SUBOG, 1, 690708, 48726

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C SUBROUTINE TRANS ( BIN, XOUT, CB, KER ) 20
C   * CALCULATES COMBUSTION PARAMETERS HR, HI  HYMN 30
C     PROGRAM BY LW VERNON FROM 11MAY67 ANALYSIS OF AJ SMITH, JR  HYMN 40
C     INCORPORATES CORRECTIONS TO ANALYSIS THRU 1 JUN 67  HYMN 50
C     BOOLE INTEGRATION AS OF 12 JUNE 67  HYMN 70
C     RHO, RHOL CONVENTIONS CORRECTED 22JUN 67  HYMN 80
C     20 SEP 67 MODIFIED FOR TABULAR INJECTOR COEFFICIENTS  HYMN 90
C   ****
C   C
C   REAL I4R, IAI, IBR, IBI  HYMN 100
C   LOGICAL LOGIK, HRUN, CKOUT, SIMPL, KNOT, LIMIT, TABLR  HYMN 110
C
C   COMMON /PROLOG/  LOGIK(38), HEAD(12), SL1, SL2, EORJ  HYMN 120
C   COMMON /ABCDF/  DIN(4300)  HYMN 130
C   1  SPACE(222), WIT(1), AVN(17), BVN(17), CVN(17), CVNI(17)  HYMN 140
C   DIMENSION B(240), GS(6,102), SLAM(12,3), ZAP(12)  HYMN 150
C   1  ZZ(102), STAB(102), GL(102), DZ(102)  HYMN 160
C   2  U(102), CTAB(102), SLAM(12)  HYMN 170
C   3  DU(102), D2U(102), ZAP(12)  HYMN 180
C   4  UL(102), DUL(102), G(12)  HYMN 190
C   5  RHO(102), DRHO(102), OLD(12)  HYMN 200
C   6  RHOL(102), DROL(102), ZING(6)  HYMN 210
C   7  QBAR(102), DQ(102), SIMP(6)  HYMN 220
C   8  ZIP3(102), V1(102), ERRZ(6)  HYMN 230
C   9  ZIP5(102), V2(102), ZF(6)  HYMN 240
C
C   DIMENSION THR(30), TH1(30), THTR(30), THTI(30)  HYMN 250
C   1  THR(30), AL(6), XOUT(100), WC(28), EIT(30), CIT(30)  HYMN 260
C   2  BIN(240), ERT(30), EIT(30), CIT(30)  HYMN 270
C   3  WET(30), CRT(30), CIT(30)  HYMN 280
C   4  ZDIST(20), DISTM(20)  HYMN 290
C
C   EQUIVALENCE
C   1  ( HRUN, LOGIK(8)), ( CKOUT, LOGIK(13)), ( SIMPL, LOGIK(14)),  HYMN 300
C   2  ( KNOT, LOGIK(15)), ( LIMIT, LOGIK(16)), ( TABLR, LOGIK(17))  HYMN 310
C
C   EQUIVALENCE
C   1  ( B(1), SNH ), ( B(10), ZINC ), ( DIN(14), RCH ),  HYMN 320
C   2  ( B(2), ZE ), ( B(18), XNE ), ( UL(1), ULO ),  HYMN 330
C   3  ( B(3), GAM ), ( B(19), XNW ), ( RHOL(1), RHOLO ),  HYMN 340
C   4  ( B(4), UE ), ( B(170), WC ), ( B(20), WET ),  HYMN 350
C   5  ( B(5), SOUND ), ( B(200), ZDIST ), ( B(50), ERT ),  HYMN 360
C   6  ( B(6), ULM ), ( B(220), DISTM ), ( B(80), EIT ),  HYMN 370
C   7  ( B(7), XK ), ( B(110), CRT ),  HYMN 380
C   8  ( B(8), XCML ), ( B(140), CIT )  HYMN 390
C
C   EQUIVALENCE
C   1  ( DIN(3406), RLON ), ( DIN(3407), TLON )  HYMN 400
C
C   EQUIVALENCE
C   1  ( AIR, AL(1) ), ( A2R, AL(3) ), ( A4R, AL(5) ),  HYMN 510
C   2  ( A1, AL(2) ), ( A2I, AL(4) ), ( A4I, AL(6) ),  HYMN 520
C   3  ( G20R, SLAM(9) ), ( NG20R, SLAM(10) ),  HYMN 530
C   4  ( G20I, SLAM(11) ), ( NG20I, SLAM(12) )  HYMN 540
C
C   ****

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000115      CALL  INT4  ( ZDIST, DISTM, ZC, UENRM )          HYMN1160
000116      SCALE = UE / UENRM                           HYMN1170
000117      SIMPL = IDZ .LE. 0                            HYMN1180
000118      IF ( SIMPL )           GO TO 230              HYMN1190
000119      INT = 2                                         HYMN1200
000120      IDZ = IDZ/4 * 4                                HYMN1210
000121      C      MUST BE POSITIVE MULTIPLE OF FOUR, LESS THAN 101  HYMN1220
000122      GO TO 240                                     HYMN1230
000123      C
000124      230  INT = 1                                  HYMN1240
000125      IDZ = -IDZ/2 * 2                                HYMN1250
000126      C
000127      240  IF ( ( IDZ .EQ. 0 ) .OR. ( IDZ .GT. 100 ) )  IDZ = 80  HYMN1260
000128      C
000129      C      IDZ IS NUMBER OF Z-INCREMENTS.        HYMN1270
000130      C
000131      IDZP = IDZ + 1                                HYMN1280
000132      DZ = ZC / FLOAT(IDZ)                         HYMN1290
000133      C
000134      ZZ(1) = 0.0                                    HYMN1300
000135      U(1) = 1.0E-10                               HYMN1310
000136      DU(1) = 0.0                                   HYMN1320
000137      RHO(1)= 1.0                                 HYMN1330
000138      ULO = ULM/SOUND                            HYMN1340
000139      GF1 = -1.0 / (GAM-1.0)                      HYMN1350
000140      GF2 = (GAM-1.0) / 2.0                        HYMN1360
000141      RHOZE = ( 1.0 + GF2*UE*UE ) **GF1          HYMN1370
000142      RHOLO = RHOZE * UE / ULO                     HYMN1380
000143      QBAR(1) = 0.0                                HYMN1390
000144      ZIP3(1) = 0.0                                HYMN1400
000145      ZIP5(1) = RHOLO                            HYMN1410
000146      C      ABOVE ARE FIRST TABULAR ENTRIES.       HYMN1420
000147      C
000148      Z = 0.0                                       HYMN1430
000149      C
000150      DO 250 IZ = 2, IDZP                         HYMN1440
000151      Z = Z + DZ                                 HYMN1450
000152      CALL  INT4I  ( ZDIST, DISTM, Z, J(IZ), DU(IZ) )  HYMN1460
000153      ZZ(IZ) = Z                                  HYMN1470
000154      U (IZ) = U(IZ)*SCALE                      HYMN1480
000155      DU(IZ) = DU(IZ)*SCALE                     HYMN1490
000156      UL(IZ) = UL(IZ-1) + XK*DZ*( U(IZ-1)-UL(IZ-1) )/UL(IZ-1)  HYMN1500
000157      TEMP = 1.0 + GAM*( U(IZ)-UL(IZ) )*U(IZ)        HYMN1510
000158      RHO(IZ) = ( 1.0 + GF2*U(IZ)*U(IZ) ) **GF1    HYMN1520
000159      RHOL(IZ) = ( RHOZE*UE - RHO(IZ)*U(IZ) ) / UL(IZ)  HYMN1530
000160      0   QBAR(IZ) = ( ( 1.0 - GAM*U(IZ)*U(IZ) )*RHO(IZ)*DU(IZ)  HYMN1540
000161      1   - GAM*U(IZ)*RHOL(IZ)*XK*( U(IZ)-UL(IZ) ) ) / TEMP  HYMN1550
000162      ZIP3(IZ) = DU(IZ) + DU(IZ)                  HYMN1560
000163      ZIP5(IZ) = RHOL(IZ) / RHO(IZ)                HYMN1570
000164      250  CONTINUE                                HYMN1580
000165      ZZ(IDZP) = ZC                                HYMN1590
000166      U (IDZP) = UE                                HYMN1600
000167      DU(IDZP) = 0.0                               HYMN1610
000168      RHO(IDZP) = RHOZE                            HYMN1620
000169      RHOL(IDZP) = 0.0                             HYMN1630
000170      QBAR(IDZP) = 0.0                            HYMN1640
000171      ZIP3(IDZP) = 0.0                           HYMN1650
000172      ZIP5(IDZP) = 0.0                           HYMN1660
000173      C

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000292      CF = COSH(PSI)
000293      SF = SINH(PSI)
C      GO TO 400
000295      CF = COS (PSI)
000296      SF = SIN (PSI)
C      390
000297      CF = QBAR(IZ) * SF
000298      SF = QBAR(IZ) * CF
000299      ZF(1) = QBAR(IZ) * SF
000300      ZF(2) = QBAR(IZ) * CF
000301      ZF(3) = ZIP3(IZ) * SF
000302      ZF(4) = ZIP3(IZ) * CF
000303      ZF(5) = ZIP5(IZ) * SF
000304      ZF(6) = ZIP5(IZ) * CF
C      ZF ARE COMPLETE INTEGRANDS
000305
000306
000307      DO 420 I = 1, 6
000308      ZING(I) = ZING(I) + WT*ZF(I)
000309      CONTINUE
C      420      .    CONTINUE
000310
000311      GO TO (460,440), INT
000312
000313
C      440      INT = 1
000314      DO 450 I = 1, 6
000315      SIMP(I) = ZING(I)*DZ/1.5
000316      SIMP IS SIMPSON INTEGRAL FOR IDZ/2 INCREMENTS
000317
000318      GO TO 310
000319
C      460      DO 470 I = 1, 6
000320      ZING(I) = ZING(I)*DZ/3.0
000321      ZING IS SIMPSON INTEGRAL FOR IDZ INCREMENTS
000322
000323
C      470      GO TO 310
000324      IF ( SIMPL ) GO TO 490
C      *INT = 2
000325      DO 480 I = 1, 6
000326      ERR7(I) = ( ZING(I)-SIMP(I) ) / 15.0
000327      IF ( ABS(ERR7(I))/ZING(I) > .05 ) COUT = TRUE.
000328      COUT = .TRUE.
000329      ZING, SIMP ARE SIMPSON INTEGRALS WITH IDZ, IDZ/2 INCREMENTS
000330
000331      ZING(I) = ZING(I) + ERR7(I)
000332      CORRECTED ZING IS NOW BOOLE INTEGRAL
000333      CONTINUE
C      ABOVE ZING(I) ARE THE REQUIRED INTEGRALS
000334
C      490      IF ( .NOT. CKOUT ) GO TO 500
000335      WRITE (6,100) ZING
000336      IF ( .NOT. SIMPL ) WRITE (6,110) ERR2
000337
000338
C      500      OZ = (MEG * ZE
000339      WKSQ = XK*XK + W*W
000340      T1 = XK*W / WKSQ
000341      T2 = W*W / WKSQ
C      543
000342
000343
000344
000345
000346
000347
000348
000349
000350
C      Y1R = GAM*ZING(2)-ZING(2) + ZING(4) + WT*ZING(6)
C      Y1I = XK*T1*ZING(6)
C      GO TO (530,510,520), IM
C      Y2R = -SNH*ERR/W
C      510

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000351      Y2I = -SNH*EI/W          HYMN3520
000352      ERCON = SNH*ER          HYMN3530
000353      EICON = SNH*EI          HYMN3540
000354      GO TO 550             HYMN3550
000355      C
000356      520      COZE = COSH(OZE)   HYMN3560
000357      SOZE = SINH(OZE)       HYMN3570
000358      GO TO 540             HYMN3580
000359      C
000360      530      COZE = COS(OZE)    HYMN3600
000361      SOZE = -SIN(OZE)      HYMN3610
000362      C
000363      540      ERCON = SNH*ER/OMEG HYMN3620
000364      EICON = SNH*EI/OMEG   HYMN3630
000365      Y2R = -SNH*ER/W*COZE  HYMN3640
000366      Y2I = -SNH*EI/W*COZE - OMEG/W*SOZE HYMN3650
000367      C
000368      550      TEMP = GAM*ZING(1)-ZING(1) + ZING(3) + W*T1*ZING(5) HYMN3660
000369      Y3R = ERCON*XK*T1*ZING(5) + EICON*TEMP   HYMN3670
000370      Y3I = EICON*XK*T1*ZING(5) - ERCON*TEMP   HYMN3680
000371      Y6R = EICON*ZING(1) + ZING(2)           HYMN3690
000372      Y6I = -ERCON*ZING(1)           HYMN3700
000373      C
000374      C
000375      ***** CALCULATION OF FIRST-ORDER SOLUTION... ***** HYMN3710
000376      C
000377      ****  CALCULATION OF FIRST-ORDER SOLUTION...  **** HYMN3720
000378      C
000379      C
000380      C
000381      560      H1R = ( Y1R+Y2R+Y3R )/GAM   HYMN3730
000382      H1I = ( Y1I+Y2I+Y3I )/GAM   HYMN3740
000383      HD = Y6R*Y6R + Y6I*Y6I   HYMN3750
000384      C
000385      HR = ( H1R*Y6R + H1I*Y6I ) / HD   HYMN3760
000386      HI = ( H1I*Y6R - H1R*Y6I ) / HD   HYMN3770
000387      C
000388      THR(IW) = HR               HYMN3780
000389      THI(IW) = HI               HYMN3790
000390      C
000391      IF ( .NOT. HRUN )      GO TO 820  HYMN3800
000392      C
000393      ***** TERMS FROM HIGH-ORDER ANALYSIS ( STILL IN W-LOOP ) ***** HYMN3810
000394      C
000395      **** TERMS FROM HIGH-ORDER ANALYSIS ( STILL IN W-LOOP ) **** HYMN3820
000396      C      INITIALIZE INTEGRALS, INTEGRANDS FOR Z=0.0  HYMN3830
000397      C
000398      DO 570 I = 1, 6            HYMN3840
000399      AL(I) = 0.0              HYMN3850
000400      DO 570 IZ = 1, 10ZP     HYMN3860
000401      570      GS(I,IZ) = 0.0   HYMN3870
000402      DO 580 I = 1, 12         HYMN3880
000403      OLD(I) = 0.0            HYMN3890
000404      ZAP(I) = 0.0            HYMN3900
000405      GL(I,1) = 0.0            HYMN3910
000406      SLAM(I) = 0.0            HYMN3920
000407      OLD(3) = -XK*OMEG2     HYMN3930
000408      IF ( IM.EQ. 1 )      SOZE = -SOZE  HYMN3940
000409      NOD = 1                  HYMN3950

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000410      TEMP = -T1*RHOLO          HYMN4110
000411      GL( 9,1) = TEMP*XK*w*SOZE   HYMN4120
000412      GL(10,1) = TEMP*XK*w*COZE    HYMN4130
000413      GL(11,1) = TEMP*OMEG2*SOZE    HYMN4140
000414      GL(12,1) = TEMP*OMEG2*COZE    HYMN4150
000415      C
000416      IF ( .NOT. TARLR ) GO TO 585    HYMN4160
000417      CALL INT4 ( WIT, AVN, W, ANH )    HYMN4161
000418      CALL INT4 ( WIT, BNW, W, BNH )    HYMN4162
000419      CALL INT4 ( WIT, CVNR, W, CNHR )    HYMN4163
000420      CALL INT4 ( WIT, CVNI, W, CNHI )    HYMN4164
000421      C
000422      BNH = RLON * BNH                HYMN4165
000423      CNHR = TLON * CNHR              HYMN4166
000424      CNHI = TLON * CNHI              HYMN4167
000425      C
000426      585     YE = ANH - CMHI/(W*GAM)    HYMN4170
000427      YF = ( BNH + CNHR ) / ( W*GAM )    HYMN4171
000428      H2R = Y6R*YE - Y6I*YF            HYMN4180
000429      H2I = Y6R*YF + Y6I*YE            HYMN4190
000430      HSSQ = H2R*H2R + H2I*H2I          HYMN4200
000431      HA = ( H1R*H2R + H1I*H2I ) / HSSQ    HYMN4210
000432      HB = ( H1I*H2R - H1R*H2I ) / HSSQ    HYMN4220
000433      C
000434      CALL INT4 ( WET, CRT, W, CR )    HYMN4230
000435      CALL INT4 ( WET, CIT, W, CI )    HYMN4240
000436      C
000437      590     GO TO (590,610,630), IM    HYMN4250
000438      DO 600 IZ = 1, IDZP            HYMN4260
000439      ARG = OMEG*ZZ(IZ)            HYMN4270
000440      STAB(IZ) = SIN (ARG)          HYMN4280
000441      CTAB(IZ) = COS (ARG)          HYMN4290
000442      SIGN = -1.0                  HYMN4300
000443      GO TO 650                  HYMN4310
000444      C
000445      610     DO 620 IZ = 1, IDZP            HYMN4320
000446      STAB(IZ) = ZZ(IZ)            HYMN4330
000447      620     CTAB(IZ) = 1.0              HYMN4340
000448      GL(11,1) = TEMP * ZE          HYMN4350
000449      GL(12,1) = TEMP              HYMN4360
000450      GO TO 650                  HYMN4370
000451      C
000452      630     DO 640 IZ = 1, IDZP            HYMN4380
000453      ARG = OMEG*ZZ(IZ)            HYMN4390
000454      STAB(IZ) = SINH(ARG)          HYMN4400
000455      640     CTAB(IZ) = COSH(ARG)          HYMN4410
000456      SIGN = 1.0                  HYMN4420
000457      C
000458      650     DO 780 IZ = 2, IDZP            HYMN4430
000459      NOD = NOD + 1                HYMN4440
000460      V3 = XK*RHOL(IZ)/RHO(IZ)        HYMN4450
000461      V4 = DU(IZ) + V3                HYMN4460
000462      V5 = QBAR(IZ)*V4 + RHO(IZ)*U(IZ)*DQ(IZ)    HYMN4470
000463      V6 = ( RHOL(IZ)/UL(IZ)*DUL(IZ) - DROL(IZ) ) / RHO(IZ)    HYMN4480
000464      V7 = ( 2.0*(D2U(IZ)-DU(IZ)) + V3 - XK*V6 )    HYMN4490
000465      V8 = XK*ZIP5(IZ) - U(IZ) - 3.0*DU(IZ)          HYMN4500
000466      V9 = V3*( DU(IZ) - DUL(IZ) - UL(IZ)/RHOL(IZ)*DROL(IZ) )    HYMN4510
000467      C
000468      1

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000469          0   V10 = ( GAM*DQ(IZ) - DQ(IZ) + RHO(IZ)*D2U(IZ) + D2U(IZ) ) HYMN4600
000470          1   * U(IZ)/RHO(IZ) HYMN4610
000471          V11 = U(IZ)/RHO(IZ)*DROL(IZ)/RHO(IZ) HYMN4620
000472          V12 = ( GAM*QBAR(IZ) - QBAR(IZ) )*DU(IZ) HYMN4630
000473          V13 = ( V12 + D2U(IZ) )/RHO(IZ) HYMN4640
000474          V16 = QBAR(IZ)/RHO(IZ) HYMN4650
000475          V17 = (GAM-1.0) * ( V16*V16 + U(IZ)/RHO(IZ)*D0(IZ) ) HYMN4660
000476          0   V18 = ((U(IZ)-UL(IZ))*DQ(IZ) + QBAR(IZ)*(DU(IZ)-DUL(IZ))) HYMN4670
000477          1   * RHO(IZ) HYMN4680
000478          V19 = ( UL(IZ)-XK-DUL(IZ) ) / ( UL(IZ)*UL(IZ) ) * RHOL(IZ) HYMN4690
000479          V20 = V19 + DROL(IZ)/UL(IZ) HYMN4700
000480          V21 = V16 - GAM*V16 - DU(IZ) - DU(IZ)/RHO(IZ) HYMN4710
000481          V22 = GAM - 1.0 HYMN4720
000482          V23 = RHO(IZ) + 1.0 HYMN4730
000483          V24 = RHO(IZ) - 1.0 HYMN4740
000484          V25 = V22 * (QBAR(IZ)*DU(IZ) + U(IZ)*DQ(IZ)) HYMN4750
000485          V26 = DU(IZ) * (V22*QBAR(IZ) + (GAM + V23)*DU(IZ)) HYMN4760
000486          V27 = RHO(IZ)*V10/T2 HYMN4770
000487          0   V28 = V22 * (QBAR(IZ)*(QBAR(IZ)/RHO(IZ) + DU(IZ)) HYMN4780
000488          1   + 2.0*U(IZ)*DQ(IZ)) HYMN4790
000489          0   V29 = RHO(IZ) * (D2U(IZ)*U(IZ) - UL(IZ)) HYMN4800
000490          1   + DU(IZ)*(DU(IZ) - DUL(IZ))) HYMN4810
000491          V30 = U(IZ)*D2U(IZ) HYMN4820
000492          HYMN4830
000493          C   THE FUNCTIONS V1 ... V20 ARE INDEPENDENT OF W. HENCE WE COULD HYMN4840
000494          C   TRADE CORE FOR TIME BY TAKING ALL OR SOME OUT OF W-LOOP AS HYMN4850
000495          C   SUBSCRIPTED VARIABLES. LET S SEE FIRST WHAT CORE WE HAVE. HYMN4860
000496          C   HYMN4870
000497          ARG = W * V1(IZ) HYMN4880
000498          CWV = COS(ARG) HYMN4890
000499          SWV = SIN(ARG) HYMN4900
000500          XI10R = CWV*V2(IZ)/RHO(IZ) HYMN4910
000501          XI10I = SWV*V2(IZ)/RHO(IZ) HYMN4920
000502          ZETAR = CWV/V2(IZ) HYMN4930
000503          ZETA1 = SWV/V2(IZ) HYMN4940
000504          XI14R = XI10R*DUL(IZ) HYMN4950
000505          XI14I = XI10I*DUL(IZ) HYMN4960
000506          OZEZ = OMEG * ( ZE-ZZ(IZ) ) HYMN4970
000507          GO TO (660,670,680), IM HYMN4980
000508          C   HYMN4990
000509          660   P0 = CTAR(IZ) HYMN5000
000510          PPO = -OMEG*STAB(IZ) HYMN5010
000511          ST = SIN( OZEZ ) HYMN5020
000512          CT = COS ( OZEZ ) HYMN5030
000513          GO TO 690 HYMN5040
000514          C   HYMN5050
000515          670   P0 = 1.0 HYMN5060
000516          PPO = 0.0 HYMN5070
000517          ST = ZE-ZZ(IZ) HYMN5080
000518          CT = 1.0 HYMN5090
000519          GO TO 690 HYMN5100
000520          C   HYMN5110
000521          680   P0 = CTAR(IZ) HYMN5120
000522          PPO = OMEG*STAB(IZ) HYMN5130
000523          ST = SINH( OZEZ ) HYMN5140
000524          CT = COSH( OZEZ ) HYMN5150
000525          C   HYMN5160
000526          690   IJK = 0 HYMN5170
000527          DO 700 JZ = IZ, IBZP HYMN5180

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000587      1           + XK*GAM*RHOL(IZ)*ZETAI/W)          HYMN5780
000588      C
000589    730   XI1R = T2/RHO(IZ) * (V25 - V26 - V27 - V28 + V29 + VK1) HYMN5790
000590           XI1I = T2 * (VK2 + V30)                      HYMN5800
000591           XI2I = ( GAM*V16 - V16 + DU(IZ) + T2*V4 )*W          HYMN5810
000592           XI3I = W*U(IZ) - T2/W*V7                      HYMN5820
000593           XI4I = T1*V6 + 2.0*W*U(IZ)                      HYMN5830
000594           XI5I = ( T2*V8 + DU(IZ)/RHO(IZ) )/W          HYMN5840
000595           XI2R = XI3R = XI4R = XI5R = 0                  HYMN5850
000596      C
000597      C
000598      C
000599           IF ( KNOT )      GO TO 740                  HYMN5860
000600           A1R = -XI16R*ZAP(8) - XI16I*ZAP(7)          HYMN5870
000601           A1I = XI16R*ZAP(7) - XI16I*ZAP(8) + GAM*P0*V5*T1 HYMN5880
000602           A2R = T1/W*(V16*V3+V5/RHO(IZ))*P0          HYMN5890
000603           T5 = W/UL(IZ) * RHOL(IZ)/UL(IZ)          HYMN5900
000604           T6 = V20*ZETAI - T5*ZETAR                  HYMN5910
000605           T7 = V20*ZETAR - T5*ZETAI                  HYMN5920
000606           T8 = W/RHO(IZ) * ( RHOL(IZ) - RHO(IZ)*RHOL(IZ) ) HYMN5930
000607      C
000608      0           A4R = T1 * ( T8*( ZETAI*ZAP(5) + ZETAR*ZAP(6) )          HYMN5940
000609      1           - RHOL(IZ)*( ZETAR*ZAP(1) + ZETAI*ZAP(2) )          HYMN5950
000610      2           - T6*ZAP(3) + T7*ZAP(4) )                      HYMN5960
000611      3           + XI16R*(ZAP( 9)-ZAP(12)) - XI16I*(ZAP(11)+ZAP(10)) HYMN5970
000612      C
000613      0           A4I = T1 * ( T8*( ZETAI*ZAP(6) - ZETAR*ZAP(5) )          HYMN5980
000614      1           - RHOL(IZ)*( ZETAR*ZAP(2) - ZETAI*ZAP(1) )          HYMN5990
000615      2           - T7*ZAP(3) - T6*ZAP(4) )                      HYMN6000
000616      3           + XI16R*(ZAP(11)+ZAP(10)) + XI16I*(ZAP( 9)-ZAP(12)) HYMN6010
000617      C
000618    740   T9 = HA * P11I                      HYMN6020
000619           T10 = HB * P11I                     HYMN6030
000620           TEMP = -GAM*W*QBAR(IZ)          HYMN6040
000621      0           A1R = A1R + TEMP*(T9+P10I) + GAM*P0*(V18+T2*V5) HYMN6050
000622      1           + XI2I*P11I + XI4I*PP11I          HYMN6060
000623           A1I = A1I + TEMP*(T10-P10R)          HYMN6070
000624           A2R = A2R + V16*(T10-P10R)          HYMN6080
000625      0           A2I = ( (V18+T2*V5)/RHO(IZ) - V16*(V3*T2-DU(IZ)) )/W*P0 HYMN6090
000626      1           - V16*(T9+P10I)          HYMN6100
000627      0           A4R = A4R + XI1R*P0          + XI4I*PP10I          + XI2I*P10I HYMN6110
000628      0           A4I = A4I + ( XI1I-OMEG2*XI5I )*P0 - XI3I*PP0 - XI4I*PP10R HYMN6120
000629      1           - XI2I*P10R          HYMN6130
000630      C
000631           *****          HYMN6140
000632      C
000633      C   SET UP INTEGRANDS ( SIMPSON RULE HERE )          HYMN6150
000634     DO 750 I = 1, 6          HYMN6160
000635           GL(2*I-1,NOD) = AL(I)*ST          HYMN6170
000636           GL(2*I ,NOD) = AL(I)*CT          HYMN6180
000637           AL(I) = 0.0          HYMN6190
000638    750   CONTINUE          HYMN6200
000639      C
000640           GO TO (780,780,760), NOD          HYMN6210
000641      C
000642    760   DO 770 I = 1, 12          HYMN6220
000643           SLAM(I) = SLAM(I) + GL(I,1) + 4.0*GL(I,2) + GL(I,3) HYMN6230
000644           C           WEIGHTED SUM FOR THREE ORDINATES          HYMN6240
000645           GL(I,1) = GL(I,3)          HYMN6250

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000646      770      CONTINUE                               HYMN6370
000647          NOD = 1                                 HYMN6380
000648      C
000649      780      CONTINUE                               HYMN6390
000650      C
000651      C***** ENDS PRINCIPAL Z-LOOP ***** HYMN6400
000652      C      STILL DOING FOR IW                      HYMN6410
000653      C
000654      C***** ***** ***** ***** ***** ***** ***** HYMN6420
000655      C
000656      C      COMPLETE INTEGRATION                  HYMN6430
000657      DO 790 I = 1, 12                           HYMN6440
000658          SLAM(I) = SLAM(I) * DZ/3.0             HYMN6450
000659      790      CONTINUE                               HYMN6460
000660      IF ( LIMIT )      GO TO 800                 HYMN6470
000661      C      CALCULATE DEFECT < CONTRIBUTION OF INTEGRALS FROM Z=ZC TO Z=ZE >HYMN6520
000662          TEMP = 2.0*W*UE                         HYMN6530
000663          SLAM( 1) = SLAM( 1) + TEMP*PP11I*(CF-1.0)/OMEG2 HYMN6540
000664          SLAM( 2) = SLAM( 2) + TEMP*PP11I*SF/OMEG   HYMN6550
000665          SLAM( 9) = SLAM( 9) + TEMP*PP10I*(CF-1.0)/OMEG2 HYMN6560
000666          SLAM(10) = SLAM(10) + TEMP*PP10I*SF/OMEG   HYMN6570
000667          SLAM(11) = SLAM(11) - TEMP*PP10R*(CF-1.0)/OMEG2 HYMN6580
000668          1      - 0.5*W*UE*( PSI*COZE-CTAB(IDZP)*SF )/OMEG  HYMN6590
000669          2      + 0.5*T2/W*UE*( PSI*SOZE-STAB(IDZP)*SF )*SIGN  HYMN6600
000670          SLAM(12) = SLAM(12) - TEMP*PP10R*SF/OMEG   HYMN6610
000671          1      - 0.5*W*UE*( PSI*SOZE-STAB(IDZP)*SF )*SIGN  HYMN6620
000672          2      + 0.5*T2/W*UE*( PSI*COZE+CTAB(IDZP)*SF )*OMEG*SIGN  HYMN6630
000673      C
000674      800      G21R = ANH*SLAM(1) + BNH*SLAM(5) + CNHR*SLAM(5) - CNHI*SLAM(7)HYMN6750
000675          G21I = ANH*SLAM(3) + BNH*SLAM(7) + CNHR*SLAM(7) + CNHI*SLAM(5)HYMN6760
000676          DG21R = ANH*SLAM(2) + BNH*SLAM(6) + CNHR*SLAM(6) - CNHI*SLAM(8)HYMN6770
000677          DG21I = ANH*SLAM(4) + BNH*SLAM(8) + CNHR*SLAM(8) + CNHI*SLAM(6)HYMN6780
000678      C
000679      C      THE FOLLOWING AVAILABLE BY EQUIVALENCE...  HYMN6790
000680          G20R IS SLAM( 9)                         HYMN6800
000681          G20I IS SLAM(11)                         HYMN6810
000682          DG20R IS SLAM(10)                         HYMN6820
000683          DG20I IS SLAM(12)                         HYMN6830
000684      C
000685      C      FOR NONZERO OMEG, DIVISION BY OMEG IS IMPLICIT IN ERCON, EICON.  HYMN6840
000686          IAR, IAI, IBR, IBI ARE TYPE REAL.        HYMN6850
000687          TEMP = UE * W * ZING(2)                 HYMN6860
000688          0      IAR = H1R - DG20R - ERCON*G20I - EICON*G20R  HYMN6870
000689          1      + ( ( CI*Y1I - CR*Y1R )*W + CR*Y1I + CI*Y1R )*W*UE  HYMN6880
000690          0      IAI = H1I - DG20I + ERCON*G20R - EICON*G20I  HYMN6890
000691          1      - ( ( CR*Y1I + CI*Y1R )*W + CR*Y1R - CI*Y1I )*W*UE  HYMN6900
000692          IBR = H2R + DG21R + ERCON*G21I + EICON*G21R + TEMP*( CI-W*CR )  HYMN6910
000693          IBI = H2I + DG21I - ERCON*G21R + EICON*G21I - TEMP*( CR+W*CI )  HYMN6920
000694      C
000695          HTD = IBR*IBR + IBI*IBI                HYMN6930
000696          HTR = ( IAR*IBR + IAI*IBI ) / HTD       HYMN6940
000697          HTI = ( IAI*IBR - IAR*IBI ) / HTD       HYMN6950
000698      C
000699          THTR(IW) = HTR                         HYMN6960
000700          THTI(IW) = HTI                         HYMN6970
000701      C
000702          IF ( .NOT. CKOUT )      GO TO 820       HYMN6980
000703          WRITE (5,150)                         HYMN6990
000704          WRITE (6,160) ! , IAR, IAI, IBR, IBI, ERCON, EICON, HYMN7000

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000705      1          G20R, G21R, DG20R, DG21R, H1R , H2R , CR ,   HYMN7060
000706      2          G20I, G21I, DG20I, DG21I, H1I , H2I , CI       HYMN7070
000707
000708      C 820    CONTINUE
000709      C          END OF W-LOOP
000710      C***** ****
000711      C
000712      KER = NW
000713      XOUT(9) = XNW
000714      C
000715      IF ( HRUN ) GO TO 850
000716      C
000717      DO 830 IW = 1, NW
000718      XOUT(IW+ 9) = WC (IW)
000719      XOUT(IW+39) = THR(IW)
000720      XOUT(IW+69) = THI(IW)
000721      830    CONTINUE
000722      GO TO (880,840), KOUT
000723      840 IF ( CKOUT ) CALL PAGE ( 70 )
000724      WRITE (6,40)
000725      WRITE (6,50) ( WC(I), THR(I), THI(I), I = 1, NW )
000726      GO TO 880
000727      C
000728      850 DO 860 IW = 1, NW
000729      XOUT(IW+ 9) = WC (IW)
000730      XOUT(IW+39) = THTR(IW)
000731      XOUT(IW+69) = THTI(IW)
000732      860    CONTINUE
000733      GO TO (880,870), KOUT
000734      870 IF ( CKOUT ) CALL PAGE ( 70 )
000735      WRITE (6,40)
000736      WRITE (6,60) ( WC(I), THR(I), THI(I), THTR(I), THTI(I),
000737      1           I = 1, NW )
000738      C
000739      880 IF ( .NOT. CKOUT ) GO TO 890
000740      CALL PAGE ( 70 )
000741      WRITE (6,120) ( ZZ(I), U(I), DU(I), UL(I), RHO(I), RHOL(I),
000742      1 QBAR(I), ZIP3(I), ZIP5(I), I = 1, IDZP )
000743      IF ( .NOT. HRUN ) GO TO 890
000744      CALL PAGE ( 70 )
000745      WRITE (6,130)
000746      WRITE (6,140) ( ZZ(I), D2U(I), DUL(I), DRHO(I), DROL(I), DQ(I), V1(I),
000747      1 V2(I), I = 1, IDZP )
000748      C
000749      C
000750      C
000751      C N.B. HTR, HTI ARE FINAL RESULTS OF THIS SUBROUTINE WHEN PLACED HYMN7520
000752      C IN XOUT. HTR, HTI INCLUDE INJECTOR EFFECTS, WHILE HR, HI HYMN7530
000753      C DO NOT. HENCE IF SUBROUTINE DDD IS ENTERED WITH HTR, HTI, HYMN7540
000754      C DDD WILL EXPAND TABLE (BY INTERPOLATION), PRINT, HYMN7550
000755      C AND RETURN. HYMN7560
000756      C
000757      C
000758      C
000759      890 RETURN
000760      END

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@ ELT SUB10,1,690702, 36302

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000001      SUBROUTINE DDD(DTN,DOUT,CD,NER,ERR)          HTNT 10
000002      C                                         HTNT 20
000003      C   PROGRAM D COMPUTE HTR,HTI + INTERPOLATE 40 POINTS    HTNT 30
000004      CC  20 SEP 67 MODIFIED FOR TABULAR INJECTOR COEFFICIENTS  HTNT 40
000005      C                                         HTNT 50
000006      LOGICAL LOGIK,HRUN,TABLR                      HTNT 60
000007      COMMON /PROLOG/ LOGIK(50)                     HTNT 70
000008      COMMON /ABCDF/ EXTRA(100), ABLOK(600), A    , B , SPACE(3556), HTNT 80
000009      1     WIT(17), AVN(17), BVN(17),CVNR(17), CVNI(17)        HTNT 90
000010      DIMENSION DIN(1),DOUT(1),A(133),B(133),OMEGA(1),HR(1),HI(1)  HTNT 100
000011      1,HTR(30),HTI(30),HTRINT(1),HTIINT(1), OMEGA(1)       HTNT 110
000012      2,DOM(30)                                     HTNT 120
000013      EQUIVALENCE (LOGIK(8),HRUN),(LOGIK(17),TABLR)        HTNT 130
000014      EQUIVALENCE (A(1),ANH),(A(2),BNH),(A(3),CNHRE),(A(4),CNHIM),  HTNT 140
000015      1(A(5),GAMMA),(A(6),XLRN),(A(7),XLON),(A(9),XNW),(A(10),OMEGA), HTNT 150
000016      2,(A(40),HR),(A(70),HI),(B(9),ONW),(B(10),OMGA),(B(51),HTRINT), HTNT 160
000017      3(B(92),HTI(NT) , (OMEGA, DOM )                HTNT 170
000018      C                                         HTNT 180
000019      10 FORMAT ( 21H0 INPUT TO PROGRAM D // 10X8H GAMMA = F8.4,5X6HLR/N =HTNT 190
000020      . 1 F12.8, 5X6HLT/N = F12.8 )                  HTNT 200
000021      20 FORMAT ( 18X3HANH12X3HBNH11X6HCNH RE 9X6HCNH IM // 9X 4F15.7 // ) HTNT 210
000022      30 FORMAT ( // 38H INJECTOR DISTRIBUTION COEFFICIENTS... //      HTNT 220
000023      117X5HOMEGA 11X3HANH 12X3HBNH 11X6HCNH RE 9X6HCNH IM // (9X5F15.7))HTNT 230
000024      40 FORMAT (1H0, 19X,8HOMEGA(C),9X3H HR,13X3H HI )           HTNT 240
000025      50 FORMAT (1H0,19X, 8HOMEGA(C),9X3HHTR 13X3HHTI )          HTNT 250
000026      60 FORMAT(1H ,10X,3F16.6)                      HTNT 260
000027      70 FORMAT (1H0 ,20H PROGRAM D OUTPUT // 19X,8HOMEGA(C) 9X  HTNT 270
000028      16H  HTR ,10X,6H HTI // )                   HTNT 280
000029      80 FORMAT (91H0 ALL VALUES OF HTR ARE NEGATIVE- ( I.E. OUT OF RANGE OFHTNT 290
000030      1INTEREST- WILL PROCEED TO NEXT CASE))          HTNT 300
000031      90 FORMAT(//,30X,69H FOLLOWING WILL BE INTERPOLATION WITHIN HTR HTIHTNT 310
000032      1 TABLE GIVEN ABOVE )                      HTNT 320
000033      100 FORMAT (19X,8H OMEGA ,9X6HHTRINT,10X,6HHTIINT )        HTNT 330
000034      110 FORMAT (11X,F10.5,10X,F10.5,10X,F10.5)            HTNT 340
000035      C                                         HTNT 350
000036      ERR=0.0                                     HTNT 360
000037      C=0.0                                      HTNT 370
000038      CALL DVCHK (K000FX)                      HTNT 380
000039      120 DO 130 I=1,133                      HTNT 390
000040      A(I)= DIN(I)                      HTNT 400
000041      130 B(I)=0.0                         HTNT 410
000042      NER=IFIX(XNW)                      HTNT 420
000043      IF(NER)140,140,160                 HTNT 430
000044      140 WRITE (6,150)NER                HTNT 440
000045      150 FORMAT (1H0,1UX,31H NUMBER OF OMEGAS IN ERROR = ,3X,I4 ) HTNT 450
000046      GO TO 510                           HTNT 460
000047      160 IF(NER-29)170,170,140             HTNT 470
000048      170 ONW = 40.0                        HTNT 480
000049      IF ( HRUN )                      GO TO 190          HTNT 490
000050      NWI = A(8) + 0.01                    HTNT 500
000051      IF ( NWI .GT. 2 )                   GO TO 180          HTNT 510
000052      ASSIGN 280 TO NT                  HTNT 520
000053      TABLR = .FALSE.                   HTNT 530
000054      ANH = AVN (1)                      HTNT 540
000055      BNH = BVN (1)                      HTNT 550

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Report 20672-P2D

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CNHRE = CVNR(1)
CNHIM = CVNI(1)
GO TO 190
180 ASSIGN 270 TO NT
      TABLR = .TRUE.
190 IF(CD=99.0)260,260,200
200 CALL PAGE ( 60 )
      WRITE (6,10) GAMMA, XLRN, XLON
      IF ( HRUN ) GO TO 230
      IF ( TABLR ) GO TO 210
      WRITE (6,20) ANH, BNH, CNHRE, CNHIM
      GO TO 220
210 WRITE (6,30) ( WIT(I), AVN(I), BVN(I), CVNR(I), CVNI(I),
      1           1 = 1, NWI )
      220 WRITE (6,40)
      GO TO 240
230 WRITE (6,50)
240 DO 250 I = 1, NER
250 WRITE (6,60)OMEGA(I),HR(I),HI(I)
C
      260 IF ( HRUN )
      DO 340 I=1,NER
      W = OMEGA(I)
      GO TO NT,(270,280)
270 CALL INT4 ( WIT, AVN, W, ANH )
      CALL INT4 ( WIT, BVN, W, BNH )
      CALL INT4 ( WIT, CVNR, W, CNHRE )
      CALL INT4 ( WIT, CVNI, W, CNHIM )
280 DEN = GAMMA*W
      X = ANH - CNHIM/DEN*XLRN
      Y = BNH / DEN * XLRN + CNHRE * XLON / DEN
      SQR = X * X + Y * Y
      HTR(I) = (X * HR(I) + Y * HI(I)) / SQR
      HTI(I) = (X * HI(I) - Y * HR(I)) / SQR
      CALL DVCHK (K000FX)
      GO TO (310,290),K000FX
000092      290 IF (CD-10.0) 340,300,300
000093      300 IF (I-1) 330,320,330
000094      310 C-10.0
000095      320 LIN=NER+6
      CALL PAGE (LIN)
      WRITE (6,70)
000097      330 WRITE (6,60)DOM(I),HTR(I),HTI(I)
000098      340 CONTINUE
      GO TO 370
C
      350 DO 360 I = 1, NER
      HTI(I) = HI(I)
      360 HTR(I) = HR(I)
      370 JOMEGL = 0
      JOMEGL2=0
      IF ( CD .LE. 99.0 ) CALL PAGE ( 60 )
000101      000102      000103      000104      000105      000106      000107      000108      000109      000110      000111      000112      000113      000114
      IF ( CD .LE. 99.0 ) CALL PAGE ( 60 )
      DO 390 I =1, NER
      IF ( HTR(I) ) 390,390,380
      380 JOMEGL = 1
      GO TO 410
      390 CONTINUE
      IF (JOMEGL)400,400,410
      400 WRITE (6,80)

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Report 20672-P2D

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000115      ERRE= -1.0
000116      GO TO 520
000117      NO 430 J = I, NER
000118      IF (HTR(J)) 420, 430, 430
000119      JOMEG2 = J
000120      GO TO 440
000121      430 CONTINUE
000122      JOMEG2 = NER
000123      DLTMEG = (DOM(JOMEG2) - DOM(JOMEG1)) / 39.0
000124      L=NER+1
000125      HTI(L)=0.0
000126      HTR(L)=0.0
000127      DOM(L)=0.0
000128      GMGA(1) =DOM(JOMEG1)
000129      DO 490 I=1,40
000130      CALL INT4(DOM(1),HTR(1),UMGA(1),HTRINT(1))
000131      CALL INT4(DOM(1),HTI(1),UMGA(1),HTINT(1))
000132      IF (CD-10.0)480,450,450
000133      450 IF ( I-1 ) 470,460,470
000134      460 IF ( .NOT. HRUN ) CALL PAGE ( 60 )
000135      WRITE (6,90)
000136      WRITE (6,100)
000137      470 WRITE (6,60) UMGA(I),HTRINT(I),HTINT(1)
000138      480 OMDA(I+1) = OMDA(I) + DLTMEG
000139      490 CONTINUE
000140      DO 500 I=1,133
000141      500 DOUT (I) = B(I)
000142      IF(C) 510,520,510
000143      510 NER=0
000144      520 RETURN
000145      END
CU0145

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Report 20672-P2D

@ ELT SUB11,1,691029, 50059

```

000001
000002
000003
C***** THIS PROGRAM WAS WRITTEN FROM A REPORT ON NOZZLE ADMITTANCE
C***** THEORY FROM PRINCETON UNIVERSITY. THE ANALYSIS WAS DONE BY
C***** CARL LJNDELUS AND THE PROGRAMMING BY JERRY HOWARD. JOB 8052
C***** NOZMIT MODIFIED 25 JUL 67 TO SUPPLY CR1,C11 IN PLACE OF B11,B1.
C***** NOZMIT 70
C***** NOZM 80
C***** NOZM 80
C***** NOZM 90
C***** NOZM 100
C***** NOZM 110
C***** NOZM 120
C***** NOZM 130
C***** NOZM 140
C***** NOZM 150
C***** NOZM 160
C***** NOZM 170
C***** NOZM 180
C***** NOZM 190
C***** NOZM 200
C***** NOZM 210
C***** NOZM 220
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C***** NOZM 300
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C***** NOZM 360
C***** NOZM 370
C***** NOZM 380
C***** NOZM 390
C***** NOZM 400
C***** NOZM 410
C***** NOZM 420
C***** NOZM 430
C***** NOZM 440
C***** NOZM 450
C***** NOZM 460
C***** NOZM 470
C***** NOZM 480
C***** NOZM 490
C***** NOZM 500
C***** NOZM 510
C***** NOZM 520
C***** NOZM 530
C***** NEW
C***** NOZM 550**-1

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SUBROUTINE CCC(DIN,DOUT,WC,CCDE,NER)

COMMON /ABCD/ LOGIK, SL1, SL2, EORJ
      XY , U2TBL , DESIRE , RAT , PAC , RCC
      RCT , ALFA , G , KN , Y , YP
      YOUT , TEMP , E , XTABLE , YTABLE , A
      R , AM , AP , AMP , ZZ , AMM
      AMP2 , CALFA , CTALFA , DELAM , DELIZ , FKN
      G1 , G2 , G3 , G4 , JFLAG1 , KNM1
      K , NN , PI , PROD , RSTA1 , RSTA2
      SALFA , T1 , T2 , T3 , XINT , XK
      Z21 , Z22 , ZZ3 , A1 , ABC , ABD
      COMMON /ARCD/ A1 , ALPHAI , ALPHAR , AR1 , B101 , B102
      B10 , B1 , B2 , B3 , B4 , B5
      B6 , B7 , B8 , B9 , B92 , B9
      B11 , BR1 , C2 , C3 , CHIR
      C11 , CR1 , D10 , D11 , D1
      D12 , D3 , D4 , D5 , D6 , D7
      D8 , D9 , DC2 , D , DU2 , EI
      ER , F31 , F3R , F1 , FR , H1
      H , I , IWO , IW , IWW , J
      COMMON /BCDF/ MDESIR , NK , NP , S2 , S , TT
      U2 , U , W2 , W , X101 , XI0R
      X121 , X12R , X1 , XJI , XJR , XMNEW
      XMOLD , XNEW , XOLD , XPT , X , Z1
      COMMON /PROLOG/ LOGIK(50), SL1, SL2, EORJ
      DIMENSION XX(200),U2TBL(200),XTABLE(200),YTABLE(200),ZZ(<0)
      DIMENSION Y(8),YP(8),YOUT(8),TEMP(72),E(8)
      DIMENSION A(200),R(200),AM(200),AP(200),ANP(200)
      DIMENSION DIN(1), DOUT(1),WC(1)

C***** NOZM 440
C***** NOZM 450
C***** NOZM 460
C***** NOZM 470
C***** NOZM 480
C***** NOZM 490
C***** NOZM 500
C***** NOZM 510
C***** NOZM 520
C***** NOZM 530
C***** NEW
C***** NOZM 550**-1

C
C     NER = 0
C     READ INPUT
C     G = DIN(1)
      NOME=WC(2)+2.0001
      MRESIR = DIN(2) + .0001
      GEN=DOUT(4)
      IF (CODE) 10,20,30

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Report 20672-P2D

```

10 NER = 1
20 RETURN
30 IF (WC(1))40,50,40
40 WCONST=DOUT(3)/(6.2831853*DCUT(1))
      GEO=GEO/DOUT(1)
50 WCONST=DOUT(3)/(6.2831853*DOUT(2))
      GEO=GEO/DOUT(2)
60 IF (CODE=99.0)100,100,70
C *****
C PRINT OUT INPUT
C *****
C
70 CALL PAGE(5)
     WRITE (6,80)
80 FORMAT (1H0,7H PROGRAM C INPUT - CALCULATES KJZZLE ADMITTANCE
1COEFFICIENTS USING 8052
     WRITE (6,901G, MDESIR
90 FORMAT (1H0,5X,SHG =,F9.3,11H , MDESIR =,I2 )
100 CONTINUE
C *****
C MDESIR=1, INPUT TABLE INPUT DESIRE MDESIRE=2, CALCULATE TABLE, INPUT*
C DESIRE MDESIR=3,CALCULATE TABLE,CALCULATE DESIRE (AT LAST POINT)*
C *****
C
110 RAT = DIN(4)
     RAC = DIN(5)
     RCC = DIN(6)
     RCT = DIN(7)
     ALFA = DIN(8)
     KN = DIN(9) + .0001
     IF (CODE = 99.0) 140,140,120
120 CALL PAGE (1)
     WRITE (6,130)RAT, RAC, RCT, ALFA, KN
130 FORMAT (1H ,5X5HRAT =,F7.3,6H,RAC =,F7.3,6H,RCT =, NOZM 890
1 F7.3,7H,ALFA = F7.3,5H,KN = 14 )
140 CONTINUE
     CALL TBLCAL
     KN = KN/2 + 1
150 J = 10
     DO 170 I = 1,200
        XX(I) = DIN(J)
        U2TRL(I) = DIN(J+1)
        J = J+2
        IF (I) 170,170,160
160 IF ( XX(I) ) 170,180,180
170 CONTINUE
C *****
C READ VELOCITY POTENTIAL TABLE. FIRST POINT IS (0,1)*
C *****
C
000092
000093 KN = KN/2 + 1
000094 GO TO 190
000095
000096
000097
000098
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NOZM 560
NOZM 570
NOZM 580
NOZM 590
NOZM 600
NOZM 610
NOZM 620
NOZM 630
NOZM 640
NOZM 650
NOZM 660
NOZM 670
NOZM 680
NOZM 690
NOZM 700
NOZM 710
NOZM 720
NOZM 730
NOZM 740
NOZM 750
NOZM 760
NOZM 770
NOZM 780
NOZM 790
NOZM 800
NOZM 810
NOZM 820
NOZM 830
NOZM 840
NOZM 850
NOZM 860
NOZM 870
NOZM 880
NOZM 890
NOZM 900
NOZM 910
NOZM 920
NOZM 930
NOZM 940
NOZM 950
NOZM 960
NOZM 970
NOZM 980
NOZM 990
NOZM1010
NOZM1020
NOZM1030
NOZM1040
NOZM1050
NOZM1060
NOZM1070
NOZM1080
NOZM1090
NOZM1100
NOZM1110
NOZM1120
NOZM1130
NOZM1140
NOZM1150
C *****
C COUNT OF TOTAL NO. OF POINTS IN THE TABLE,*
C *****
C
180 KN = I - 1
190 IF (CODE=199.0)240,240,200
200 CALL PAGE(70)
     WRITE (6,220)
     KKKN=KN/2+1
     00 210 I=1,KKKN

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000115      KKK=KKKN+I                               NOZM1160
000116      VOL1=SQRT(U2TBL(I))                  NOZM1170
000117      VOL2=SQRT(U2TBL(KKK))                 NOZM1180
000118      WRITE(6,230)I,ZZ(2*I-1),XX(I),VOL1,KKK,ZZ(2*KKK-1),XX(KKK),VOL2 NOZM1190
000119      210 CONTINUE                           NOZM1200
000120      220 FORMAT(//,40X, 25HVELOCITY POTENTIAL TABLE ,//,35X, 46HZ = AXIAL PNOZM1210
000121          10ISION IN NOZZLE (INCHES)           ,/,35X,39HX = VELOCITY POTENNOZM1220
000122          2TIAL (NONDIMENSIONAL) ,/,35X, 69HV = AXIAL VELOCITY (UNDIMENSIONALNOZM1230
000123          3IZED BY SPEED OF SOUND AT THROAT)    NOZM1240
000124          4 ,/,5X,5HPOINT.11X,1HZ,16X,1HX,15X,16X,5HPOINT,11X,1HZ,16X,1HNOZM1250
000125          5X,16X,1HV,/,,)                      NOZM1260
000126      230 FORMAT(6X,I3,6X,3(E12.5,5X),6X,I3,6X,2(E12.5,5X),E12.5,) NOZM1270
000127      240 CONTINUE                           NOZM1280
000128      C *****
000129      C REVERSE ORDER OF TABLE VALUES AND SET UP FOR INT4D* NOZM1290
000130      250 NK = KN+1                           NOZM1300
000131          XTABLE(NK) = 0.0                   NOZM1310
000132          YTABLE(NK) = 0.0                   NOZM1320
000133          DO 260 I = 1,KN                  NOZM1330
000134          NK = NK - 1                     NOZM1340
000135          XTABLE(I) = XX(NK)                NOZM1350
000136          YTABLE(I) = U2TBL(NK)              NOZM1360
000137      260 CONTINUE                           NOZM1370
000138      C *****
000139      C READ ONE CASE AT A TIME*          NOZM1380
000140      C *****
000141      270 IWW = 410                          NOZM1390
000142          IWO = 2                         NOZM1400
000143          NP = DIN(3) + .0001             NOZM1410
000144          IF (CODE - 99.0) 290,290,270   NOZM1420
000145          NPR = NP + 3                  NOZM1430
000146          NPT = 3 * NP + 409            NOZM1440
000147          CALL PAGE(NPR)                NOZM1450
000148          WRITE(6,280)(DIN(I), I = 410, NPT ) NOZM1460
000149          280 FORMAT(1H0,39X, 6X,4H WN,12X,6H(SNH)N,10X,4H DES // NOZM1470
000150          1          (40X,3E16.6)          NOZM1480
000151      290 CONTINUE                           NOZM1490
000152          300 IF (CODE - 9.0) 340,340,310   NOZM1500
000153          C *****
000154          C PRINT HEADER AND OUTPUT SYMBOLS* NOZM1510
000155          C *****
000156          310 CALL PAGE(70)                NOZM1520
000157          KPAGE=48                         NOZM1530
000158          KCOUNT=0                         NOZM1540
000159          WRITE(6,320)                      NOZM1550
000160          320 FORMAT(1H0, 20H PROGRAM C OUTPUT ) NOZM1560
000161          WRITE(6,330)                      NOZM1570
000162          330 FORMAT(//4X,6H(SNH)C,5X2HWC,6X,7HMACH NO,9X,2HAR,14X,2HAI,14X,2HBRNOZM1640
000163          1,14X,2HBI,14X,2HCR,14X,2HCI/4X,6H(SNH)N,5X2HWN,9X,1HG,6X,13H-AR/(MNOZM1650
000164          2ACH NO),3X,13H-AI/(MACH NO),9X,2HT1,14X,2HT2,8X,13H-CR/(MACH NO),3NOZM1660
000165          3X,13H-CI/(MACH NO)//)          NOZM1670
000166          340 CONTINUE                           NOZM1680
000167          DO 660 IW = 1,NP                  NOZM1690
000168          W = DIN(IWW)                      NOZM1700
000169          S = DIN(IWW+1)                      NOZM1710
000170          GO TO (350,350,360), MDESTR        NOZM1720
000171          350 DESIRE = DIN(IWW+2)            NOZM1730
000172          360 IWW = IWW + 3                  NOZM1740
000173

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```

C
000174
000175      XMOLD=0.0
000176      YMNEW=0.0
000177      XOLD=J.U
000178      YPT = 0.0
000179      X = 0.0
000180      XNEW=0.0
000181      XI = -.001
000182      H=XI
000183      W2=H*W
000184      S2=S*S
000185      G2=G*G
C *****
C *INITIALIZE EQUATIONS AT X=U.*
C *****
000186      DO 370 I = 1,6
000187      I = 0
000188      CALL ADSET(8,Y,YP,YOUT,TEMP,X,H,E)
000189      A1=.5*(G+1.0)
000190      C2=1.0
000191      C3=(G+1.0)*(G+1.0)+4.0*w2
000192      C6=.1*A1+w2
000193      B7=.25*(A1*(W2-S2)-W2*(G-1.0))/B6
000194      B8=-.125*W*(G2-1.0+2.0*(W2-S2))/B6
000195      B9=1/B7*(A1*A1+A1*W2)-A1*B8*(1.0-A1*W)+.125*(G2-1.0)*(W2-S2)
000196      B6=1/A1*(B7*B7-B8*B6)+2.0*A1*W*B7*B6
000197      B9=(B91+B92)/B5
000198      B10=.5*A1*(3.-G)*W*B7+B8*(A1*A1*A1+W2)+.125*(G-1.0)*W*(A1*A1-S2)
000199      B102=-A1*W*(B7*R-B8*B8)+2.0*A1*A1*B7*B8
000200      B10=(B101+B102)/B6
000201
000202
000203
000204
000205
000206
000207
000208
000209
000210
000211
000212
000213
000214
000215
000216
000217
000218
000219
000220
000221
000222
000223
000224
000225
000226
000227
000228
000229
000230
000231
000232
000233

C
000186      C *****
C *INTERPOLATING ON VELOCITY POTENTIAL TABLE*
C *****
370 CALL INT4(XTABLE(1),YTABLE(1),X,U2,DU2)
C2=.5*(G+1.0)-(G-1.0)
C=SQRT(C2)

NOZM1750
NOZM1760
NOZM1770
NOZM1780
NOZM1790
NOZM1800
NOZM1810
NOZM1820
NOZM1830
NOZM1840
NOZM1850
NOZM1860
NOZM1870
NOZM1880
NOZM1890
NCZM1900
NOZM1910
NOZM1920
NOZM1940
NOZM1950
NOZM1960
NOZM1970
NOZM1980
NOZM1990
NOZM2000
NOZM2010
NOZM2020
NOZM2030
NOZM2040
NOZM2050
NOZM2060
NOZM2070
NOZM2080
NOZM2090
NOZM2100
NOZM2110
NOZM2120
NOZM2130
NOZM2140
NOZM2150
NOZM2160
NOZM2170
NOZM2180
NOZM2190
NOZM2200
NOZM2210
NOZM2220
NOZM2230
NOZM2240
NOZM2250
NOZM2260
NOZM2270
NOZM2280
NOZM2290
NOZM2300
NOZM2310
NOZM2320
NOZM2330

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```

000233          U=SQRT(U2)
000234          D=-(G-1.0)*U2
C *** SINGULARITY AT THROAT-TAKE EQUATIONS 7 AND 8 UNTIL PAST *
000235          C
000236          C
000237          C
000238          C
000239          C
000240          C
000241          C
000242          C
000243          C
000244          C
000245          C
000246          C
000247          C
000248          C
000249          C
000250          C
000251          C
000252          C
000253          C
000254          C
000255          C
000256          C
000257          C
000258          C
000259          C
000260          C
000261          C
000262          C
000263          C
000264          C
000265          C
000266          C
000267          C
000268          C
000269          C
000270          C
000271          C
000272          C
000273          C
000274          C
000275          C
000276          C
000277          C
000278          C
000279          C
000280          C
000281          C
000282          C
000283          C
000284          C
000285          C
000286          C
000287          C
000288          C
000289          C
000290          C
000291          C

U=SQRT(U2)
D=-.5*(G-1.0)*U2
C *** SINGULARITY AT THROAT-TAKE EQUATIONS 7 AND 8 UNTIL PAST *
C
1F(X-XI)400,460,410
400 H1=U2*(C2-U2)
B2=A1*U2*D12/C2
B3=W*U2
B4=.25*(W2-U*C2*(G*(G-1.0))*S2)
E5=.25*((G-1.0)*U2*D12*S1)/C2
C
ABD=Y(7)*Y(7)-Y(-8)*Y(-8)
YP(7)=(B2*Y(7)-B3*Y(-8)-B4)/B1-ABD
YP(-8)=(B3*Y(7)+B2*Y(-8)+B5)/B1-2.0*Y(7)*Y(-8)
C
410 YP(1)=.5*(D12-W*Y(2)/U2)
YP(2)=.5*W*Y(1)/U2
D1=-Y(3)*Y(7)+Y(4)*(Y(-8)-W*(.5/U2+2.0/((G+1.0)*(1.0-U2))))
D2=S2*C2*(1.0/(G-1.0))*Y(2)/(2.0*W*U)
D3=(-W*Y(2)/U2+NU2*(1.0+(G-1.0)*Y(1)/C2))/(2.0*C2)
YP(3)=D1+D2+D3
C
D4=-Y(4)*Y(7)-Y(3)*(Y(-8)-W*(.5/U2+2.0/((G+1.0)*(1.0-U2))))
D5=-S2*C2*(1.0/(G-1.0))*U*((1.0-U2)/(2.0*U2)+Y(1)/U2)/(2.0*W)
D6=(W*Y(1)/U2+D12*(G-1.0)*Y(2)/C2)/(2.0*C2)
YP(4)=D4+D5+D6
C
D7=S2*C2*(1.0/(G-1.0))/((4.0*U)-Y(5)*Y(7))
D8=Y(6)*(Y(-8)-W* (.5/U2+2.0/((G+1.0)*(1.0-U2))))
YP(5)=D7+D8
C
ABC=-Y(6)*Y(7)
YP(6)=ABC-Y(5)*(Y(-8)-W* (.5/U2+2.0/((G+1.0)*(1.0-U2))))
C
CALL ADCOR($3y0)
C
420 XMNEW=U/C
XNEW=X
C
IF(XMNEW-DESIRE)>30,500,440
C *** IF OUR CALCULATED MACH NUMBER IS CLOSE ENOUGH TO DESIRE WE WILL STOP ***
C
430 IF(ABS(XMNEW-DESIRE)-1.E-5)>0,500,4/0
440 IF(X+H-XX(KN))450,460,460
450 XNEW=XX(KN)
GO TO 500
460 XMOLD=XMNEW
XMOLD=XNEW
GO TO 380
C
*** PASSED DESIRED MACH NUMBER ***
C LINEAR INTERPOLATION TO GET X CORRESPONDING TO DESIRED MACH ***
C
470 XPT=XMOLD+(XNEW-XMOLD)/(XMNEW-XMOLD)*(DESIRE-XMOLD)
XMOLD=XNEW
XMOLD=XNEW
XNEW=XPT
NOZM2340
NOZM2350
NOZM2360
NOZM2370
NOZM2380
NOZM2390
NOZM2400
NOZM2410
NOZM2420
NOZM2430
NOZM2440
NOZM2450
NOZM2460
NOZM2470
NOZM2480
NOZM2490
NOZM2500
NOZM2510
NOZM2520
NOZM2530
NOZM2540
NOZM2550
NOZM2560
NOZM2570
NOZM2580
NOZM2590
NOZM2600
NOZM2610
NOZM2620
NOZM2630
NOZM2640
NOZM2650
NOZM2660
NOZM2670
NOZM2680
NOZM2700
NOZM2710
NOZM2720
NOZM2730
NOZM2740
NOZM2750
NOZM2760
NOZM2770
NOZM2780
NOZM2790
NOZM2800
NOZM2810
NOZM2820
NOZM2830
NOZM2840
NOZM2850
NOZM2860
NOZM2870
NOZM2880
NOZM2890
NOZM2900
NOZM2910
NOZM2920

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0000292 CALL INT4(XTABLE(1),YTABLE(1),XNEW,K,U2)
0000293 C2 = .5*(G+1.0-U2*(G-1.0))
0000294 C = SQR((C2))
0000295 U = SQR((U2))
0000296 XNEW = U/C
0000297 I = I+1
0000298 IF((I-15)>480,460,481)
0000299 480 WRITE(6,490)
0000300 490 FORMAT(72HO) ITERATION SCHEME DOES NOT CONVERGE AFTER 10 ITERATIONS NOZM3010
0000301 500 CALL ADPAR(XNEW)
0000302 GO TO 10
0000303 500 CALL ADPAR(XNEW)
0000304
0000305 C **** COMPUTE ADMITTANCE COEFFICIENTS AND PRINT FINAL RESULTS ****
0000306 C **** ***** ***** ***** ***** ***** ***** ***** ***** ***** ****
0000307 C COMPUTE ADMITTANCE COEFFICIENTS AND PRINT FINAL RESULTS ****
0000308 C **** ***** ***** ***** ***** ***** ***** ***** ***** ***** ****
0000309 510 CALL INT4D(XTABLE(1),YTABLE(1),XNEW,U2,DU2)
0000310 C2=.5*(G+1.0-U2*(G-1.0))
0000311 C=SQRT(C2)
0000312 U=SQRT(U2)
0000313
0000314 DC2=-.5*(G-1.0)*DU2
0000315 D=SQRT(2.0/(G+1.0))*U*C2/((C2/(.5*(G+1.0)))*(1.0*G/(G-1.0)))
0000316 D9=(-1.0-U2)*(G+1.0)
0000317 F3I=YOUT(1)/C2
0000318 F3I=YOUT(2)/C2
0000319 X12R=2.0*YOUT(3)/D9
0000320 X12I=2.0*YOUT(4)/D9
0000321 X10R=2.0*YOUT(5)/D9
0000322 X10I=2.0*YOUT(6)/D9
0000323 ZI=YOUT(7)
0000324 ZI=YOUT(8)
0000325 ER=C2*X10R-ZR
0000326 EI=C*X10I-ZI
0000327 FR=U2*C2*X10R-ZF*U2
0000328 F1=U2*C2*X10I-Z1*U2-.5*W
0000329 F1=FR+FI*FI
0000330 AR1= D*(ER*FR+EI*FI)/D10
0000331 A1= D*(EI*FR-ER*FI)/D10
0000332 IF(S)=540,530,540
0000333 G1=W*C2*SQRT(U/(C2*(1.0/(G-1.0))))
0000334 GO TO 550
0000335 G1=W*C2*SQRT(U/(C2*(1.0/(G-1.0)))/S
0000336 E1=G1*(-S*R*X10I+FI*X10R)/D10
0000337 F1= G1*(FR*X10R+FI*X10I)/D10
0000338 H1=U*C2*SQRT(2.*G/(G+1.0))
0000339 XJ1=F3R*ZR-F3I*ZI+.5*(1.0-U2)*X10R+.5*W*X12I
0000340 XJ1=F3I*ZR+F3R*ZI+.5*(1.0-U2)*X10I-.5*W*X12R
0000341 CR1= H1*(XJR*FR+XJI*FI)/D10
0000342 C11= H1*(XJJ*FR-XJR*FI)/D10
0000343
0000344 ALPHAR=-AR1/DESIRE
0000345 ALPHAI=-AI1/DESIRE
0000346 CHIR=-CR1/DESIRE
0000347 CHI1=-C11/DESIRE
0000348 TT=(W/SQRT(.5*(G+1.0)))/SQRT(U*(.5*(G+1.0)-U2*(G-1.0)/2.0))
0000349 T1=.5*(G-1.0)
0000350

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```

000351      T2 = AI1*TT + BR1
000352
000353      C *****
000354      C CASE IS COMPLETED
000355      C *****
000356
000357      C FOR S=0 ADM COEF ARE ALPHA FOR 8005 LONGITUDINAL
000358
000359      C FOR S=N ADM COEF ARE T FOR 993 TRANSVERSE
000360
000361      C
000362      570 DOUT(IWO+1)=ALPHAR
000363          DOUT(IWO+101)=ALPHAI
000364          DOUT(IWO)=W/GEO
000365          DOUT(IWO+100)=W/GEO
000366          GO TO 590
000367
000368      580 CONTINUE
000369          DOUT(IW+19)=W/GEO
000370          DOUT(IW+49)=T1
000371          DOUT(IW+79)=T2
000372          DOUT(IW+109) = CR1
000373          DOUT(IW+139) = CI1
000374      590 IWO =IWO+2
000375          IF ( CODE - 9.0)    660,660,600
000376
000377      600 CONTINUE
000378          KKKN=(2*IW)+1
000379          IF(NOMEK-KKKN)610,620,620
000380      610 KKKN=KKKN-1
000381      620 KCOUNT=KCOUNT+4
000382          IF(KCOUNT-KPAGE)640,640,630
000383      630 CALL PAGE(70)
000384          WRITE (6,330)
000385          KCOUNT=0
000386          KPAGE=48
000387
000388      C *****
000389      C PRINT FINAL RESULTS*
000390      C *****
000391      640 WRITE (6,650)WC(1),WC(KKKN),DESIRE,AR1,AI1,BR1,BI1,CR1,CI1,S,W,G,ANOZM3890
000392          1LPHAR,ALPHAI,T1,T2,CHIR,CHII
000393      650 FORMAT(2(3X,F7.4,2X,F7.4,3X,F7.4,6E16.5//))
000394          FCCPSS=(WCONST*WC(KKKN))*12.0
000395          WRITE (6,670)FCCPS
000396
000397      660 CONTINUE
000398      670 FORMAT(4X,8HFC(CPS)=F10.4//)
000399          DOUT(205)=DESIRE
000400          IF(S)690,680,690
000401      680 DOUT(1)=NP
000402          DOUT(101)=NP
000403          RETURN
000404      690 DOUT(18)=NP
000405          DOUT(NP+21)=0.0
000406          DOUT(NP+51)=0.0
000407          DOUT(NP+81)=0.0
000408          DOUT(NP+111)=0.0
000409          DOUT(NP+141)=0.0
000410          RETURN
000411          END

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000001      SUBROUTINE TBLCAL
000002      C TBL CAL SUBROUTINE CALCULATES XX VS U2TBL FROM NOZZLE GEOMETRY
000003      C SIMPSONS RULE IS USED WITH KN INPUT ODD AND CHANGED TO KN/2+1 IN MAIN*VELP 10
000004      C                                           *VELP 20
000005      C                                           VELP 30
000006      C                                           VELP 40
000007      C                                           VELP 50
000008      LOGICAL LOGIK, SL1, SL2, EORJ
000009      COMMON /PROLOG/ LOGIK(50), SL1, SL2, EORJ
000010      COMMON /ABCD/   EXTRA(100), ABLOK(600)
000011      1      , XX      , U2TBL , DESIRE , RAT      , RAC      , RCC
000012      2      , RCT      , ALFA    , G      , KN      , Y      , YP
000013      3      , YOUT     , TEMP    , E      , XTABLE  , YTABLE  , A
000014      4      , R      , AM      , AP      , AMP    , ZZ      , AMM
000015      5      , AMP2     , CALFA   , CTALFA  , DELAM   , DELTZ   , FKN
000016      6      , G1      , G2      , G3      , G4      , JFLAG1  , KNM1
000017      7      , K      , NN      , PI      , PROD   , RSTA1  , RSTA2
000018      8      , SALFA   , T1      , T2      , T3      , XINT   , XK
000019      9      , ZZ1     , ZZ2     , ZZ3     , A1      , ABC    , ABD
000020      COMMON /ARCD/   ALPHA1   , ALPHAR  , AR1    , B101   , B102
000021      1      , B10     , B1      , B2      , B3      , B4    , B5
000022      2      , B6      , B7      , B8      , B91    , B92   , B9
000023      3      , B11     , BR1    , C2      , C3      , CHIi   , CHIR
000024      4      , C11     , CR1    , C       , D10    , D11   , D1
000025      5      , D2      , D3      , D4      , D5      , D6    , D7
000026      6      , D8      , D9      , DC2    , D      , DU2    , EI
000027      7      , ER      , F31    , F3R    , F1      , FR    , H1
000028      8      , H      , I      , TWO    , IW      , IWN   , J
000029      9      , MDESTR  , NK      , NP      , S2      , S     , TT
000030      1      , U2      , U      , U2     , W      , X101  , XI0R
000031      2      , XI21    , XI2R   , XI     , XJ1    , XJR   , XMNEW
000032      3      , XWOLD   , XNEW   , XOLD   , XPT    , X     , ZI
000033      4      , ZR      , ZR
000034      5      , ZR
000035      DIMENSION XX(200),U2TBL(200),XTABLE(200),YTABLE(200),ZZ(200)
000036      DIMENSION Y(8),YP(8),YUT(8),TEMP(72),E(8)
000037      DIMENSION A(200),R(200),AM(200),AR(200),AMP(200)
000038
000039      C
000040      C
000041      KNM1 = KN - 1
000042      DELAM = 1.0/(FKN+1.0)
000043      PI = 3.1415927
000044      ZZ(1) = 0.6
000045      DC 10 J = 1,200
000046      ZZ(J) = 0.0
000047      A(J) = 0.0
000048      R(J) = 0.0
000049      AMP(J) = 0.0
000050      AM(J) = 0.0
000051      XY(J) = 0.0
000052      U2TEL(J) = 0.0
000053      VELP 520
000054      VELP 530
000055      VELP 540
000056      VELP 550
000057      VELP 560
000058      VELP 570
000059      VELP 580
000060      VELP 590
000061      VELP 600
000062      VELP 610
000063      VELP 620
000064      VELP 630
000065      VELP 640
000066      VELP 650
000067      VELP 660
000068      VELP 670
000069      VELP 680
000070      VELP 690
000071      VELP 700
000072      VELP 710
000073      VELP 720
000074      VELP 730
000075      VELP 740
000076      VELP 750
000077      VELP 760
000078      VELP 770
000079      VELP 780
000080      VELP 790
000081      VELP 800
000082      VELP 810
000083      VELP 820
000084      VELP 830
000085      VELP 840
000086      VELP 850
000087      VELP 860
000088      VELP 870
000089      VELP 880
000090      VELP 890
000091      VELP 900
000092      VELP 910
000093      VELP 920
000094      VELP 930
000095      VELP 940
000096      VELP 950
000097      VELP 960
000098      VELP 970
000099      VELP 980
000100      VELP 990
000101      VELP 500
000102      VELP 510
000103      VELP 520
000104      VELP 530
000105      VELP 540
000106      VELP 550
000107      VELP 560
000108      VELP 570
000109      VELP 580
000110      VELP 590
000111      VELP 600
000112      VELP 610
000113      VELP 620
000114      VELP 630
000115      VELP 640
000116      VELP 650
000117      VELP 660
000118      VELP 670
000119      VELP 680
000120      VELP 690
000121      VELP 700
000122      VELP 710
000123      VELP 720
000124      VELP 730
000125      VELP 740
000126      VELP 750
000127      VELP 760
000128      VELP 770
000129      VELP 780
000130      VELP 790
000131      VELP 800
000132      VELP 810
000133      VELP 820
000134      VELP 830
000135      VELP 840
000136      VELP 850
000137      VELP 860
000138      VELP 870
000139      VELP 880
000140      VELP 890
000141      VELP 900
000142      VELP 910
000143      VELP 920
000144      VELP 930
000145      VELP 940
000146      VELP 950
000147      VELP 960
000148      VELP 970
000149      VELP 980
000150      VELP 990
000151      VELP 500
000152      VELP 510
000153      VELP 520
000154      VELP 530
000155      VELP 540
000156      VELP 550
000157      VELP 560
000158      VELP 570
000159      VELP 580
000160      VELP 590
000161      VELP 600
000162      VELP 610
000163      VELP 620
000164      VELP 630
000165      VELP 640
000166      VELP 650
000167      VELP 660
000168      VELP 670
000169      VELP 680
000170      VELP 690
000171      VELP 700
000172      VELP 710
000173      VELP 720
000174      VELP 730
000175      VELP 740
000176      VELP 750
000177      VELP 760
000178      VELP 770
000179      VELP 780
000180      VELP 790
000181      VELP 800
000182      VELP 810
000183      VELP 820
000184      VELP 830
000185      VELP 840
000186      VELP 850
000187      VELP 860
000188      VELP 870
000189      VELP 880
000190      VELP 890
000191      VELP 900
000192      VELP 910
000193      VELP 920
000194      VELP 930
000195      VELP 940
000196      VELP 950
000197      VELP 960
000198      VELP 970
000199      VELP 980
000200      VELP 990
000201      VELP 500
000202      VELP 510
000203      VELP 520
000204      VELP 530
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000720      VELP 690
000721      VELP 700
000722      VELP 710
000723      VELP 720
000724      VEL
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Report 20672-P2D

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R(1)= RAT
A(1)=PI**R(1)**2
U2TBL(1)=1.0
R(KN)= RAC
ALFA = ALFA*.01745329
CALFA=COS(ALFA)
SALFA= SIN(ALFA)
CTALFA=CALFA/SALFA
RSTA1=RAT+RCT*(1.0-CALFA)
RSTA2=RAC-RCC*(1.0-CALFA)
ZZ1=RCT*SALFA
ZZ2=ZZ1+CTALFA*(RSTA2-RSTA1)
ZZ3=ZZ2+RCC*SALFA
DELTZ = ZZ3/(FKN-1.0)
C
  JFLAG1=1
C
DO 80 I = 2,KNM1
ZZ(I) = ZZ(I-1) + DELTZ
GO TO (20,40,60),JFLAG1
20 R(1)=RAT+RCT-SQRT(RCT**2-ZZ(1)**2)
IF (R(1)-RSTA1)>0,70,30
30 JFLAG1=2
40 R(1)=RSTA1+(RSTA2-DELTZ)*(ZZ(1)-ZZ1)/(ZZ2-ZZ1)
IF (R(1)-RSTA2)>0,70,50
50 JFLAG1=3
60 F(1)=RAC-RCC+SQRT(RCC**2-(ZZ3-ZZ(1))**2)
70 A(1)=PI*R(i)**2
80 CONTINUE
C
ZZ(KN) = ZZ(KNM1) + DELTZ
A(KN) = PI*RAC**2
AMM = 1.0+ DELAM
G1=2.0*(G +1.0)
G2 =(G - 1.0)/2.0
G3 = (G + 1.0)/(2.0*G - 2.0)
G4=1.0/G1
C
DO 90 J = 1,KN
AMM = AMM - DELAM
AM(J) = AMM
AP(J)=A(1)/AMM*(G1*(1.0+G2*AMM**2))**G3
90 CONTINUE
C
DO 100 K = 2,KN
CALL INT4(AP(1),AM(1),A(K),AMP(K))
AMP2=AMP(K)**2
U2TBL(K)=(G4*AMP2)/(1.0+G2*AMP2)
100 CONTINUE
C
DESIRE = AMP(KN)
YINT = J_0
NN = KN - 2
K = 1
XK = SQRT(G1*RAT/RCI)
PROD = 2.0*XK*DELTZ/3.0
DO 110 J = 1,NN,2
T1 = SQRT(U2TEL(J))
T2 = SQRT(U2TBL(J+1))
110

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000115      T3 = SQRT(U2TBL(J+2))          VELP1150
000116      XINT = XINT + PROD*(T1+4.0*T2+T3)  VELP1160
000117      K = K + 1                         VELP1170
000118      XX(K) = -XINT/RAT                VELP1180
000119      U2TBL(K-1) = U2TBL(J)            VELP1190
000120      :10 CONTINUE                     VELP1200
000121      U2TBL(K) = U2TBL(KN)             VELP1210
000122      *****                         VELP1220
000123      RETURN                         VELP1230
000124      END                            VELP1240
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@ ELT SUB13,1,690708, 48736

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000001      SUBROUTINE  LONGL          LONG  10
000002      C
000003      COMMON /ABCD/  DINP(4300)    LONG  20
000004      DIMENSION
000005      1  EXTRA(100),DISTL(20),DISTM(20),AMIT(90),    LONG  30
000006      2  TAB(150,3),  OMG(150),  ALFR(150),  ALFI(150), W(27)    LONG  40
000007      EQUIVALENCE
000008      1  (EXTRA(11),GAMMA),  (DINP(107), U1BAR ),  (EXTRA(23), W ),    LONG  50
000009      2  (EXTRA(14),RAC), (EXTRA(15), ELCH), (EXTRA(16),SOUND,CO),    LONG  60
000010      3  ( DINP(17),ULM ),( LINP(18),ZK ),    LONG  70
000011      4  (EXTRA(20),ELNOZ),(EXTRA(51),DISTL),(EXTRA(71),DISTM),    LONG  80
000012      5  (DINP(1),  EXTRA),
000013      6  (DINP(151),TAB,OMG),(DINP(301),ALFR),(DINP(451),ALFI),    LONG  90
000014      7  (DINP(601),AMIT)
000015
000016      C
000017      10 FORMAT (21X F7.1, 11X F10.5, 10X F10.5, 10X F10.5)    LONG 100
000018      20 FORMAT ( / 11X 30H RESULTS FOR LONGITUDINAL MODE //21X7HFC(CPS)    LONG 110
000019      1 15X5HOMECA14X7HTAU(MS)16X1HN )    LONG 120
000020      30 FORMAT  (/BH U1BAR =,E15.8,3X,7HGAMMA =,E15.8,3X,3HK =,E15.8,3LONG 130
000021      1X,3HX =,E15.8,3X5HULM =E15.8 )    LONG 140
000022      C
000023      CALL PAGE (60)          LONG 150
000024      NINC = 10             LONG 160
000025      EIN = 1.0E-4           LONG 170
000026      CALL INT4 ( DISTL(1), DISTM(1), ELCH, EDIST )    LONG 180
000027      CALL INTGR ( 0.0, ELCH, X, NINC )    LONG 190
000028      31  CONTINUE          *NEW
000029      CALL INT4 ( DISTL(1), DISTM(1), X , 10FX )    LONG 200
000030      CALL INTGS($31,10FX,SUMM,EIN,MINC)    *NEW
000031      XX = 1.0 - SUMM/(EDIST*ELCH)    LONG 210
000032      ULO = ULM / SOUND
000033      WRITE (6,30)U1BAR, GAMMA, ZK, XX, ULM    LONG 220
000034      WRITE (6,20)
000035      U1BAR2=U1BAR*U1BAR    LONG 230
000036      T1BAR=1.0-.5*(GAMMA-1.0)*U1BAR2    LONG 240
000037      C1BAR=SQRT(T1BAR)    LONG 241
000038      ZETA1B=1.0/(T1BAR-GAMMA*U1BAR2*(ZK-1.0))    LONG 250
000039      ASTAR=2.0*C1BAR/(C1BAR**2-U1BAR2)    LONG 260
000040      C
000041      50  NOMEGL = EXTRA(22) + .001    LONG 270
000042      IJ = NOMEGL-1    LONG 280
000043      KK = 1             LONG 290***-1
000044      IK = 5*IJ + 1    LONG 300
000045      DO 60 J = 1, IJ    LONG 310
000046      OMG(KK) = W(J)    LONG 320
000047      DELT = 0.2*(W(J+1)-W(J))    LONG 330
000048      KK = KK+1          LONG 340
000049      DO 60 I = 1, 4    LONG 350
000050      OMG(KK) = OMG(KK-1) + DELT    LONG 360
000051      KK = KK + 1          LONG 370
000052      60  CONTINUE          LONG 380
000053      OMG(KK) = W(NOMEGL)    LONG 390
000054      DO 70 KK = 1, IK    LONG 400
000055      CALL INT4 ( AMIT(1), AMIT(31), OMG(KK), ALFR(KK) )    LONG 410

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000056      CALL  INT4  ( AMIT(1), AMIT(61), OMG(KK), ALF1(KK) )      LONG 570
000057      70  CONTINUE                                         LONG 580
000058      DO 130 I = 1, 1K                                     LONG 590
000059      IF ( I .EQ. 51 .OR. I .EQ. 101 )      CALL  PAGE ( 60 )    LONG 600
000060      OMEGA=TAB(1,1)                                         LONG 610
000061      ALPRE=TAB(1,2)                                         LONG 620
000062      ALPIM=TAB(1,3)                                         LONG 630
000063      DENB=(C1BAR+U1BAR*ALPRE)**2+U1BAR2*ALPIM*ALPIM          LONG 640
000064      BRE=(C1BAR*C1BAR-U1BAR2*(ALPRE*ALPRE+ALPIM*ALPIM))/DENB  LONG 650
000065      BIM=2.0*C1BAR*U1BAR*ALPIM/DENB                      LONG 660
000066      UL=ULO-ZK*XX                                         LONG 670
000067      ZETAL=ZETA1B*U1BAR/UL                                LONG 680
000068      A=2.0*ZETA1B*U1BAR*GAMMA*ZK/OMEGA                  LONG 690
000069      B=T1BAR/GAMMA+U1BAR2/GAMMA                         LONG 700
000070      C=2.0*U1BAR*C1BAR/GAMMA                         LONG 710
000071      D=1.0+ZETAL*ZK/OMEGA                           LONG 720
000072      PHI=OMEGA*ASTAR*(1.0-XX)                         LONG 730
000073      THETA=2.0*OMEGA*XX                               LONG 740
000074      SINPHI=SIN(PHI)                                 LONG 750
000075      COSPHI=COS(PHI)                                 LONG 760
000076      SINTH=SIN(THETA)                                LONG 770
000077      COSTH=COS(THETA)                                LONG 780
000078      CR=1.0+BRE*COSPHI-BIM*SINPHI                  LONG 790
000079      CI=BIM*COSPHI+BRF*SINPHI                     LONG 800
000080      DR=1.0-BRE*COSPHI+BIM*SINPHI                  LONG 810
000081      DI= -BIM*COSPHI-BRE*SINPHI                   LONG 820
000082      ER=1.0-COSTH                                  LONG 830
000083      EI= SINTH                                    LONG 840
000084      FR=1.0+COSTH                                 LONG 850
000085      FI=-SINTH                                  LONG 860
000086      CAPI=(FR/GAMMA)*(U1BAR*CR-C1BAR*DR)-(FI/GAMMA)*(U1BAR*CI-C1BAR*DI)  LONG 870
000087      1+(D*B-U1BAR*A)*(ER*CR-EI*CI)+(C1BAR*A-C*D)*(ER*DR-EI*DI)        LONG 880
000088      CAPJ=(FI/GAMMA)*(U1BAR*CR-C1BAR*DR)+(FR/GAMMA)*(U1BAR*CI-C1BAR*DI)  LONG 890
000089      1+(D*B-U1BAR*A)*(ER*CI+EI*CR)+(C1BAR*A-C*D)*(ER*DI+EI*DR)        LONG 900
000090      CAPK=FR*(B*CR-C*DR)-FI*(B*CI-C*DI)                LONG 910
000091      CAPL=FI*(B*CR-C*DR) +FR*(B*CI-C*DI)               LONG 920
000092      DENMN=CAPK*CAPK+CAPL*CAPL                         LONG 930
000093      CAPM=(CAPK*CAPI+CAPL*CAPJ)/DENMN                 LONG 940
000094      CAPN=(CAPK*CAPJ-CAPL*CAPI)/DENMN                 LONG 950
000095      SE=UL*GAMMA*(1.0+ZETAL-ZETA1B)                  LONG 960
000096      T=.5*(CAPM*CAPM+CAPN*CAPN)/CAPM                 LONG 970
000097      ZN=T/SE                                         LONG 980
000098      COSOD=1.0-CAPM/T                                LONG 990
000099      SINOD = CAPN /T                                LONG1000
000100      OMDL = ATAN(SINOD/COSOD)                         LONG1010
000101      IF (SINOD) 80,110,110                            LONG1020
000102      80 IF (COSOD) 100,100,90                          LONG1030
000103      90 OMDL=6.2831853+OMDL                         LONG1040
000104      GO TO 120                                         LONG1050
000105      100 OMDL=3.1415927+OMDEL                      LONG1060
000106      GO TO 120                                         LONG1070
000107      110 IF (COSOD) 100,120,120                      LONG1080
000108      120 DELTA=OMDL/OMEGA                           LONG1090
000109      C      NON-DIMENSIONALIZED RESULTS             LONG1100
000110      TAUMS = DELTA*ELCH/SOUND*83.333333            LONG1110
000111      FREQ = OMEGA*SOUND/ELCH*12.0/6.2831853       LONG1120
000112      WRITE (6,10)  FREQ, OMEGA, TAUMS, ZN           LONG1130
000113      130 CONTINUE                                     LONG1140
000114      RETURN                                         LONG1150

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Report 20672-P2D

000115

F N)

1.0NC1160


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000056      180 HTIINT(41) = 0.0          NTAU 560
000057      HTRINT(41)=0.0           NTAU 570
000058      XN(41)=0.0              NTAU 580
000059      OMX(41)=0.0             NTAU 590
000060      FCCPSS(41)=0.0            NTAU 600
000061      190 FORMAT(36X,5HNMIN=,F10.5,/36X,8HTAU(MS)=,F10.5,/36X,9H(OMEGA)D=,F1NTAU 610
000062      10.5,/36X,8HFC(CPS)=,F10.1,)   NTAU 620
000063      DO 200 I =1,40                NTAU 630
000064      200 CALL INT4D(OMX(1),XN(1),OMX(I),SAVNOT,XNNEW(I))  NTAU 640
000065      XNNEW(41)=0.0               NTAU 650
000066      CALL INT4(XNNEW(1),OMX(1),0.0,DOMMIN)  NTAU 660
000067      FCMIN=CONST*DOMMIN        NTAU 670
000068      CALL INT4(FCCPSS(1),HTRINT(1),FCMIN,HTR1)  NTAU 680
000069      CALL INT4(FCCPSS(1),HTIINT(1),FCMIN,HTI1)  NTAU 690
000070      HTRMIN=(HTR1*HTR1+HTI1*HTI1)/(2.0*HTR1)  NTAU 700
000071      DNOM=HTRMIN-HTR1         NTAU 710
000072      CALL QUAD(DNOM,HTI1,TAUMIN)  NTAU 720
000073      TAUMIN=(TAUMIN*A(1)*83.33333)/(A(2)*DOMMIN)  NTAU 730
000074      CALL PAGE (8)            NTAU 740
000075      WRITE (6,210)            NTAU 750
000076      210 FORMAT(//21X,58H THE FOLLOWING ARE VALUES INTERPOLATED AT SLOPE OF NTAU 760
000077      1. N=0.0                 ,/)    NTAU 770
000078      WRITE (6,190)HTRMIN,TAUMIN,DOMMIN,FCMIN       NTAU 780
000079      220 RETURN              NTAU 790
000080      END                      NTAU 800

```

@ ELT SUB15,1,690702, 39149

000001	SUBROUTINE QUAD (A,B,ANGLE)	
000002	IF(B) 10,50,80	QUAD 10
000003	10 IF(A) 20,30,40	QUAD 20
000004	20 ROTATE = 3.1415927	QUAD 30
000005	GO TO 110	QUAD 40
000006	30 ANGLE = 4.7123890	QUAD 50
000007	GO TO 120	QUAD 60
000008	40 ROTATE = 6.2831853	QUAD 70
000009	GO TO 110	QUAD 80
000010	50 IF (A) 60,70,76	QUAD 90
000011	60 ANGLE = 3.1415927	QUAD 100
000012	GO TO 120	QUAD 110
000013	70 ANGLE = 0.0	QUAD 120
000014	GO TO 120	QUAD 130
000015	80 IF(A) 20,90,100	QUAD 140
000016	90 ANGLE = 1.5707963	QUAD 150
000017	GO TO 120	QUAD 160
000018	100 ROTATE = 0.0	QUAD 170
000019	110 ANGLE = ATAN(B/A) + ROTATE	QUAD 180
000020	120 RETURN	QUAD 190
000021	END	QUAD 200
		QUAD 210

@ ELT SUB16,1,690702, 39150

```
600001      SUBROUTINE CORE(X,N,CODE)
000002      DIMENSION X(1)
000003      IF(CODE=500.0)40,10,10
000004      CODE=100.0
10      CALL PAGE(70)
000005      WRITE(6,20)
20      FORMAT(10X,37HINPUT DATA DUMP FOR PROGRAM FAILIER
          //)
000006      WRITE(6,20)
000007      20 FORMAT(10X,37HINPUT DATA DUMP FOR PROGRAM FAILIER
          //)
000008      WRITE(6,30)(X(I),I=1,N)
000009      30 FORMAT(5X,10(F10.4,2X))
000010      40 RETURN
000011      END
```

```

000001      SUBROUTINE  INJECTR
000002      C           COMMON /PROLOG/ LOGIK(38), HEAD(12), SL1, SL2, EOR
000003      COMMON /JECTOR/ EJDATA( 9600)
000004      C           EQUIVALENCE (LOGIK(5),ERUN) , (LOGIK(10),JRUN) , (LOGIK(9),IRUN)
000005      LOGICAL LOGIK, ERUN, JRUN, SL1, SL2, EOR, IRUN
000006      DIMENSION HEAD1(12)
000007
000008
000009      C           IF ( SL1 )          GO TO 20
000010      DO 10 I = 1, 9600
000011      10   EJDATA(I) = 6.0
000012      SL1 = .TRUE.
000013      GO TO 30
000014
000015      C           READ (13) EJDATA
000016      BACKSPACE 13
000017
000018      30   CALL AS138 ( EJDATA, HEAD1, NE )
000019      IF ( NE .NE. 1 )      CALL EXIT
000020      WRITE (13) EJDATA
000021      BACKSPACE 13
000022      IF ( .NOT. JRUN )    GO TO 40
000023      CALL JJJ
000024      40   IF ( ERUN .OR. IRUN )  CALL INJDIS
000025
000026
000027      C           50 RETURN
000028      END

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@ ELT SUB18,1,690708, 48741

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000001      SUBROUTINE JJJ                                JECD  10
000002      C
000003      C ***** DECK MODIFIED 20 AUG 67 *****        JECD  20
000004      C
000005      DIMENSION THET1(1450), R1(1450), TMU(1000)    JECD  50
000006      DIMENSION NELE(1000), X(1000), Y(1000), NTYPEE(1000), R(22)JECD  60
000007      1, THETA(182), AS(20), WTE(1000), AAX(1000), AAF(1000), NBAND(1000), XMRE(JECD  70
000008      21000), XMUTOT(20), AXTY(200), AFY(200), XX(1000), YY(1000)    JECD  80
000009      COMMON /JECTOR/ DATA ( 9600)                JECD  90
000010      C
000011      EQUIVALENCE (DATA(3),XM), (DATA(4),XN)        JECD 130
000012      EQUIVALENCE (DATA(1021),THET1), (DATA(2471),R1), (DATA(3921),TMU)  JECD 140
000013      EQUIVALENCE (NTYPEE,DATA(2001)), (AXTY,DATA(1001)), (AFY,DATA(1201))JECD 150
000014      1), (DATA(1921),XX), (DATA(2921),YY), (DATA(4921),XMUTOT)  JECD 160
000015      C
000016      NERROR=0                                     JECD 170
000017      SECT=DATA(5)                                 JECD 180
000018      WT=DATA(9573)                               JECD 200
000019      RINJ=DATA(9574)                             JECD 210
000020      XMR=DATA(9575)                             JECD 220
000021      FFC=DATA(9576)                            JECD 230
000022      DFFC=DATA(9577)                           JECD 240
000023      NT=DATA(9570)+.0001                      JECD 250
000024      POLAR=DATA(9572)                          JECD 260
000025      NE=DATA(9571)+.0001                      JECD 270
000026      ROX=DATA(9579)                           JECD 280
000027      ROF=DATA(9580)                           JECD 290
000028      EMUMAX=5.0                                JECD 300
000029      PXADJ=1.0                                 JECD 310
000030      PFADJ=1.0                                 JECD 320
000031      CDX=DATA(9585)                            JECD 330
000032      CDF=DATA(9586)                            JECD 340
000033      XFC=DATA(9591)                            JECD 350
000034      DXFC=DATA(9592)                           JECD 360
000035      PFFC = DATA(9589)/100.0                  JECD 370
000036      PXFC = DATA(9590)/100.0                  JECD 380
000037      IF (XM .EQ. 0.0 ) XM = 20.0               JECD 390
000038      IF ( XN .EQ. 0.0 ) XN = 180.0             JECD 400
000039      10 K=319
000040      THFNL=6.2831853/SECT                      JECD 410
000041      IF(DATA(322))20,30,30                   JECD 420
000042      20 ROTATE=3.1415926/SECT                 JECD 430
000043      GO TO 40
000044      30 ROTATE=0.0                            JECD 440
000045      40 IF(POLAR)50,180,50                   JECD 450
000046      50 IF(SECT-1.0)80,80,60                 JECD 460
000047      60 DO 70 I=1,NE
000048      KK=K+1
000049      NELE(I)=DATA(KK)+.0001                  JECD 470
000050      X(I)=DATA(KK+1)
000051      Y(I)=DATA(KK+2)
000052      NTYPEE(I)=DATA(KK+3)+.0001              JECD 480
000053      SAVE=SQRT(X(I)*X(I)+Y(I)*Y(I))
000054      Y(I)=(ATAN(Y(I)/X(I)))+ROTATE          JECD 490
000055      X(I)=SAVE                                JECD 500

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000174      400 IF(DXFC)420,420,410                               JECT1780
000175      410 AXFC=XFC*.785398*DXFC*DXFC                JECT1790
000176          AXTMIN=AXTMIN-AXFC                           JECT1800
000177          AXTMAX=AXTMAX-AXFC                           JECT1810
000178      420 AXNOM=(AXTMAX+AXTMIN)/2.0                  JECT1820
000179          AFNOM=(AFTMAX+AFTMIN)/2.0                  JECT1830
000180          IF(DFFC+DXFC)440,440,430                  JECT1840
000181      430 WXT2=(WXT2*AXNOM)/(AXNOM+AXFC)            JECT1850
000182          WFT2=(WFT2*AFNOM)/(AFNOM+AFFC)            JECT1860
000183      440 XMR1=WXT2/WFT2                            JECT1870
000184          ETOF=0.0                                 JECT1880
000185          ETFF=0.0                                 JECT1890
000186          QX=WXT2/AXTOT                           JECT1900
000187          QF=WFT2/AFTOT                           JECT1910
000188          CALL DVCHK (K000FX)                      JECT1920
000189      460 DO 480 I=1,NE                            JECT1940
000190          NBAND(I)=0                                JECT1950
000191          WFE1=AAC(I)*QF                           JECT1960
000192          WXE1=AAX(I)*QX                           JECT1970
000193          WTE(I)=WFE1+WXE1                         JECT1980
000194          XMRE(I)=WXE1/WFE1                         JECT1990
000195          ETOF=ETOFO+WXE1                         JECT2000
000196          ETFF=ETFF+WFE1                         JECT2010
000197          CALL DVCHK (K000FX)                      JECT2020
000198          GO TO (470,480),K000FX                  JECT2030
000199      470 NBAND(I)=-1                            JECT2040
000200      480 CONTINUE                                JECT2050
000201          ETOF=SECT*ETOFO                         JECT2060
000202          ETFF=SECT*ETFF                          JECT2070
000203          WMRELM=ETOFO/ETFF                        JECT2080
000204          AXXTT=AXTOT+AXFC                         JECT2090
000205          AFFTT=AFTOT+AFFC                         JECT2100
000206          WFT2 = ETFF                            JECT2110
000207          WXT2 = ETOF                            JECT2120
000208          WFT1=WFT2/(1.0-PFFC)                   JECT2130
000209          WXT1=WXT2/(1.0-PXFC)                   JECT2140
000210          WFT1 = WFT1*AFFTT/AFTOT                 JECT2150
000211          WXT1 = WXT1*AXXTT/AXTOT                 JECT2160
000212          XMRINJ=WXT1/WFT1                        JECT2170
000213          D=((WXT1/(CDX*AXXTT))**2)*2.2360248   JECT2180
000214          WTOT=WXT1+WFT1                        JECT2190
000215          DPX1=D/ROX                            JECT2200
000216          D=((WFT1/(CDF*AFFTT))**2)*2.2360248   JECT2210
000217          DPF1=D/ROF                            JECT2220
000218          TOFCF = WXT1*(1.0 - PXFC)              JECT2230
000219          TOFCF = (TOFCF*(AXXTT - AXFC))/AXXTT    JECT2240
000220          TOFCF = WXT1 - TOFCF                     JECT2250
000221          TFFC = WFT1*(1.0 - PFFC)               JECT2260
000222          TFFC = (TFFC*(AFFTT - AFFC))/AFFTT     JECT2270
000223          TFFC = WFT1 - TFFC                     JECT2280
000224          VINJX=SORT((9273.6*DPX1 /ROX))        JECT2290
000225          VINJF=SORT((9273.6*DPPF1 /ROF))       JECT2300
000226          XXY=TPS*SIGMEN*SECT                     JECT2310
000227      490 WRITE (6,820)                          JECT2320
000228          GO TO 500                            JECT2330
000229      500 WRITE (6,760)AXTOT,AFTOT,AXFC,AFFC,AXXTT,AFFTT,DPX1,DPF1   JECT2340
000230          WRITE (6,770)WTOT,WMRELM,XMRINJ,ETOFO,ETOFF,TOFCF,TFFC,WXT1,WFT1,JECT2350
000231          1VINJX,VINJF                           JECT2360
000232          PFFC=PFFC*100.0                         JECT2370

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000233      PXFC=PXFC*100.0          JECT2380
000234      510 WRITE (6,830)WT,NT,NE,CDX  JECT2390
000235      WRITE (6,780)CDF,PFFC,PXFC,DFFC,DXFC,FFC,XFC,ROX,ROF  JECT2400
000236      CALL PAGE(70)           JECT2410
000237      WRITE (6,810)           JECT2420
000238      NPGE=49               JECT2430
000239      DO 540 I=1,NE          JECT2440
000240      1F(NPGE-I)520,520,530  JECT2450
000241      520 CALL PAGE(70)       JECT2460
000242      NPGE=NPGE+48          JECT2470
000243      WRITE (6,810)           JECT2480
000244      530 DEGREE=Y(I)/.0174532  JECT2490
000245      B=X(I)*SIN(Y(I))     JECT2500
000246      A=X(I)*COS(Y(I))     JECT2510
000247      WRITE (6,800)NELE(I),NTYPEE(I),X(I),DEGREE,A,B  JECT2520
000248      540 CONTINUE            JECT2530
000249      CALL PAGE(70)         JECT2540
000250      NPGE=46               JECT2550
000251      JCINT=0                JECT2560
000252      WRITE (6,840)           JECT2570
000253      NN=4944              JECT2580
000254      DO 570 I=1,NT          JECT2590
000255      KK=NN+1              JECT2600
000256      NST=DATA(KK)+.0001   JECT2610
000257      KK1=KK+1              JECT2620
000258      JJ=KK1                JECT2630
000259      NX=DATA(KK1)+.0001   JECT2640
000260      JCINT=JCINT+NX+1    JECT2650
000261      1F(NPGE-JCINT)550,550,560  JECT2660
000262      550 CALL PAGE(70)       JECT2670
000263      WRITE (6,840)           JECT2680
000264      JCINT=0                JECT2690
000265      560 AXMAX=0.0          JECT2700
000266      AFMAX=0.0             JECT2710
000267      WFE1=0.0              JECT2720
000268      WXE1=0.0              JECT2730
000269      WRITE (6,850)NST,NX   JECT2740
000270      1F(NX)570,590,570    JECT2750
000271      570 DO 580 JX=1,NX      JECT2760
000272      JJ=KK1+JX              JECT2770
000273      A=.7853891*DATA(JJ)*DATA(JJ)  JECT2780
000274      B=A*QX                JECT2790
000275      WRITE (6,860)DATA(JJ),A,B  JECT2800
000276      AXMAX=AXMAX+A        JECT2810
000277      WXE1=WXE1+B          JECT2820
000278      580 CONTINUE            JECT2830
000279      590 NN1=JJ+1            JECT2840
000280      NN=NN1                JECT2850
000281      NF=DATA(NN1)+.0001   JECT2860
000282      JCINT=JCINT+NF+2    JECT2870
000283      1F(NPGE-JCINT)600,600,610  JECT2880
000284      600 CALL PAGE (70)   JECT2890
000285      WRITE (6,840)           JECT2900
000286      JCINT=0                JECT2910
000287      610 WRITE (6,870)NF    JECT2920
000288      1F(NF)620,640,620    JECT2930
000289      620 DO 630 JF=1,NF      JECT2940
000290      NN=NN1+JF              JECT2950
000291      A=.7853891*DATA(NN)*DATA(NN)  JECT2960

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000292      B=A*QF                                JECT2970
000293      WRITE (6,880) DATA(NN),A,B           JECT2980
000294      AFMAX=AFMAX+A                      JECT2990
000295      WFE1=WFE1+B                      JECT3000
000296 630  CONTINUE                           JECT3010
000297 640  WTOT1=WXE1+WFE1                  JECT3020
000298      IF(WFE1)>650,650,660                JECT3030
000299 650  WRITE (6,900) AXMAX,AFMAX,WTOT1   JECT3040
000300      GO TO 670                            JECT3050
000301 660  XMR1=WXE1/WFE1                  JECT3060
000302      WRITE (6,890) AXMAX,AFMAX,WTOT1,XMR1 JECT3070
000303 670  CONTINUE                           JECT3080
000304 680  READ (13)  DATA                     JECT3090
000305      BACKSPACE 13                      JECT3100
000306      LINKNT = 0                         JECT3110
000307      AJS = XM*XN/WT                      JECT3120
000308      DO 700 J = 1,NE                      JECT3130
000309      TMU(J) = WTE(J)*AJS                JECT3140
000310      IF (LINKNT .GT. 0) GO TO 690        JECT3150
000311      CALL PAGE(70)                      JECT3160
000312      WRITE (6,910)                      JECT3170
000313      WRITE (6,930)                      JECT3180
000314      LINKNT = 50                        JECT3190
000315 690  WRITE(6,920) J, X(J), Y(J), TMU(J) JECT3200
000316      LINKNT = LINKNT - 1                JECT3210
000317 700  CONTINUE                           JECT3220
000318      DO 705 I = 1, NE                    JECT3222
000319      XX(I) = X(I)                      JECT3224
000320 705  YY(I) = Y(I)                      JECT3225
000321      WRITE (13)  DATA                     JECT3230
000322      BACKSPACE 13                      JECT3240
000323      XMUMAX=0.0                        JECT3250
000324      AJS = AJS*AECT/XN                 JECT3260
000325      DO 730 J=1,20                      JECT3270
000326      TOTW=0.0                          JECT3280
000327      XXX = XXX * AECT                  JECT3290
000328      DO 710 I=1,NE                      JECT3310***-1
000329      IF (X(I) .LE. R(J+1) .AND. X(I) .GT. R(J)) TOTW = TOTW + WTE(I) JECT3320
000330 710  CONTINUE                           JECT3330
000331      XMUTOT(J) = TOTW*AJS                JECT3340
000332      IF(XMUTOT(J)-XMUMAX)>730,730,720 JECT3350
000333 720  XMUMAX=XMUTOT(J)                  JECT3360
000334 730  CONTINUE                           JECT3370
000335      CALL PAGE(70)                      JECT3380
000336      WRITE (6,790)                      JECT3390
000337      DO 740 J=1,20                      JECT3400
000338      XXMAX=XMUTOT(J)/XMUMAX            JECT3410
000339      WRITE (6,750)R(J+1),XMUTOT(J),XXMAX JECT3420
000340 740  CONTINUE                           JECT3430
000341      RETURN                               JECT3440
000342 750  FORMAT(32X,F6.3,14X,F7.3,13X,F6.4) JECT3450
000343 760  FORMAT(//,5X,28H...,PROPELLENT ORFICE AREAS,/,9X,34HELEMENT TOTAL) JECT3460
000344      1L OXIDIZER AREA      =,F11.8,8H SQ. IN.,15X,30HELEMENT TOTAL FUEL JECT3470
000345      2AREA      =,F11.8,8H SQ. IN.,/,9X,34HTOTAL OXIDIZER FILM COOLING AJECT3480
000346      3REA =,F11.8,8H SQ. IN.,15X,30HTOTAL FUEL FILM COOLING AREA =,F11.8,8H EJECT3490
000347      4,8H SQ. IN.,/,9X,34HINJECTOR TOTAL OXIDIZER AREA      =,F11.8,8H SQ EJECT3500
000348      5. IN.,15X,30HINJECTOR TOTAL FUEL AREA      =,F11.8,8H SQ. IN.,/,5X EJECT3510
000349      6,54HB....INJECTOR PRESSURE DROPS FOR ABOVE INJECTOR DESIGN,/,9X, JECT3520
000350      724HOXIDIZER PRESSURE DROP =,F6.1,3HPSI,35X,20HFUEL PRESSURE DROP =EJECT3530

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@ ELT SUB19,1,691029, 58811

000001      SUBROUTINE INJDIS                      INJD 10
000002      C
000003      C **** DECK MODIFIED 20 AUG 67 ****          INJD 20
000004      C
000005      REAL IPP,IPR,IPT,INTEG,IPX                INJD 30
000006      INTEGER DSCRB, TIME                     INJD 40
000007      LOGICAL LOGIK, SL1, SL2, EORJ, IRUN       INJD 50
000008      COMMON /PROLOG/ LOGIK(50), SL1, SL2, EORJ   INJD 60
000009      COMMON /JECTOR/ DATA ( 9600)               INJD 70
000010      COMMON GAMMA, NW, WC, AVN, BVN, CVNR, CVNI, CE, CI INJD 80
000011      DIMENSION
000012      U (1000), AVN ( 30), BVN ( 30), CVNR ( 30), INJD 90
000013      CVNI ( 30), RR (1000), THATA (1000), FIRST ( 30), INJD 110
000014      SECOND( 30), Z ( 2), WC ( 30), INJD 120
000015      IPP(50), OPP(50), IPR(50), OPR(50), IPT(50), OPT(50), INJD 130
000016      X (1000), Y (1000)                         INJD 140
000017      EQUIVALENCE ( IRUN, LOGIK(9) ),             INJD 150
000018      (E1 ,DATA(1)), (XM ,DATA(3)),              INJD 160
000019      (XN ,DATA(4)),(V ,DATA(6)),(SVN ,DATA(8)), INJD 170
000020      (POO ,DATA(13)), (Z1 ,DATA(15)),           INJD 180
000021      (RR, X, DATA(1921) ),(THATA, Y, DATA(2921)), INJD 190
000022      (U ,DATA(3921)),                          INJD 200
000023      (IPP ,DATA(20)),                         INJD 210
000024      (OPP ,DATA(70)),(IPR ,DATA(120)), (OPR ,DATA(170)), INJD 220
000025      (IPT ,DATA(220)),(OPT ,DATA(270)),(TFLP,DATA(9596)), INJD 230
000026      (TFLR,DATA(9597)),(TFLT,DATA(9598))        INJD 240
000027      C                                         INJD 250
000028      10 FORMAT (/12X30HRESULTS OF DESCRIBING FUNCTION // 23X10HELEMENT INJD 260
000029      1 6HRADIUS4X5HANGLE3X10HFRACTIONAL /13X5HOMEGA7X3HNO.7X3H 7X3HRADINJD 270
000030      2 4X9HFLOW-RATE10X2HFP12X2HFR12X2HFT // )     INJD 280
000031      20 FORMAT (10XF9.4,I9,F11.3,F10.4,F11.5,2X3F14.6 ) INJD 290
000032      30 FORMAT (/ 12X41HRESULTS OF INJECTION DISTRIBUTION EFFECTS // INJD 300
000033      143X5HOMEGA6X3HAVN8X3H8VN7X3HCVN7X3HCVN / 48X3(6X4HREAL),6X4HIMAG/ INJD 310
000034      2/ )                                         INJD 320
000035      40 FORMAT (39X5F10.4 )                         INJD 330
000036      50 FORMAT ( 44X5HALL 4F10.4 )                  INJD 340
000037      60 FORMAT ( // 5X39HINPUT TO INJECTION DISTRIBUTION PROGRAM//10X9HCONINJD 350
000038      1STANTS//14X18HNUMBER OF OMEGAS = I3//14X20HNUMBER OF ELEMENTS =I5,INJD 360
000039      1 13H FOR EACH OF 14, 20H SYMMETRIC SECTIONS.      INJD 370
000040      2//14X22HRADIAL DIVISIONS(XM) = F5.0//14X24HANGULAR DIVISIONS (XN) INJD 380
000041      3=F5.0//14X27HACOUSTIC MODE NUMBER(SVN) =F7.4//14X30HORDER OF BESSIEINJD 390
000042      4L FUNCTIONS(V) = F3.0//14X17HINJECTOR RADIUS =F8.3,5H, IN./14X32HINJD 400
000043      5RATIO OF SPECIFIC HEATS(GAMMA) =F7.4//14X39HMAXIMUM PRESSURE AMPLITINJD 410
000044      6TUDERATIO(POO) =F7.3///14X39HTRANSFER FUNCTIONS FOR LINEAR OPERATINJD 420
000045      7ION//20X16HPRESSURE(TFLP) =F7.3//20X23HRADIAL VELOCITY(TFLR) =F7.3INJD 430
000046      8//20X27HTANGENTIAL VELOCITY(TFLT) =F7.3 )          INJD 440
000047      70 FORMAT ( // 10X17HINPUT FREQUENCIES )            INJD 450
000048      80 FORMAT ( / 7X 5F20.4 )                         INJD 460
000049      90 FORMAT (//10X19HELEMENT INFORMATION )           INJD 470
000050      100 FORMAT (//31X/HELEMENT14X6HRADIUS15X5HANGLE11X12HDISTRIBUTION/9UX INJD 480
000051      111HCOEFFICIENT/34X3HNO.17X3HIN.15X7HRA11ANS15X2H4U// )    INJD 490
000052      110 FORMAT (32XI5,11XF10.3,10XF10.4,11XF10.4 )          INJD 500
000053      120 FORMAT (1H1//26H TABULAR NONLINEAR EFFECTS//11X8HPRESSURE11X10HCOMINJD 510
000054      1BUSTION12X6HRADIAL12X10HCOMBUSTION10X10HTANGENT14L1UX10HCOMBUSTIONINJD 520
000055      2/51X8HVELOCITY32X8HVELOCITY/ 9X 3(12HPERTURBATION13X4HGAIN12X) ) INJD 530

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130 FORMAT ( 6(F18.3,2X) ) THESE VALUES PERTAIN TO A STANDING MOINJD 560
140 FORMAT (//33X69***** ) INJD 570
1DE ****      ) INJD 580
150 FORMAT (//33X69***** ) THESE VALUES PERTAIN TO A SPINNING MOINJD 590
1DE ****      ) INJD 590
160 FORMAT (23X42HTHE VALUE OF IZZIT IS ZERO AND NOT ALLOWED) INJD 600
170 FORMAT (23X45HVALUE OF BESEL ARGUMENT TOO HIGH OR LOW Z = F10.4) INJD 620
INJD 620
INJD 630
INJD 640
INJD 650
INJD 660
INJD 670
INJD 680
INJD 690
INJD 700
INJD 710
INJD 720
INJD 730
INJD 731
INJD 740
INJD 750
INJD 760
INJD 770

C 180 DSCRIB = 1 GU 16, 190
IF ( .NOT. IRUN )
CE = 100.0
DSCRIB = 2
GO TO 200
190 NW = 1
WC(1) = 1.0
200 TIME = 1
RINJ = DATA(9574)
NE = DATA(9571) + 0.0001
NS = DATA(5) + 0.0001
NUMBR = DATA(9599) + 0.0001
IZZIT = DATA(2)
K = V + 0.0001
KK = K + 1
L=K
M=L+1
N=L+2
C ONLY THE REAL PART IS USED.
IF ( E1.LE. 0.0 ) E1 = 0.0001
IF ( NUMBR .LE. 0 ) NUMBR = 10
IF ( CE.LE. 99.0 ) GO TO 260
CALL PAGE ( 70 )
WRITE (6,60) NW,NE,NS,XM,XN,SVN,V,RINJ,GAMMA,P00,TFLR,TFLT
WRITE (6,60) (WC(IW), 1W = 1,NW)
GO TO (220,210), DSCRIB
210 WRITE (6,70)
WRITE (6,80) (WC(IW), 1W = 1,NW)
220 LINKNT = 0
DO 240 J = 1,NE
IF (LINKNT .GT. 0) GO TO 230
CALL PAGE ( 70 )
WRITE (6,90)
WRITE (6,100)
LINKNT = 50
230 WRITE (6,110) J, RR(J), THATA(J), U(J)
LINKNT = LINKNT - 1
240 CONTINUE
GO TO (260,250), DSCRIB
250 WRITE (6,120)
WRITE (6,130) (IPP(1),OPP(1),IPR(1),IPT(1),OPT(1),I,1,50)
INJD1000
INJD1000
INJD1020
INJD1020
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INJD1080
INJD1080
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INJD1090
INJD1100
INJD1100
INJD1110
INJD1110
INJD1120
INJD1120

CXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXINJD1020
C RUNNING DESCRIBING FUNCTION IMPLIES THAT THE EXPANSION
C COEFFICIENTS AVN, BVN, AND CVN ARE FUNCTIONS OF THE FREQUENCY, OMEGA. INJD1040
C THEREFORE, AN OMEGA LOOP MUST BE ESTABLISHED. OTHERWISE, THIS LOOP
C IS GONE THROUGH ONLY ONCE.
CXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXINJD1070
260 DO 470 1W = 1, NW
WCR = WC(IW)
V00 = P00/(GAMMA*WCR)
SUMP = 0.0
SUMR = 0.0

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000115          SUMT = 0.0                                INJD1130
000116          LLINKT = 0                                INJD1140
000117          DO = 450, J = 1, NE                      INJD1150
000118          R = RR(J)/RINJ                           INJD1160
000119          ETA = U(J)/(XMXZN)                         INJD1170
C***** THE ANSWERS WILL BE
C STORED IN THE FOLLOWING FASHION,   J(V-1) = FIRST(L),   J(V) =
C FIRST(M), AND J(V+1) = FIRST(N).
C***** KERR = 0                                         *****
000121          Z(1) = SVN*R                            INJD1270
000122          Z(2) = 0.0                                INJD1280
000123          CALL BESEL ( FIRST(1), SECOND(1), KK, Z(1), KERR )  INJD1290
000124          IF ( KERR )    270,270,550                INJD1300
000125          SIVN = FIRST(M)                           INJD1310
000126          DSIVN = ( V*FIRST(M) - Z(1)*FIRST(N) )/R INJD1320
000127          Z(1) = SVN                                INJD1330
000128          Z(2) = 0.0                                INJD1340
000129          CALL BESEL ( FIRST(1), SECOND(1), KK, Z(1), KERR )  INJD1350
000130          IF ( KERR )    280,280,550                INJD1360
000131          Z(1) = SVN                                INJD1370
000132          Z(2) = 0.0                                INJD1380
000133          CALL BESEL ( FIRST(1), SECOND(1), KK, Z(1), KERR )  INJD1390
000134          IF ( KERR )    280,280,550                INJD1400
000135          GO TO (290,320), TIME                   INJD1410
000136          IF ( K )      300,300,310                INJD1420
000137          290, ( FIRST(M)*FIRST(M) + FIRST(L)*FIRST(L) ) / 2.0 INJD1430
000138          300, D = ( FIRST(M)*FIRST(M) - FIRST(L)*FIRST(N) )*3.14159/(2.0*DATA(5)) INJD1440
000139          GO TO 320                                INJD1450
000140          310, D = ( FIRST(M)*FIRST(M) - FIRST(L)*FIRST(N) )*3.14159/(2.0*DATA(5)) INJD1460
000141          320, IF ( IZIT )    330,560,340               INJD1470
000142          C IZIT IS NEGATIVE FOR STANDING MODES AND POSITIVE FOR SPINNING MODES INJD1480
000143          330, VT = V*THATA(J)                         INJD1490
000144          VT = COS(VT)                            INJD1490
000145          SVT = SIN(VT)                            INJD1490
000146          GO TO 350                                INJD1490
000147          340, CVT = 1.0                                INJD1500
000148          340, CVT = 1.0                                INJD1510
000149          340, SVT = 1.0                                INJD1520
000150          350, FP = 1.0                                INJD1530
000151          350, FR = 1.0                                INJD1540
000152          350, FT = 1.0                                INJD1550
000153          360, GO TO (420,360), DSCR8           INJD1560
000154          360, PO = ABS(P00*SIVN*CVT)            INJD1570
000155          360, VO = ABS(V00*DSIVN*CVT)            INJD1580
000156          360, WO = ABS(V00*SIVN*SVT/R)            INJD1590
000157          371, A = -3.14159                          INJD1600
000158          371, B = -A                                INJD1610
000159          371, CONTINUE                            INJD1620
000160          371, IF ( TFLP )    370,380,370             INJD1630
000161          370, SAVEP = 1.0/(3.14159*PO*TFLP)        INJD1640
000162          CALL INT4(IPP1), OPP1, IPX, OPX           INJD1650
000163          371, PSI = CCS(PSI)                         INJD1660
000164          371, IPX = P0*CPSI                        INJD1670
000165          371, CALL INT4(IPP1), OPP1, IPX, OPX           INJD1680
000166          371, F = QPX*CPSI                         INJD1690
000167          371, CALL INTG($371,F,INTEG,E1,MM)        INJD1700
000168          371, PSI = SAVEP*INTEG                  INJD1710
000169          371, IF ( TFLP )    390,400,390             INJD1720
000170          390, SAVER = 1.0/(3.14159*VO*TFLP)        INJD1730
000171          390, CALL INTG(A,B,PSI,NUMER)            INJD1740
000172          390, CONTINUE                            INJD1750
000173          390, CONTINUE                            INJD1760

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000174 CPSI = COS(PSI) I NJD1730
000175 IPX = V0*CPSI INJD1740
000176 CALL INT4(IPT(1), OPR(1), IPX, OPX) INJD1750
000177 F = OPX*CPSI INJD1760
000178 CALL INTGS($391,F,INTEG,E1,MM)
000179 FR = SAVER*INTEG INJD1780
000180 400 IF ( TFLT ) 410,420,410 INJD1790
000181 410 SAVET = 1.0/(3.14159*k0*TFLT) *NEW
000182 CALL INTGR(A,B,PSI,NUMBR) INJD1810**-1
000183 411 CONTINUE
000184 CPSI = COS(PSI) INJD1820
000185 IPX = W0*CPSI INJD1830
000186 CALL INT4(IPT(1), OPT(1), IPX, OPX) INJD1840
000187 F = OPX*CPSI INJD1850
000188 CALL INTGS($411,F,INTEG,E1,MM)
000189 FT = SAVER*INTEG INJD1870
000190 420 SUMP = ETA*FP*SIVN**2*CVT**2 INJD1880
000191 SUMP = SUMP + TERM P INJD1890
000192 TERM R = ETA*FR*SIVN*DSIVN*CVT**2 INJD1900
000193 SUMR = SUMR + TERM R INJD1910
000194 SUMT = -ETA*FT*SIVN**2*CVT*V*SVT/R INJD1920
000195 SUMT = SUMT + TERM T INJD1930
000196 TIME = 2 INJD1940
000197 GO TO (450,430), DSCRIB INJD1950
000198 430 IF ( LINKNT .GT. 0 ) GO TO 440 INJD1960
000199 000199 CALL PAGE ( 70 ) INJD1970
000200 WRITE (6,10) INJD1980
000201 LINKNT = 50 INJD1990
000202 440 WRITE (6,20) WCR, J, R, THATA(J), ETA, FP, FR, FT INJD2000
000203 LINKNT = LINKNT - 1 INJD2010
000204 450 CONTINUE INJD2020
000205 DD = D INJD2030
000206 IF (IZZIT .GT. 0) DD = D/2.0 INJD2040
000207 AVN(IW) = SUMP/DD INJD2050
000208 BVN(IW) = SUMR/DD INJD2060
000209 IF (IZZIT .GT. 0) GO TO 460 INJD2070
000210 CVNR(IW) = SUMT/DD INJD2080
000211 CVNI(IW) = 0.0 INJD2090
000212 GO TO 470 INJD2100
000213 460 CVNR(IW) = 0.0 INJD2110
000214 CVNI(IW) = SUMT/DD INJD2120
000215 470 CONTINUE INJD2130
000216 IF (CE .LT. 10.0 ) GO TO 530 INJD2140
000217 CALL PAGE ( 70 ) INJD2150
000218 WRITE (6,30) INJD2160
000219 GO TO (480,490), DSCRIB INJD2170
000220 480 WRITE (6,50) AVN(1), BVN(1), CVNR(1), CVNI(1) INJD2180
000221 GO TO 500 INJD2190
000222 490 WRITE (6,40) ( WC(1), AVN(1), BVN(1), CVNR(1), CVNI(1), j=1,NW ) INJD2200
000223 500 IF ( IZZIT ) 510,560,520 INJD2210
000224 510 WRITE (6,140) INJD2220
000225 GO TO 530 INJD2230
000226 520 WRITE (6,150) INJD2240
000227 530 CONTINUE INJD2250
000228 540 RETURN INJD2260
000229 550 WRITE (6,170) Z(1.) INJD2270
000230 560 WRITE (6,160) INJD2280
000231 GO TO 540 INJD2290
000232 INJD2300

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Report 20672-P2D

INJD2310

END

000233

@ ELT SUB20,1,691029, 50052

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000001      SUBROUTINE TBLCAL          *NEW
000002      C TBLCAL SUBROUTINE CALCULATES XX VS U2TBL FROM NOZZLE GEOMETRY *ANNU0030**-1
000003      C SIMPSONS RULE IS USED WITH KN INPUT ODD AND CHANGED TO KN/2+1 IN MAIN*ANNU0040
000004      C DECK ANNULR DERIVED FROM DECK VELPOT... TREATS ANNULAR NOZZLES ANNU0050
000005      C
000006      LOGICAL LOGIK, SL1, SL2, EORJ ANNU0060
000007      COMMON /PROLOG/ LOGIK(50), SL1, SL2, EORJ ANNU0070
000008      C
000009      COMMON /ABCDF/ EXTRA(100), ABLOK(600) ANNU0080
000010      1 , XX , U2TBL , DESIRE , RAT , RAC , RCC ANNU0090
000011      2 , RCT , HANG , G , KN , Y , YP ANNU0100
000012      3 , YOUT , TEMP , E , XTABLE , YTABLE , A ANNU0110
000013      4 , R , AM , AP , AMP , ZZ , AMM ANNU0120
000014      5 , AMP2 , CALFA , CTALFA , DELAM , DELTZ , FKN ANNU0130
000015      6 , G1 , G2 , G3 , G4 , JFLAG1 , KNM1 ANNU0140
000016      7 , K , NN , PI , PROD , RSTA1 , RSTA2 ANNU0150
000017      8 , SALFA , T1 , T2 , T3 , XINT , XK ANNU0160
000018      9 , ZZ1 , ZZ2 , ZZ3 , A1 , ABC , ABD ANNU0170
000019      COMMON /ARCDF/
000020      1 AI1 , ALPHAI , ALPHAR , AR1 , B101 , B102 ANNU0180
000021      2 B10 , B1 , B2 , B3 , B4 , B5 ANNU0190
000022      3 B6 , B7 , B8 , B91 , B92 , B9 ANNU0200
000023      4 BI1 , BR1 , C2 , C3 , CHII , CHIR ANNU0210
000024      5 CI1 , CR1 , C , D10 , D11 , D1 ANNU0220
000025      6 D2 , D3 , D4 , D5 , D6 , D7 ANNU0230
000026      7 D8 , D9 , DC2 , D , DU2 , EI ANNU0240
000027      8 ER , F3I , F3R , FI , FR , HI ANNU0250
000028      9 H , I , IWO , IW , IWW , J ANNU0260
000029      COMMON /ABCDF/
000030      1 MDESIR , NK , NP , S2 , S , TT ANNU0270
000031      2 U2 , U , W2 , W , XI0I , XI0R ANNU0280
000032      3 XI2I , XI2R , XI , XJI , XJR , XMNEW ANNU0290
000033      4 XMOLD , XNEW , XOLD , XPT , X , ZI ANNU0300
000034      5 ZP ANNU0310
000035      C
000036      DIMENSION XX(200),U2TBL(200),XTABLE(200),YTABLE(200),ZZ(200) ANNU0320
000037      DIMENSION Y(8),YP(8),YOUT(8),TEMP(72),E(8) ANNU0330
000038      DIMENSION A(200),R(200),AM(200),AP(200),AMP(200) ANNU0340
000039      C
000040      EQUIVALENCE (XK,GRAD),(EXTRA(91),RATI), ANNU0400
000041      1 (EXTRA(93),RACI),(EXTRA(94),RCCI),(EXTRA(95),HANGI) ANNU0410
000042      C
000043      FKN = KN ANNU0420
000044      KNM1 = KN - 1 ANNU0430
000045      DELAM = 1.0/(FKN+1.0) ANNU0440
000046      PI = 3.1415927 ANNU0450
000047      C
000048      DO 10 J = 1,200 ANNU0460
000049      ZZ(J) = 0.0 ANNU0470
000050      A(J) = 0.0 ANNU0480
000051      R(J) = 0.0 ANNU0490
000052      AMP(J) = 0.0 ANNU0500
000053      AM(J) = 0.0 ANNU0510
000054      XX(J) = 0.0 ANNU0520
000055      U2TBL(J) = 0.0 ANNU0530

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000056      10 AP(J) = 0.0                               ANNU0570
000057      C                                         ANNU0580
000058      R(1)= RAT                                ANNU0590
000059      RI = R ATI                               ANNU0600
000060      RCTI = EXTRA(92)                           ANNU0610
000061      A(1) = PI*(R(1)*R(1)-RI*RI)             ANNU0620
000062      U2TBL(1)=1.0                             ANNU0630
000063      R(KN) = RAC                               ANNU0640
000064      ALFA = HANG*.01745329                  ANNU0650
000065      CALFA=COS(ALFA)                         ANNU0660
000066      SALFA=SIN(ALFA)                         ANNU0670
000067      CTALFA=CALFA/SALFA                      ANNU0680
000068      RSTA1=RAT+RCT*(1.0-CALFA)               ANNU0690
000069      RSTA2=RAC-RCC*(1.0-CALFA)               ANNU0700
000070      ZZ1=RCT*SALFA                          ANNU0710
000071      ZZ2=ZZ1+CTALFA*(RSTA2-RSTA1)            ANNU0720
000072      ZZ3=ZZ2+RCC*SALFA                      ANNU0730
000073      C                                         ANNU0740
000074      JFLAG1=1                               ANNU0750
000075      JFLAG2 = 1                             ANNU0760
000076      IF ( RACI .EQ. 0.0 .AND. R ATI .EQ. 0.0 ) JFLAG2 = 4 ANNU0770
000077      ALFI = HANGI*.01745329                ANNU0780
000078      CALFI = COS(ALFI)                      ANNU0790
000079      SALFI = SIN(ALFI)                      ANNU0800
000080      CTALFI = CALFI/SALFI                  ANNU0810
000081      RI1 = R ATI + RCTI*(1.0-CALFI)          ANNU0820
000082      RI2 = RACI - RCCI*(1.0-CALFI)          ANNU0830
000083      ZI1 = RCTI*SALFI                      ANNU0840
000084      ZI2 = ZI1 + CTALFI*(RI2-RI1)            ANNU0850
000085      ZI3 = ZI2 + RCCI*SALFI                 ANNU0860
000086      Z4 = ZZ3                               ANNU0870
000087      IF ( ZI3 .GT. ZZ3 )      Z4 = ZI3       ANNU0880
000088      DELTZ = Z4 / (FKN-1.0)                  ANNU0890
000089      C                                         ANNU0900
000090      DO 80 I = 2,KNM1                         ANNU0910
000091      ZZ(I) = ZZ(I-1) + DELTZ                 ANNU0920
000092      Z = ZZ(I)                               ANNU0930
000093      GO TO ( 20, 40, 60, 65 ), JFLAG1        ANNU0940
000094      20 R(I)=RAT+RCT-SQRT(RCT*#2-ZZ(I)**2)   ANNU0950
000095      IF(R(I)-RSTA1)70,70,30                  ANNU0960
000096      30 JFLAG1=2                            ANNU0970
000097      40 R(I)=RSTA1+(RSTA2-RSTA1)*(ZZ(I)-ZZ1)/(ZZ2-ZZ1) ANNU0980
000098      IF ( Z-ZZ2 )           70, 70, 50        ANNU0990
000099      50 JFLAG1 = 3                           ANNU1000
000100      60 IF ( Z-ZZ3 )           62, 65, 65        ANNU1010
000101      62 R(I) = RAC - RCC + SQRT ( RCC*RCC - (ZZ3-Z)**2 ) ANNU1020
000102      GO TO 70
000103      65 R(I) = RAC                           *NEW
000104      JFLAG1 = 4
000105      70 GO TO ( 72, 74, 76, 77 ), JFLAG2    ANNU1030
000106      72 TX = SQRT ( RCTI*RCTI - Z*Z )          ANNU1040
000107      IF ( RCTI .LT. 0.0 )      1X = -TX        ANNU1050
000108      RT = R ATI + RCTI - TX                  ANNU1060
000109      IF ( Z-ZI1 )           78, 78, 73        ANNU1070
000110      73 JFLAG2 = 2                           ANNU1080
000111      74 RI = RI1 + (RI2-RI1)*(ZZ(I)-ZI1)/(ZI2-ZI1) ANNU1090
000112      IF ( Z-ZI2 )           78, 78, 75        ANNU1100
000113      75 JFLAG2 = 3                           ANNU1110
000114      76 IX = SQRT ( RCCI*RCCI - ( ZI3-Z )**2 ) ANNU1120
                                         ANNU1130
                                         ANNU1140

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000115      IF ( RCCI .LT. 0.0 )    TX = -TX          ANNU1150
000116      RI = RACI - RCCI + TX          ANNU1160
000117      IF ( Z-ZI3 )           78, 77, 77          ANNU1170
000118      77 RI = RACI          ANNU1180
000119      JFLAG2 = 4          ANNU1190
000120      78 A(I) = PI*( R(I)*R(I) - RI*RI )          ANNU1200
000121      80 CONTINUE          ANNU1210
000122      C
000123          ZZ(KN) = ZZ(KNM1) + DELTZ          ANNU1220
000124          A(KN) = PI*( RAC*RAC - RACI*RACI )          ANNU1230
000125          AMM = 1.0+ DELAM          ANNU1240
000126          G1=2.0/(G +1.0)          ANNU1250
000127          G2 =(G + 1.0)/2.0          ANNU1260
000128          G3 = (G + 1.0)/(2.0*G - 2.0)          ANNU1270
000129          G4=1.0/G1          ANNU1280
000130          C
000131          DO 90 J = 1,KN          ANNU1290
000132          AMM = AMM - DELAM          ANNU1300
000133          AM(J) = AMM          ANNU1310
000134          AP(J)=(A(1)/AMM)*(G1*(1.0+G2*AMM**2))**G3          ANNU1320
000135          90 CONTINUE          ANNU1330
000136          C
000137          DO 100 K = 2,KN          ANNU1340
000138          CALL INT4(AP(1),AM(1),A(K),AMP(K))          ANNU1350
000139          AMP2=AMP(K)**2          ANNU1360
000140          U2TBL(K)=(G4*AMP2)/(1.0+G2*AMP2)          ANNU1370
000141          100 CONTINUE          ANNU1380
000142          C
000143          DESIRE = AMP(KN)          ANNU1390
000144          XINT = 0.0          ANNU1400
000145          NN = KN - 2          ANNU1410
000146          K = 1          ANNU1420
000147          IF ( RCTI .EQ. 0.0 )    RCTI = 1.0          ANNU1430
000148          GRAD = SQRT ( G1*(RAT/RCT - RATI/RCTI )/( RAT*RAT - RATI*RATI ) )          ANNU1440
000149          *NEW
000150          PROD = 2.0*XK*DELTZ/3.0          ANNU1450
000151          DO 110 J = 1,NN,2          ANNU1460
000152          T1 = SQRT(U2TBL(J))          ANNU1470
000153          T2 = SQRT(U2TBL(J+1))          ANNU1480
000154          T3 = SQRT(U2TBL(J+2))          ANNU1490
000155          XINT = XINT + PROD*(T1+4.0*T2+T3)          ANNU1500
000156          K = K + 1          ANNU1510
000157          XX(K) = -XINT/RAT          ANNU1520
000158          U2TBL(K-1) = U2TBL(J)          ANNU1530
000159          110 CONTINUE          ANNU1540
000160          U2TBL(K) = U2TBL(KN)          ANNU1550
000161          *****
000162          RETURN          ANNU1560
000163          END          ANNU1570

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@ EL1 SUB21,1,690714, 35957

000001      SUBROUTINE ADSET(N,F,D,FP,T,X,HA,E)
000002      DIMENSION F(1),D(1),FP(1),T(8,8),HA(1),E(1),AC(6,3),AD(10),AH(10)
000003      1.ACC(6)
000004      EQUIVALENCE (ACC(1),AC(13))
000005      DATA AC /0.,1.,.5,.416666,.375,.348611,.348611,.651389,.151389,
000006      1 .068056,.026389,0.,0.,0.,0.,0.,0./
000007      DATA AD /2.,-1.,0.,0.,4.,-4.,1.,8.,-12.,16./
000008      DATA AH /.5,.125,.0625,.0390625,.25,.125,.078125,.125,.09375,
000009      1 .0625/
000010      C
000011      **** THIS SUBROUTINE WILL INTEGRATE N DIFFERENTIAL EQUATIONS.
000012      **** THE CALLING SEQUENCE IS AS FOLLOWS.
000013      **** N IS THE NUMBER OF EQUATIONS
000014      **** F IS THE ARRAY OF FUNCTIONS
000015      **** D IS THE ARRAY OF DERIVATIVES OF THE FUNCTIONS F
000016      **** FP IS THE ARRAY OF THE PARTIAL STEP VALUES OF F AT X = TP
000017      **** T IS AN ARRAY OF 8*N WORDS
000018      **** HA IS EITHER AN ARRAY OR A SINGLE WORD
000019      **** IN EITHER CASE HA(1) IS THE INITIAL STEP SIZE GUESS
000020      **** IF THE ARRAY FEATURE IS USED THE FOLLOWING CONDITIONS HOLD.
000021      **** IF HA(2) IS EQUAL TO 1111 THEN STEP SIZE IS LIMITED
000022      **** HA(3) IS THE LOWEST VALE OF THE STEP SIZE ALLOWED
000023      **** HA(4) IS THE LARGEST VALUE OF THE STEP SIZE ALLOWED
000024      **** IF HA(2) IS EQUAL TO 2222 BOTH THE LIMIT AND THE CORRECTED
000025      **** DERIVATIVES ARE USED
000026      **** IF HA(2) IS EQUAL TO 3333 ONLY THE CORRECTED DERIVATIVES ARE USED
000027      **** IF HA(2) IS NOT DEFINED THEN NEITHER ARE USED
000028      KKF=0
000029      **** SET FOR NO RECAL OF DERIVATIVES
000030      HMIN=0.
000031      IF(HA(1).LT.0.) HMIN=-HMAX
000032      IF(HA(1).LT.0.) HMAX=0.
000033      HMAX=1.E30
000034      **** SET MAX-MIN STEP SIZE
000035      IF(HA(2).EQ.1111.) GO TO 400
000036      IF(HA(2).EQ.2222.) GO TO 401
000037      IF(HA(2).EQ.3333.) KKF=1
000038      403  GO TO 4
000039      400  HMIN=HA(3)
000040      HMAX=HA(4)
000041      GO TO 403
000042      401  KKF=1
000043      GO TO 400
000044      C
000045      C
000046      ENTRY ADINT
000047      IENT=1
000048      IDF=0
000049      IF(INT.EQ.0) GO TO 20
000050      21  KF=1
000051      X=X+H
000052      GO TO 100
000053      20  H=HA(1)
000054      GO 504 I=1,N
000055      506  IF(E(I).LT.1.E-9) E(I)=1.E-9

```

```

000056      504    CONTINUE
000057      520    IF(IENT.NE.0) RETURN
000058          RETURN1
000059          C
000060          ENTRY ADCOR(*)
000061          IENT=0
000062          2     IF(INT.EQ.0) GO TO 23
000063          22    IF(KKF.EQ.2) GO TO 34
000064          DO 41 I=1,N
000065          T(8,I)=F(I)
000066          41    T(1,I)=D(I)
000067          KF=2
000068          GO TO 100
000069          C
000070          23    INT=1
000071          DO 40 I=1,N
000072          T(7,I)=F(I)
000073          40    T(2,I)=D(I)
000074          GO TO 21
000075          C
000076          C TEST ERROR TERM HERE.
000077          42    CONTINUE
000078          IDF=2
000079          DO 16 I=1,N
000080          BOT=F(I)
000081          IF(ABS(BOT).LT.1.E-6) BOT=1.E-6
000082          ERR=ABS((F(I)-T(8,I))/BOT)
000083          IF(ERR.LT.E(I)) GO TO 18
000084          19    IDF =1
000085          GO TO 500
000086          18    IF(64.*ERR.LT.E(I)) GO TO 16
000087          33    IDF=0
000088          16    CONTINUE
000089          IF(KKF.NE.0) GO TO 404
000090          C NEW DIFFERENCES
000091          34    IF(NS.GT.5) NS=5
000092          12    DO 17 I=1,N
000093          T(7,I)=F(I)
000094          TE = D(I)
000095          DO 15 K=2,NS
000096          TF = TE -T(K,I)
000097          T(K,1)=TE
000098          15    TE =TF
000099          17    T(NS+1,I)=TE
000100          IF(KKF.NE.0) KKF=1
000101          NS=NS+1
000102          IF(IDF.EQ.2) GO TO 25
000103          501    RETURN
000104          C
000105          404    KKF=2
000106          700    RETURN1
000107          C
000108          C HALF
000109          500    IF(H.LE.HMIN) GO TO 34
000110          502    INT =INT +1
000111          IF(INT.GE.10) GO TO 34
000112          X=X-H
000113          24    H=H/2.
000114          GO TO 28

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```

000115      C      DOUBLE
000116      25     INT=1
000117      IF(2.*H.GE.HMAX) RETURN
000118      510    H=H+H
000119      28     NN=NS-2
000120      DO 26 I=1,N
000121      KKK=1
000122      DO 26 L=1,NN
000123      TE=0.
000124      DO 27 K=L,NN
000125      GO TO (44,45),IDF
000126      44     TF=AH(KKK)
000127      GO TO 29
000128      45     TF =AD(KKK)
000129      29     TE = TE +TF*T(K+2,I)
000130      27     KKK=KKK+1
000131      26     T(L+2,I) =TE
000132      IF(IDF=2)21,501,21
000133      C
000134      ENTRY ADPAR(TP)
000135      3      KF = 3
000136      P= (TP-X) / H
000137      P2 =P*P
000138      P3 =P*P2
000139      P4 = P*P3
000140      P5 = P*P4
000141      ACC(2)=P
000142      ACC(3)=P2/2.
000143      ACC(4) =(2.*P3+3.*P2)/12.
000144      ACC(5) =(P4+4.*(P3+P2))/24.
000145      ACC(6) =(6.*P5 +45.*P4+110.*P3 +90.*P2)/720.
000146      KF=3
000147      GO TO 100
000148      C
000149      43     DO 46 I=1,N
000150      46     FP(I) = F(I)
000151      INT=1
000152      RETURN
000153      C
000154      ENTRY ADRES
000155      4      INT=0
000156      NS=2
000157      RETURN
000158      C
000159      C
000160      100    DO 101 I=1,N
000161      YT=0.
000162      DO 102 K=1,NS
000163      102    YT = YT + AC(K,KF)* T(K,I)
000164      101    F (I) = YT *H + T(7,I)
000165      GO TO (520,42,43),KF
000166      C
000167      C
000168      END

```

*NEW
**-1

© ELT SUB22, 1, 690715, 33520

```

000056          C                                     CTP 510
000057      10 READ (5,240) DCARD                 CTP 520
000058      IF (DCARD(1).EQ.TCARD) GO TO 200     CTP 530
000059      DO 190 I=1,73                         CTP 540
000060      IF (I.EQ.73) GO TO 80                  CTP 550
000061      IF (DCARD(I).EQ.BLANK) GO TO 190     CTP 560
000062      DO 20 J=1,17
000063          IF (DCARD(I).EQ.SYMB(J)) GO TO (40,40,40,40,40,40,40,40,30,100,CTP 580 **-1
000064          160,80,50,70,90,100),J
000065      20 CONTINUE                            CTP 600
000066          GO TO 230                          CTP 610
000067          C                                     CTP 620
000068          30 J=0                             CTP 630
000069          IF (IDIG.EQ.0) GO TO 190           CTP 640
000070          C                                     CTP 650
000071          40 IDIG=IDIG+1                      CTP 660
000072          IF (.NOT.DECMAL) NDEC=IDIG-1       CTP 670
000073          XNUM(IDIG)=J                      CTP 680
000074          GO TO 190                          CTP 690
000075          C                                     CTP 700
000076          50 IF (DECIMAL) GO TO 230           CTP 710
000077          DECMAL=.TRUE.                     CTP 720
000078          IF (IDIG.GT.0) GO TO 190           CTP 730
000079          IDIG=1                           CTP 740
000080          XNUM(1)=0.0                      CTP 750
000081          GO TO 190                          CTP 760
000082          C                                     CTP 770
000083          60 KSIGN=-1                      CTP 780
000084          GO TO 100                          CTP 790
000085          C                                     CTP 800
000086          70 IF (EXPON) GO TO 230           CTP 810
000087          EXPON=.TRUE.                     CTP 820
000088          NUMBER=.FALSE.                   CTP 830
000089          C                                     CTP 840
000090          80 KSIGN=0                        CTP 850
000091          GO TO 110                          CTP 860
000092          C                                     CTP 870
000093          90 IF (LOCATE) GO TO 230           CTP 880
000094          LOCATE=.TRUE.                    CTP 890
000095          KSIGN=1                         CTP 900
000096          IF (XSIGN.EQ.0.0.AND.IDIG.EQ.0) GO TO 180 CTP 910
000097          NUMBER=.FALSE.                   CTP 920
000098          GO TO 110                          CTP 930
000099          C                                     CTP 940
000100          100 IF (XSIGN.EQ.0.0.AND.IDIG.EQ.0) GO TO 180 CTP 950
000101          C                                     CTP 960
000102          110 X=0.0                         CTP 970
000103          IF (IDIG.EQ.0) GO TO 130           CTP 980
000104          DO 120 K=1,1DIG                   CTP 990
000105          X=X+10.*NDEC*XNUM(K)            CTP1000
000106          120 NDEC=NDEC-1                  CTP1010
000107          C                                     CTP1020
000108          IDIG=0                           CTP1030
000109          NDEC=0                           CTP1040
000110          DECMAL=.FALSE.                   CTP1050
000111          C                                     CTP1050
000112          IF (XSIGN.LT.0.0) X=-X           CTP1070
000113          130 IF (.NOT.NUMBER) GO TO 140     CTP1080
000114          IF (LOCATE) GO TO 160             CTP1090

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000115      IF (EXPON) GO TO 170          CTP1100
000116      GO TO 150                  CTP1110
000117      140 NUMBER=.TRUE.           CTP1120
000118      ESIGN=XSIGN              CTP1130
000119      IF (ESIGN.EQ.0.0) ESIGN=1.0 CTP1140
000120      C                                CTP1150
000121      C                                CTP1160
000122      150 LOCN=LOCN+1            CTP1170
000123      C(LOCN)=X                 CTP1180
000124      GO TO 180                CTP1190
000125      C                                CTP1200
000126      160 LOCN=ABS(X)           CTP1210
000127      LOCATE=.FALSE.           CTP1220
000128      GO TO 180                CTP1230
000129      C                                CTP1240
000130      170 EXPON=.FALSE.         CTP1250
000131      IF (C(LOCN).EQ.0.0) C(LOCN)=ESIGN CTP1260
000132      C(LOCN)=C(LOCN)*10.*IFIX(X) CTP1270
000133      C                                CTP1280
000134      180 XSIGN=KSIGN          CTP1290
000135      KSIGN=1                  CTP1300
000136      C                                CTP1310
000137      190 CONTINUE             CTP1320
000138      C                                CTP1330
000139      GO TO 10                 CTP1340
000140      C                                CTP1350
000141      C                                CTP1360
000142      THE FOLLOWING LOGIC IS TO PACK THE 'DCARD' DATA INTO 'ITITLE' CTP1370
000143      FOR A 'FORMAT(1X,12A6)' PRINTOUT. CTP1380
000144      C                                CTP1390
000145      200 DCARD(1)=BLNK          CTP1450
000146      L=0                      CTP1460
000147      DO 220 I=1,72,6          CTP1470
000148      L=L+1                  CTP1480
000149      KK=I-1                  CTP1490
000150      DO 210 J=1,6            CTP1500
000151      K=KK+J                  CTP1510
000152      DCARD(K)=AND(IDCARD(K),MASK) CTP1520
000153      IF (J.EQ.1) GO TO 210    CTP1530
000154      IDCARD(K)=IDCARD(K)/MULT1(J) CTP1540
000155      IF (ISIGN(1, IDCARD(K)).LT.0) IDCARD(K)=IABS(IDCARD(K))+MASK1(J) CTP1550
000156      210 CONTINUE             CTP1560
000157      220 ITITLE(L)=IDCARD(I)+ISIGN((IDCARD(I+1)+IDCARD(I+2)+IDCARD(I+3)+IDCARD(I+4)+IDCARD(I+5)),IDCARD(I)) CTP1570
000158      RETURN                  CTP1580
000159      C                                CTP1590
000160      C                                CTP1600
000161      230 IERR=2               CTP1610
000162      WRITE (6,250) DCARD     CTP1620
000163      GO TO 10                 CTP1630
000164      C                                CTP1640
000165      240 FORMAT (72A1)        CTP1650
000166      250 FORMAT (1X,72A1)      CTP1660
000167      END                     CTP1670
000168      C                                CTP1680-

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Report 20672-P2D

Subroutine 23 was deleted when the program was revised.

Report 20672-P2D

```

SUBROUTINE INTGR (A,B,X,N)
X=A
I=1
NL=128*N
RETURN
ENTRY INTGS ($,F,Y,E,M)
GO TO (1,2,3),I
C FIRST TIME
1 X=B
F0 = F
I=2
RETURN1
C
000013 FEND = F0
000014 N= ((N+3)/4)*4
000015 DX = (B-A) / N
000016 F1=0.
000017 F2=0.
000018 F3=0.
000019 F4=0.
000020 K=1
000021 I=3
000022 X=A+ DX
000023 RETURN1
000024
000025
000026 KF = MOD(K - 1,4)+1
000027 GO TO (10,11,12,13),KF
000028 F1=F1 + F
10 GO TO 14
000029 GO TO 14
000030 F2=F2 + F
11 GO TO 14
000031 F3=F3 + F
12 GO TO 14
000032 F4=F4 + F
13 GO TO 14
000033 X=X+DX
14 K=K+1
000036
000037 IF (K.NE.N) RETURN1
000038 SUM1 = DX/3.* (FEND+ 2.* (F2+F4) + 4.* (F1+F3))
000039 SUM2 = 2*DX/3.* (FEND+ 2.* F4+4.* F2)
000040 ER= (SUM1-SUM2) /15.
000041 TF (ABS(ER/SUM1) .LT.E) GO TO 15
000042 IF (N.GT.NL) GO TO 15
000043 N=2*N
000044 GO TO 20
000045 Y=SUM1 + ER
000046 M=N
000047 RETURN
000048
END CUR

```

@ ELT BESJ,1,690714, 35959

000001	SUBROUTINE BESJ(X,N,BJ,D,IER)	BESJ 1
000002	BJ=.0	BESJ 2
000003	IF(N)10,20,20	BESJ 3
000004	10 IER=1	BESJ 4
000005	RETURN	BESJ 5
000006	20 IF(X)30,30,31	BESJ 6
000007	30 IER=2	BESJ 7
000008	RETURN	BESJ 8
000009	31 IF(X-15.)32,32,34	BESJ 9
000010	32 NTEST=20.+10.*X-X** 2/3	BESJ 10
000011	GO TO 36	BESJ 11
000012	34 NTEST=90.+X/2.	BESJ 12
000013	36 IF(N-NTEST)40,38,38	BESJ 13
000014	38 IER=4	BESJ 14
000015	RETURN	BESJ 15
000016	40 IER=0	BESJ 16
000017	N1=N+1	BESJ 17
000018	BPREV=.0	BESJ 18
000019	C COMPUTE STARTING VALUE OF M	BESJ 19
000020	IF(X-5.)50,60,60	BESJ 20
000021	50 MA=X+6.	BESJ 21
000022	GO TO 70	BESJ 22
000023	60 MA=1.4*X+60./X	BESJ 23
000024	70 MB=N+IFIX(X)/4+2	BESJ 24
000025	MZERO=MA	BESJ 25
000026	IF(MA-MB)80,90,90	BESJ 26
000027	80 MZERO=MB	BESJ 27
000028	C SET UPPER LIMIT OF M	BESJ 28
000029	90 MMAX=NTEST	BESJ 29
000030	100 DO 190 M=MZERO,MMAX,3	BESJ 30
000031	C SET F(M),F(M-1)	BESJ 31
000032	FM1=1.0E-28	BESJ 32
000033	FM=.0	BESJ 33
000034	ALPHA=.0	BESJ 34
000035	IF(M-(M/2)*2)120,110,120	BESJ 35
000036	110 JT=-1	BESJ 36
000037	GO TO 130	BESJ 37
000038	120 JT=1	BESJ 38
000039	130 M2=M-2	BESJ 39
000040	DO 160 K=1,M2	BESJ 40
000041	MK=M-K	BESJ 41
000042	BMK=2.*FLOAT(MK)*FM1/X-FM	BESJ 42
000043	FM=FM1	BESJ 43
000044	FM1=BMK	BESJ 44
000045	IF(MK-N-1)150,140,150	BESJ 45
000046	140 BJ=BMK	BESJ 46
000047	150 JT=-JT	BESJ 47
000048	S=1+JT	BESJ 48
000049	160 ALPHA=ALPHA+BMK*S	BESJ 49
000050	BMK=2.*FM1/X-FM	BESJ 50
000051	IF(N)180,170,180	BESJ 51
000052	170 BJ=BMK	BESJ 52
000053	180 ALPHA=ALPHA+BMK	BESJ 53
000054	BJ=BJ/ALPHA	PESJ 54
000055	IF(ABS(BJ-BPREV)-ABS(D*BJ))200,200,190	BESJ 55

Report 20672-P2D

56
REFS J
57
RES J
58
BES J
59
RES J

190 BPREV=B J
1ER 3
200 RETURN
END

000056
000057
000058
000059

@ ELT BESEL,1,690716, 76335

```
000001      SUBROUTINE BESEL (J,Y,V,X,K)
000002      INTEGER V
000003      REAL J,Y
000004      DIMENSION J(1),Y(1)
000005      D=1.E-6
000006      NV=V+1
000007      DO 1 I=1,NV
000008      CALL BESJ(X,I-1,J(I),D,IER )
000009      IF(IER.NE.0) GO TO 10
000010      CALL BESY(X,I-1,Y(I),IER)
000011      IF(IER.NE.0) GO TO 11
000012      1  CONTINUE
000013      RETURN
000014      10  WRITE(6,100)X,V
000015      GO TO 12
000016      11  WRITE(6,101)X,V
000017      12  K=1
000018      RETURN
000019      100 FORMAT(10X,28HERROR IN BESJ, X AND V ARE. ,2E15.7)
000020      101 FORMAT(10X,28HERROR IN BESY, X AND V ARE. ,2E15.7)
000021      END
```

@ ELT BESY,1,690714, 35961

000001	SUBROUTINE BESY(X,N,BY,IER)	BESY	1
000002	C CHECK FOR ERRORS IN N AND X	BESY	2
000003	IF(N)180,10,10	BESY	3
000004	10 IER=0	BESY	4
000005	IF(X)190,190,20	BESY	5
000006	20 PI=3.141592653	BESY	6
000007	C BRANCH IF X LESS THAN OR EQUAL 4	BESY	7
000008	IF(X-4.)40,40,30	BESY	8
000009	C COMPUTE Y0 AND Y1 FOR X GREATER THAN 4	BESY	9
000010	30 T=4./X	BESY	10
000011	P0=.3989422793	BESY	11
000012	Q0=-.0124669441	BESY	12
000013	P1=.3989422819	BESY	13
000014	Q1=.0374008364	BESY	14
000015	A=T*T	BESY	15
000016	B=A	BESY	16
000017	P0=P0-.0017530620*A	BESY	17
000018	Q0=Q0+.0004564324*A	BESY	18
000019	P1=P1+.0029218256*A	BESY	19
000020	Q1=Q1-.00063904*A	BESY	20
000021	A=A*A	BESY	21
000022	P0=P0+.00017343*A	BESY	22
000023	Q0=Q0-.0000869791*A	BESY	23
000024	P1=P1-.000223203*A	BESY	24
000025	Q1=Q1+.0001064741*A	BESY	25
000026	A=A*B	BESY	26
000027	P0=P0-.0000487613*A	BESY	27
000028	Q0=Q0+.0000342468*A	BESY	28
000029	P1=P1+.0000580759*A	BESY	29
000030	Q1=Q1-.0000398708*A	BESY	30
000031	A=A*B	BESY	31
000032	P0=P0+.0000173565*A	BESY	32
000033	Q0=Q0-.0000142078*A	BESY	33
000034	P1=P1-.000020092*A	BESY	34
000035	Q1=Q1+.00001642*A	BESY	35
000036	A=A*B	BESY	36
000037	P0=P0-.0000037043*A	BESY	37
000038	Q0=Q0+.0000032312*A	BESY	38
000039	P1=P1+.0000042414*A	BESY	39
000040	Q1=Q1-.0000036594*A	BESY	40
000041	A=SQRT(2.*PI)	BESY	41
000042	B=4.*A	BESY	42
000043	P0=A*B0	BESY	43
000044	Q0=B*Q0/X	BESY	44
000045	P1=A*P1	BESY	45
000046	Q1=B*Q1/X	BESY	46
000047	A=X-PI/4.	BESY	47
000048	B=SQRT(2./(PI*X))	BESY	48
000049	Y0=B*(P0*SIN(A)+Q0*COS(A))	BESY	49
000050	Y1=B*(-P1*COS(A)+Q1*SIN(A))	BESY	50
000051	GO TO 90	BESY	51
000052	C COMPUTE Y0 AND Y1 FOR X LESS THAN OR EQUAL TO 4	BESY	52
000053	40 XX=X/2.	BESY	53
000054	X2=XX*XX	BESY	54
000055	T= ALOG(XX)+.5772156649	BESY	55

```

000056      SUM=0.                                BESY  56
000057      TERM=T                                BESY  57
000058      Y0=T                                BESY  58
000059      DO 70 L=1,15                            BESY  59
000060      IF(L-1)50.60,50                          BESY  60
000061      50 SUM=SUM+1./FLOAT(L-1)                BESY  61
000062      60 FL=L                               BESY  62
000063      TS=T-SUM                            BESY  63
000064      TERM=(TERM*(-X2)/FL)**2)*(1.-1./(FL*TS)) BESY  64
000065      70 Y0=Y0+TERM                          BESY  65
000066      TERM = XX*(T-.5)                      BESY  66
000067      SUM=0.                                BESY  67
000068      Y1=TERM                            BESY  68
000069      DO 80 L=2,16                            BESY  69
000070      SUM=SUM+1./FLOAT(L-1)                BESY  70
000071      FL=L                               BESY  71
000072      FL1=FL-1.                            BESY  72
000073      TS=T-SUM                            BESY  73
000074      TERM=(TERM*(-X2)/(FL1*FL))*((TS-.5/FL)/(TS+.5/FL1)) BESY  74
000075      80 Y1=Y1+TERM                          BESY  75
000076      PI2=2./PI                           BESY  76
000077      Y0=PI2*Y0                           BESY  77
000078      Y1=-PI2/X+PI2*Y1                     BESY  78
000079      C   CHECK IF ONLY Y0 OR Y1 IS DESIRED BESY  79
000080      90 IF(N-1)100,100,130                 BESY  80
000081      C   RETURN EITHER Y0 OR Y1 AS REQUIRED BESY  81
000082      100 IF(N)110,120,110                  BESY  82
000083      110 BY=Y1                           BESY  83
000084      GO TO 170                           BESY  84
000085      120 BY=Y0                           BESY  85
000086      GO TO 170                           BESY  86
000087      C   PERFORM RECURRENCE OPERATIONS TO FIND YN(X) BESY  87
000088      130 YA=Y0                           BESY  88
000089      YB=Y1                           BESY  89
000090      K=1                                BESY  90
000091      140 T=FLOAT(2*K)/X                   BESY  91
000092      YC=T*YB-YA                         BESY  92
000093      K=K+1                           BESY  93
000094      IF(K-N)150,160,150                 BESY  94
000095      150 YA=YB                           BESY  95
000096      YB=YC                           BESY  96
000097      GO TO 140                           BESY  97
000098      160 BY=YC                           BESY  98
000099      170 RETURN                         BESY  99
000100      180 IER=1                           BESY 100
000101      RETURN                           BESY 101
000102      190 IER=2                           BESY 102
000103      RETURN                           BESY 103
000104      END                                BESY 104

```

II, Programming (cont.)

D. METHODS OF VERIFICATION

For most sections of this program, the only method of verification is the "reasonableness" of the numbers output. This is a nebulous statement and the only way an engineer can know what is reasonable is from experience with the sensitive time lag theory and its application. There are some guidelines that can be given, however, that may help those new to the program.

1. If A_{vn} , B_{vn} , and C_{vn} are 1.0, the n minimum will be on the order of 0.5 to 1.0. It will always be positive.
2. The frequency of the n minimum is near the acoustic mode frequency of a cylinder. This frequency is given in a formula on Figure 2.
3. The calculation of A_{vn} , B_{vn} , and C_{vn} can be checked by running a case with combustion concentrated at a particular location. The answer can then be easily checked using the formulas in Section I,B,(5) and Figure 8.
4. When τ at n minimum is given in seconds, it can be converted to an equivalent frequency by the relation $\tau^* = \frac{1}{2f^*}$.
5. The test cases given in this manual are a convenient reference to establish whether the program and computer are working correctly.

Report 20672-P2D

Section III, Deck Setup

Section III Deck Setup

A. COMPUTER CONFIGURATION

1. Univac 1108 computer, 65K of core minimum
2. 46211_8 for code, 72245_8 for data
3. FORTRAN V
4. Executive II monitor system
5. No plot output required
6. No punch output required
7. Units 12, 13, 14 are used for temporary storage.

B. ESTIMATED RUNNING TIME

Because of the extremely large number of ways of running this program, it would be very difficult to give a formula for running time. As a guide, the sample case given in Section III,L ran in 2.06 minutes. The nozzle admittance calculation is the single most time consuming portion of the program.

III, Deck Setup (cont.)

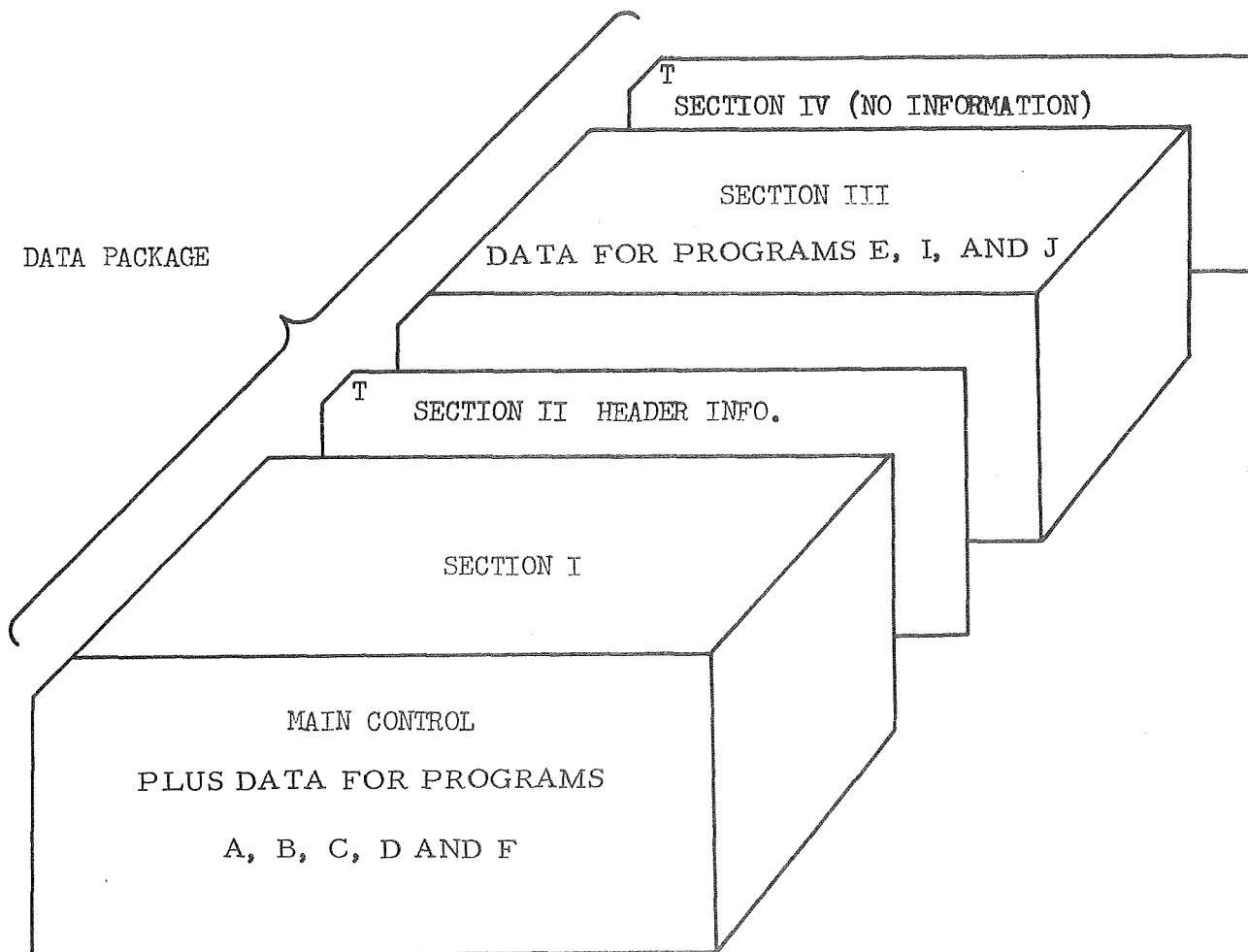


Figure 18 -- Input Load Sequence Required by the Computer Program

III, Deck Setup (cont.)

C. DECK SEQUENCE

It is necessary to discuss the general organization of the data as well as how the data actually get into the computer before proceeding with any further discussion of the computer program. Hereafter, the input data deck will be referred to as a set of data packages.

The manner in which the data deck is assembled is shown in Figure 18. It can be seen that the data package (one package required per case), is divided into four sections. The first section contains the data for MAIN CONTROL and for Programs A, B, C, D and F. The second section is one card that has the letter T punched in card column one. This card serves the purpose of an end-data signal and of a header card such that all information that follows the T will be printed on the top of each output page. The third section contains the data for Programs E, I, and J. The fourth section is a T-card that is used only to signal the end of that data.

It should be noted that if neither E, I, or J are run, Sections III and IV are not needed. However, Sections I and II must always be on the data package.

Running Multiple Cases

The flexibility of the program is such that stacking cases (i.e., running multiple cases) is an easy task. All that is required is to add the required number of data packages to the data deck. There is no restriction as to the flow paths of individual data packages; therefore, data packages of parametric studies involving the use of one program can be intermingled with data packages that use any of the other program combinations for an analysis.

III, C, Deck Sequence (cont.)

Getting the Data Onto the Card

The inputting of the data is accomplished in a flexible fashion. The method employed is called scatter load.* This method has a minimum number of restrictions as to how and in what manner the data are punched on the card. Examples are given below that will illustrate the flexibility of scatter load.

Load and Terminal Flags

The first thing that must be punched on a card is the letter L or the letter T. The L signals the computer that data are on the card whereas the T signifies that the computer has received all of the data for that section of the data package.

Data Input

Immediately after the L will appear 1 to 4 numbers; therefore, the card thus far has been punched with L followed by 4 digits, e.g., L4175. This tells the computer to start loading the data that will follow into computer core starting at Location 4175. Following this number will be a plus or minus sign and data, another plus or minus sign and data, etc. Since the signs serve to separate the data, the second data point will automatically be loaded into core location 4176. This process continues across the first 72 columns of the data card.

Consider the following example of input data

*Except for the input to main control.

III, C, Deck Sequence (cont.)

L0 + 10.0
L1 + 19.4
L2 + 0.0
L3 - 0.92
L8 + 6.4

This may be punched on a single card as

(Example 1) L0 + 10.0 + 19.4 + 0.0 - 0.92 L8 + 6.4
(Example 2) L0 + 10.0 + 19.4 + -0.92 + + + + 6.4
(Example 3) L8 + 6.4 L0 + 10.0 + 19.4 + -0.92
(Example 4) L39 + 0.21 + 3.14 + 5.0 + 1.5 -35.5 L39 1545.

Example 1 illustrates a normal load sequence for the given input. No data are transferred into core locations L4 thru L7; therefore, any previous data stored there remains there. Example 2 illustrates how algebraic signs can be used to index the core location to the proper station. Note also the L2, which is identically zero, has no number punched on the card. This illustrates that the computer, when it sees no number following the sign, loads the value of zero into that core location. If data have been previously stored in Locations L4 thru L7 and are to be used again, the use of indexing presented in Example 2 will load zeros into those core locations; consequently, the data will be lost.

Example 3 illustrates that the L-numbers do not have to be punched in sequential order. Example 4 illustrates the method of correcting data. Specifically, L39 was initially loaded with 0.21 and later loaded with 1545.0; therefore, the former number is erased on core and the latter included in its place. The most convenient method for correcting data cards is to punch all the corrections on one or more cards and place these cards immediately before the T-card of that data section.

III, C, Deck Sequence (cont.)

Presented below are some basic rules to employ when punching data cards:

1. DO start each input card with L. The L does not have to be punched in card column 1 but it must appear before the data.

2. DO pay close attention to the sequence of the remaining data included on the card so that data are not loaded into the wrong core location.

3. DO NOT use more than 8 significant digits (including decimal point) for the input data. Exponential notion is permitted. That is, the number 0.0625 can be loaded as 6.25 E-02.

4. DO NOT start the data on one card and complete it on another.

5. DO NOT use more than 72 card columns for data input. The computer looks at 73 to 80 but does not transfer that information to core. Therefore, columns 73 and 80 can be used for the card sequence number in the data deck or identification of some significant aspect of the data so that it can be identified at some later date.

6. DO include a T-card at the end of a data section in the data package. The T must be punched in card column 1. If the T appears anywhere else on the card, the computer will dump the entire run.

7. DO include a description of the case on the T-card of Section 2. This information serves as a header for each output page. This is a convenience more than a necessity.

III, C, Deck Sequence (cont.)

8. DO NOT use two or more T cards for a header. This can confuse the computer's input logic.

Thus far the storage locations for the individual data bits have not been noted. They will be provided in Section III,E. It is sufficient to state here that the input data have reserved locations in core and that these data remain in those locations unless over-written by the next set of input data. Therefore, it is not necessary to input all the data on the next run if only one parameter (e.g., the ratio of the specific heats) is to be changed. Only the data that changes from one case to the next have to be input on successive data packages (except for main control).

Operation of MAIN CONTROL

Since the computer obeys every command explicitly, it is necessary to indicate correctly to the computer the programs that are desired for a particular case. Furthermore, this must be done for every case because the computer will turn off the switch that activated the program after it is through with the program. This is done purposely to avoid using a program that is not needed for the second case.

The first 10 core locations are reserved for MAIN CONTROL in the following order:

- L0: Program A, Longitudinal Mode Chamber Analysis and Stability Zones
- L1: Program B, Transverse Mode Chamber Analysis
- L2: Program C, Exhaust Nozzle Admittance Coefficients for Longitudinal and Transverse Modes

III, C, Deck Sequence (cont.)

- L3: Program D, Expansion of Results from Program B.
- L4: Program E, Injector Nonuniformity Coefficients
- L5: Program F, Final Solution of Instability Zones
- L6: Program G, Not used in this package
- L7: Program H, High Combustion Chamber Mach Number Analysis
- L8: Program I, Nonlinear Combustion Response Analysis
- L9: Program J, Injected Mass Distribution Effects

A zero in any of the locations indicates that this program will not be used. A number greater than zero instructs the computer to execute this program at the time it is required. The program knows when to execute the program and a number in the proper place tells the computer whether or not to execute the program.

Program Options

Most programs have various options concerning the desired output to be printed. These options are exercised by the same control number that executes the program and are keyed by the magnitude of the number. These print options are presented in the discussion of the individual programs. However, a few examples are presented here to illustrate this point:

EXAMPLE 1: EXECUTE PROGRAM C - PRINT NO OUTPUT

LO + + + 9.0 + + + + + + (0 < L2 < 9.0)

EXAMPLE 2: EXECUTE PROGRAM C - PRINT OUTPUT

LO + + + 99.0 + + + + + + (10 < L2 ≤ 99.0)

III, C, Deck Sequence (cont.)

EXAMPLE 3: EXECUTE PROGRAM C - PRINT INPUT AND OUTPUT

L0 + + + 199.0 + + + + + + + (100 < L2 \leq 199.0)

Determination of Design Criteria

Table III shows the program combinations that are required to obtain stability maps for the longitudinal and transverse modes and to make certain parameter studies.

TABLE III
PROGRAM COMBINATIONS FOR DESIGN CRITERIA

<u>Desired Output</u>	<u>Critical Data Requirements</u>	<u>Required Program</u>
η, τ Map for Longitudinal Modes	Nozzle Admittance Coefficient, a_N	Known A
η, τ Map for Transverse Modes	Nozzle Admittance Coefficients, A, B, C, $B_{\eta\eta}, C_{\eta\eta}$	Not Known A, C A, B, C Known B, E B, C, F
Number of Data Points	One not known All Known One not known 10 Sufficient More than 10 required	One not known B, E, F B, F B, D, F C J, E I, E A, C or B, C, D, F B, D, E, F
Parameter Studies	Nozzle Effects Variation of Nonuniformity Effects with Respect to Mass Distribution Variation of Nonuniformity Effects with Respect to Nonlinear Combustion Response Variation of Stability Zones with Respect to Nozzle Effects Variation of Stability Zones with Respect to Nonuniformity Coefficients	

D. INPUT DATA

PROGRAM INDEX

<u>Program</u>		<u>Page</u>
A	Longitudinal Mode Chamber Analysis and Instability Zones	231
B	Transverse Mode Chamber Analysis	235
C	Exhaust Nozzle Admittance Coefficients for Longitudinal and Transverse Modes	238
D	Expansion of Results from Program B	243
E	Injector Nonuniformity Coefficients	245
F	Final Solution of Instability Zones	248
G	(Obsolete and deleted from the listing)	250
H	High Combustion Chamber Mach Number Analysis	250
I	Nonlinear Combustion Response	250
J	Injected Mass Distribution Effects	253

III, Deck Setup (cont.)

D. INPUT DATA

1. Program A: Longitudinal Mode Chamber Analysis and Instability Zones

a. Input Requirements: the following data go into Section I of data package.

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L0	-	Make greater than zero to execute Program A.
L10	γ	Ratio of the specific heats.
L11	M_e	Steady-state Mach number at the entrance to the exhaust nozzle. This can be determined by the contraction ratio or by Program C. In the latter case, leave L11 blank.
L13	r_c^*	Chamber radius, in. also loaded in L3804, Program C.
L14	L_c^*	Length of cylindrical portion of chamber, in.
L15	c_o^*	Speed of sound in the chamber, ft/sec.
L16	u_{L0}^*	Weighted liquid injection velocity, ft/sec. See equation (56) at the end of this section.
L17	κ	Gas/liquid momentum interchange coefficient. ($\kappa = 0$ for no droplet momentum effects)
L20	s_{vn}	Set equal to zero.
L21	N_{wc}	Number of chamber frequencies to be used. Leaving this column blank will turn on Program GENMEC which will select 10 frequencies according to the relationship given by Eq. (57).
L22	ω	Table of nondimensional, chamber frequencies arranged in ascending order. A zero must be included at the end of the table. The maximum number of frequencies is 28 (including the zero point). This is left blank if L21 is blank.
.		
.		
.		
L49		

III, D, Input Data (cont.)

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L50	Z*	Table of ascending axial positions at which the combustion distribution (i.e., the variation of the local Mach number with respect to Z) is known.
.		Dimensioned in inches. A zero value must appear at the last point. Minimum of four real data points is required.
L69		
L70	M(Z*)	The local steady-state Mach number that corresponds to the given L _Z . A zero <u>must</u> appear as the last value.
.		
.		
L89		
L600		The ascending table of chamber frequencies for which the longitudinal, real and imaginary parts of the nozzle admittance coefficients (to be input next) are known. If Program C is run to determine the admittances, these frequencies will be automatically transferred. The last point in the table <u>must</u> be zero.
L629	ω	
L630	α _{Nr}	The real part of the admittances corresponding to the above frequencies. The last point in the table <u>must</u> be zero. These can be determined by running Program C.
L659		
L660	α _{Ni}	The imaginary part of the admittances corresponding to the above frequencies. The last point in the table <u>must</u> be zero. These can be determined by running Program C.
L689		

b. Print Options

There are no print options available with this program. Any L0 number greater than zero will give a program execution as well as an output of the input data and the results of the program.

c. Placement of the Data into the Data Package

These data are inserted anywhere in Section I of the data package.

III, D, Input Data (cont.)

d. Output

The following output results from the efforts of this program:

<u>Label in Output</u>	<u>Symbol in Analysis</u>
GAMMA	γ
DESIRED MACH NUMBER	M_e
CHAMBER RADIUS	R_{AC}^*
CHAMBER LENGTH	L_c^*
SPEED OF SOUND	c_o^*
CHAMBER MODE DESCRIPTION	s_{vn}
MACH DISTRIBUTION	$M(Z^*)$
UIBAR	M_e
K	κ
X	ξ_1
FC(CPS)	f^*
OMEGA	ω
TAU (MS)	τ^*
N	
ULM	\bar{u}_{LO}^*
WC	ω

III, D, Input Data (cont.)

e. Auxiliary Equations

(1) Axial Liquid Velocity (Weighted)

$$\bar{u}_{LO}^* = \frac{(MR)v_x \cos \theta_x + v_F \cos \theta_F}{MR+1}, \text{ ft/sec} \quad (56)$$

MR = mixture ratio = \dot{w}_x/\dot{w}_F

v_x = oxidizer injection velocity, ft/sec

v_F = fuel injection velocity, ft/sec

$\theta_{x,F}$ = oxidizer and fuel impingement angle

(2) Selection of Frequencies by GENMEG

$$\begin{aligned} (\text{Longitudinal}) &= (1 \pm 0.10) \pi \\ (\text{Transverse}) &= (1 \pm 0.10) s_{vn} \end{aligned} \quad (57)$$

where

π = $3.14159 +$ = resonant frequency
(non-dimensional) for longitudinal modes

s_{vn} = transverse acoustic mode number
given in the Program B writeup.

(3) Other Information

For a longitudinal mode a resonant frequency of π is true for a very short nozzle. It may be necessary to override GENMEG to find an n minimum. Also GENMEG gives only the first mode. Other modes can be obtained by specifying the frequencies to be run.

III, D, Input Data (cont.)

2. Program B: Transverse Mode Chamber Analysis

a. Input Requirements: the following data go into Section I of the data package.

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L1	-	Execute Program B. Magnitude of number depends on print options given in Paragraph b.
L20	s_{vn}	Transverse acoustic mode number given for various modes at the end of this section for cylindrical chambers. For annular chambers, see Figure 9.
L10 · L89		These are identical to Program A. Refer to the writeup of Program A for these requirements.
L3017	N_w	The number of input frequencies at which the transverse nozzle admittance coefficients are known. This number must be greater than 2 and less than 30. If the admittance for a nozzle is unknown and Program C is run, C will provide this number
L3019 : L3048	ω	The values of the chamber frequencies, arranged in ascending order, for which the transverse admittances are known. Program C will provide them if it is run. The last value must be zero.
L3049 : L3078	E_r	The values of the real part of the transverse nozzle admittance coefficient. The last value must be zero. Program C will supply these values.
L3079 : L3108	E_i	The values of the imaginary part of the transverse nozzle admittance coefficient. The last value <u>must</u> be zero. Program C will supply these values.

b. Print Options

$0 < L1 \leq 9$: Execute B, do not print input or output
 $10 \leq L1 \leq 99$: Execute B, print output

III, D, Input Data (cont.)

- $100 \leq L_1 \leq 199$: Execute B, print input and output (recommended)
- $200 \leq L_1 \leq 299$: Execute B, print input and output, print steady state tables and values of integrals associated with high Mach number cases.

c. Placement of the Data into the Data Package

These data are inserted anywhere in Section I of the data package.

d. Output

<u>Label in Output</u>	<u>Symbol in Analysis</u>
GAMMA	γ
DESIRED MACH NUMBER	M_e
CHAMBER RADIUS	R_{AC}^*
CHAMBER LENGTH	L_c^*
SPEED OF SOUND	c_o^*
CHAMBER MODE DESCRIPTION	$s_{v\eta}$
CHAMBER FREQUENCIES	ω
WC	ω
MACH DISTRIBUTION	$M(Z^*)$
SNH	$s_{v\eta}$
ZE	L_c
UE	M_e
SOUND	c_o^*

III, D, Input Data (cont.)

<u>Label In Output</u>	<u>Symbol in Analysis</u>
ULM	\bar{u}_{L0}^*
XK	κ
OMEGA (CH)	ω
ERT	E_r
EIT	E_i
H REAL	h_r
H IMAG	h_i

e. Tabulation of Transverse Acoustic Mode Number ($s_{v\eta}$)

(1) Tangential Modes

First tangential: $s_{11} = 1.8413$
 Second tangential: $s_{21} = 3.0543$
 Third tangential: $s_{31} = 4.2012$
 Fourth tangential: $s_{41} = 5.3175$
 Fifth tangential: $s_{51} = 6.4154$

(2) Radial Modes

First radial: $s_{02} = 3.8317$
 Second radial: $s_{03} = 7.0156$
 Third radial: $s_{04} = 10.1734$

(3) Combined tangential-radial modes

IT-1R: $s_{12} = 5.3313$
 IT-2R: $s_{13} = 8.5263$
 IT-3R: $s_{14} = 11.7059$

III, D, Input Data (cont.)

2T-1R:	s ₂₂	=	6.7060
2T-2R:	s ₂₃	=	9.9695
2T-3R:	s ₂₄	=	13.1705
3T-1R:	s ₃₂	=	8.0151
3T-2R:	s ₃₃	=	11.3459
3T-3R:	s ₃₄	=	14.5858

3. Program C: Exhaust Nozzle Admittance Coefficients for Longitudinal and Transverse Modes

a. Input Requirements: The following data go into Section I of the data package.

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L3801	M	= 1.: the table of velocity potential values within the nozzle is input and the Mach number to the entrance of the nozzle is input. = 2.: the Mach number at the entrance to the nozzle is input but the velocity potential table must be calculated. = 3.: the Mach number and the velocity potential table must be calculated.
L3803	R _{ATO} *	Radius of the throat, in.
L3804	R _{ACO} *	Radius of the chamber, in., also loaded in L13, Program A.
L3805	R _{CCO} *	Radius of chamber curvature at the nozzle entrance, in.
L3806	R _{CTO} *	Radius of curvature at the throat, in.
L3807	α_0	Nozzle convergent half-angle, deg.
L90*	R _{ATi} *	Radius of centerbody throat, in.
L91*	R _{CTi} *	Radius of curvature of the centerbody throat, in.

*Note 1: These values may be plus or minus, see Figures 14 and 15.

Note 2: For cylindrical chambers, leave L90 through L94 blank.

III, D, Input Data (cont.)

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>	<u>Description</u>
L92*	R_{ACi}^*	Radius of chamber of centerbody, in.	
L93*	R_{CCi}^*	Radius of curvature of centerbody at the nozzle entrance.	
L94*	α_i	Centerbody nozzle convergent half-angle, deg.	
L20	s_{vn}	Transverse acoustic mode number is given on the previous page for cylindrical chambers. For annular chambers see Table 1, Section I,B.	
L3808	KN	If L3801 \geq 2, then KN is either	
		(1) An odd integer less than 200 telling the desired size of the program generated velocity potential table, or	
		(2) Blank and program will assume $K_N = 101$ (recommended)	
L3809	$\phi(Z)$	Dimensionless velocity potential table (199 values maximum) in the odd numbered locations only. If L3801 \geq 2, this is not necessary.	
L3811			
L3813			
L4205			
L3810	$\bar{q}^2(Z)$	Squares of the reduced velocity table (199 values maximum) in the even numbered locations only. If L3801 \geq 2, this not necessary.	
L3812			
L3814			
L4206			

*Note 1: These values may be plus or minus, see Figures 14 and 15.

Note 2: For cylindrical chambers, leave L90 through L94 blank.

When this program is run by itself the frequencies to be run must either be input or generated by GENMEG. As discussed later this admittance calculation is done for every other input or generated frequency. To run Program C by itself the above data must be supplemented as follows.

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L10	γ	Ratio of specific heats
L11	M_e	Steady state Mach number at the entrance to the nozzle. Not needed if L3801 is 3.

III, D, Input Data (cont.)

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L13	r_c^*	Chamber radius, in.
L14	L_c^*	Chamber length, in.
L15	c_o^*	Speed of sound in the chamber, ft/sec.
L21	N_{wc}	Number of chamber frequencies to be used leaving this column blank will turn on Program GENMEG. Admittances will actually be calculated for every other frequency as discussed later.
L22 · L49	ω	Table of non-dimensional chamber frequencies arranged in ascending order. Last point must be zero.

b. Print Options

- $0 < L2 \leq 9:$ Execute Program C, print no output
- $10 \leq L2 \leq 99:$ Execute Program C, print output
- $100 \leq L2 \leq 199:$ Execute Program C, print input and output (recommended)
- $200 \leq L2 \leq 299:$ Execute Program C, print input and output, and print the nondimensional velocity potential table.

c. Placement of the Data in the Data Package

This data is inserted anywhere in Section I of the data package.

d. Output

<u>Label In Output</u>	<u>Symbol In Analysis</u>
(SNH)C	s_{vn}
(SNH)N	\hat{s}_{vn}
WC	ω
WN	$\hat{\omega}$

III, D, Input Data (cont.)

<u>Label In Output</u>	<u>Symbol In Analysis</u>
MACH NO.	M_e
G	γ
AR	A_r
AI	A_i
-AR/(MACH NO.)	α_{Nr}
-AI/(MACH NO.)	α_{Ni}
BR	B_r
BI	B_i
T1	E_r
T2	E_i
CR	C_r
CI	C_i
-CR/(MACH NO.)	β_{Nr}
-CI/(MACH NO.)	β_{Ni}
FC (CPS)	f^*

e. Auxiliary Equations

(1) The Selection of the Chamber Frequencies to be Used

Because of the long execution time of this program for a given value of ω , the program starts with the first chamber frequency and uses every other frequency thereafter; that is, if n is the total number of chamber frequencies, Program C will use m number of frequencies according to the relationship

III, D, Input Data (cont.)

$$m = \frac{n}{2} + 1$$

In computer language, m and n are whole numbers.

Therefore, if n = 11

$$m = \frac{11}{2} + 1$$

m = 5 + 1 (where 0.5 has been truncated out)

$$m = 6$$

(2) Nondimensional chamber frequency

$$\omega = \frac{(2\pi f^*) (v_{AC}^*)}{c_o^*} \quad (58)$$

where

* = denotes dimensional variables
subscript c denotes chamber conditions

f^* = chamber frequency, cps

c_o^* = chamber speed of sound ft/sec

v_{AC}^* = chamber length L_c^* or radius r_c^*
(depending if longitudinal or transverse
modes respectively are desired).

(3) Nondimensional nozzle frequency

$$\hat{\omega} = \frac{\omega}{\hat{\kappa}} \quad (59)$$

where

$$\hat{\kappa} = R_{ATO}^* \left[\frac{2}{\gamma+1} \left(\frac{R_{ATO}^*}{R_{CTo}^*} - \frac{R_{ATi}^*}{R_{CTi}^*} \right) \right] / \left[\left(R_{ATO}^* \right)^2 - \left(R_{ATi}^* \right)^2 \right]^{1/2}$$

(4) Nozzle transverse acoustic nozzle number

$$\hat{s}_{vn} = \frac{s_{vn}}{\hat{\kappa}} \quad (60)$$

III, D, Input Data (cont.)

4. Program D: Expansion of Results from Program B

a. Input Requirements

The following data go into Section of the data package:

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L3		Must be greater than zero to run this program,
L3405	$1_r/\eta$	The ratio of the radial velocity coefficient to the pressure interaction index. Generally set equal to zero.
L3406	$1_\theta/\eta$	The ratio of the tangential velocity coefficient to the pressure interaction index. Generally set equal to zero.
L3407		= 1 for linear combustion response. >1 for nonlinear combustion response. This parameter indicates the number of frequencies for which the injector nonuniformity coefficients, A_{vn} , B_{vn} , and C_{vn} , are known. The running of Program I will determine this number. (Not required if Program B is run.)
L3408		The number of chamber frequencies (Not required if Program B is run.)
L3409	ω	The table of frequencies arranged in ascending order. The last value must be zero. (Not required if Program B is run.)
L3437		
L3439	$h_r(\omega)$	Real part of the damping effects computed in Program B. The last value must be zero. (Not required if Program B is run.)
L3467		
L3469	$h_i(\omega)$	Imaginary part of the damping effects computed in Program B. The last value must be zero. (Not required if Program B is run.)
L3497		
L4522		The values of chamber frequencies for which the nonuniformity coefficients are known. Use only if data are available.
L4538		

III, D, Input Data (cont.)

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L4539		The pressure nonuniformity coefficient corresponding to the above frequencies (ω). $A_{v\eta} = 1.0$ for uniform injection distribution.
⋮	$A_{v\eta}$	
L4555		
⋮		
L4556		The radial velocity nonuniformity coefficient corresponding to the above frequencies ω . Generally set equal to zero.
⋮		
L4572		
⋮		
L4573		The real part of the tangential velocity nonuniformity coefficient corresponding to the above frequencies ω . Generally set equal to zero.
⋮	$C_{v\eta} R$	
L4589		
⋮		
L4590		The imaginary part of the tangential velocity non-uniformity coefficient corresponding to the above frequencies ω . Generally set equal to zero.
⋮	$C_{v\eta} i$	
L4606		

NOTES: a. All these data, with the exception of l_r/η and l_θ/η , can be calculated using Programs B, E, and I.

b. This program was constructed specifically to include the effects of the nonuniformity coefficients for the low Mach number cases.

b. Print Options

$0 < L3 \leq 9:$ Execute D, print no output or input
 $10 \leq L3 \leq 99:$ Execute D, print output only
 $100 \leq L3 \leq 199:$ Execute D, print input and output

c. Placement of the Data into the Data Package

These data can be inserted anywhere in Section I of the data package.

III, D, Input Data (cont.)

d. Output

<u>Label on Output</u>	<u>Symbol in Analysis</u>
LR/N	$\frac{l_r}{n}$
LT/N	$\frac{l_\theta}{n}$
ERT	\bar{E}_r
EIT	\bar{E}_i
CRT	C_r
CIT	C_i
OMEGA (C)	ω
OMEGA (CH)	ω
HTR	\tilde{h}_r
HTI	\tilde{h}_i
HTRINT	\tilde{h}_r (interpolated)
HTIINT	\tilde{h}_i (interpolated)
OMEGA	ω

5. Program E: Injector Nonuniformity Coefficients: A_{vn}, B_{vn}, C_{vn}

a. Input Requirements (not programmed for annular chambers)

MAIN CONTROL requires L4 in Section I of data package.

The remaining data go into Section III of the data package.

III, D, Input Data (cont.)

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L1	IZZIT	Indicates whether the mode is standing or spinning: Standing: IZZIT <0 Spinning: IZZIT >0
L2	X _M	The number of radial divisions desired on the injector face ($10 \leq X_M \leq 21$).
L3	X _N	The number of angular divisions desired around the injector face ($20 \leq X_N \leq 181$).
L4	SECTOR	The number of symmetrical sectors that the injector can be divided into, ($1 \leq \text{SECTOR} \leq 180$).
L5	v	Order of transverse mode in tangential direction 1, 2, 3, etc. For radial modes v = 0.
L7	s _{vη}	Transverse acoustic mode number given by tabulation presented in Program B write-up.
L9573	R _{inj}	Injector radius, in.
L9570	NE	Number of elements per symmetrical sector. The maximum number of elements is 1000. Ignore if Program J is run.
L1920 ⋮ L2919	r	The radial position of each element within the symmetrical sector, in. Program J supplies these data when they are run.
L2920 ⋮ L3919	θ	The angular displacement (from any convenient reference line on the injector face) of each element within the symmetrical sector, radians. Program J supplies these data when they are run.
L3920 ⋮ L4919	μ	The element injection distribution given by equation (6) at the end of this section. Usually Program J provides this information to Program E.

III, D, Input Data (cont.)

b. Print Options

$0 \leq L4 \leq 9$: Execute E, do not print input or output
 $10 \leq L4 \leq 99$: Execute E, print output only
 $100 \leq L4 \leq 199$: Execute E, print input and output

c. Placement of the Data into the Data Package

Main control data: Section I of data package.

All other data: Section III of data package. Section IV must be included in the data package.

d. Output

<u>Label on Output</u>	<u>Symbol in Analysis</u>
AVN	A_{vn}
BVN	B_{vn}
CVN	C_{vn}
MU	μ

e. Auxiliary Equations

Distribution coefficient, μ_E

$$\mu_E = \frac{(\dot{w}_T)_E / (A_s)_E}{\dot{w}_T / A_{inj}} = \left(\frac{1}{x_M \cdot x_N} \right)^{-1} \frac{(w_T)_E}{\dot{w}_T} \quad (6)$$

III, D, Input Data (cont.)

where

$$\begin{aligned}(w_T)_E &= \text{total weight flow rate of element, lb/sec} \\ w_T &= \text{total weight flow rate of injector, lb/sec} \\ (A_s)_E &= \text{surface area serviced by the element, in.}^2 \\ A_{inj} &= \text{total surface area of injector, in.}^2\end{aligned}$$

6. Program F: Final Solution for Instability Zones

a. Input Requirements

The input for this program comes directly from Program D and consists of the following parameters:

The frequency in the chamber, ω

The radius of the chamber R_{AC}^* , in.

Speed of sound in the chamber, c_0^* , ft/sec

Real and imaginary parts of the damping parameters h corresponding to the above frequencies.

This program can be run by itself if the data are inserted into those locations specified by Program D.

b. Print Options

$0 < L5 \leq 9:$

Execute Program F, print no input and output

$10 \leq L5 \leq 99:$

Execute Program F, print output only

$100 \leq L5 \leq 199:$

Execute Program F, print input and output

III, D, Input Data (cont.)

c. Placement of the Data into the Data Package

These data are included into Section I of the data package.

d. Output

The following output results from this program:

f^* = frequency of oscillation, Hz
 ω = nondimensional frequency
 τ^* = sensitive time lag corresponding to the above frequency, millisec
 n = pressure interaction index

At the bottom of the page, an effort is made to locate the minimum interaction index. In most cases, this information is valid. However, effects from an adjacent mode will intervene occasionally thereby invalidating this information.

e. Other Information

This program obtains its result by the solution of the following equations:

Frequency, cps

$$f^* = \frac{\omega}{2\pi} , \frac{c^* 12}{R^*_{AC}}$$

III, D, Input Data (cont.)

Pressure interaction index, n

$$n = \frac{\tilde{h}_r^2 + \tilde{h}_i^2}{2\tilde{h}_r}$$

Sensitive time lag, τ , millisec

$$\tau^* = (83.33) \frac{R^* A_{Co}}{c_o^* 12} \frac{1}{f^*} \tan^{-1} \left(\frac{h_i}{n-h_r} \right)$$

7. Program G: Obsolete and deleted from the listing.
8. Program H: High Combustion Chamber Mach Number Analysis

Program H is not operational. Recommended procedure is to place a negative number in load location L7 of MAIN CONTROL.

9. Program I: Nonlinear Combustion Response (Option for Program E)

- a. Input Requirements

MAIN CONTROL requires L8 for Section I of data package.
The remaining data go into Section III of data package:

III, D, Input Data (cont.)

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
ALL THE DATA REQUIRED TO RUN PROGRAM E AS WELL AS:		
L0	E1	The permissible error. If blank, the program will assume E1 = 0.001.
L12	P _{oo}	The ratio of the maximum pressure amplitude at the injector face to the steady-state pressure value.
L19 L68	IPP	The values of the pressure perturbation associated with the pressure-dependent nonlinear element.
L69 L118	OPP	The values of the combustion perturbation corresponding to the above IPP values.
L119 L168	IPR	The values of the radial velocity perturbation associated with the velocity-dependent nonlinear element.
L169 L218	OPR	The values of the combustion perturbation corresponding to the above IPR values.
L219 L268	IPT	The values of the tangential velocity perturbation associated with the velocity dependent nonlinear element.
L269 L318	OPT	The values of the combustion perturbation corresponding to the above IPT values.
L9595	TFLP	The linear transfer function for equivalent linear operation associated with the pressure-dependent non-linear element.
L9596	TFLR	The same as TFLP except for radial velocity-dependent nonlinear element.
L9597	TFLT	The same as TFLP except for tangential velocity-dependent nonlinear elements.
L9598	NUMBR	The number of steps to be used in the integration scheme associated with this problem. If left blank, the computer will assume 20, which is sufficient for most cases.

III, D, Input Data (cont.)

b. Print Options

$0 \leq L8 \leq 9$: Execute I, print no input or output data
 $10 \leq L8 \leq 99$: Execute I, print output only
 $100 \leq L8 \leq 199$: Execute I, print input and output

c. Placement of the Data into the Data Package

These data are included in Section III of the data package.
Along with these data, Section IV must be included.

d. Output

The output of this program is as follows:

The frequency, ω

The element number, location, fractional flow rate,
 F_p , F_R , and F_T necessary for Program E.

This will automatically change the output from Program E
as follows:

The frequency, ω

The frequency dependent expansion coefficients $A_{v\eta}$,
 $B_{v\eta}$, and $C_{v\eta}$.

III, D, Input Data (cont.)

10. Program J: Injected Mass Distribution Effects (Not Programmed for Annular Chambers)

a. Input Requirements

MAIN CONTROL requires L9 in Section I of data package. The remaining data go in Section III of data package.

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L319		Element number (maximum = 1000) within symmetrical sector.
L323	n	
L327		
L319 + 4n		
L320		
L324		
L328	x_n or r_n	Element location, in.
L320 + 4n		
L321		
L325		
L329	y_n or θ_n	Element location, in. or degrees
L321 + 4n		
L322		
L326		
L330	T_n	Type of injection element. The details concerning this type number are given next.
L322 + 4n		
L4	DX	Number of symmetrical sectors, DX = 1 for no symmetry.
L4944 to L9568	-	The data input in this section serves to define the element types and consists of a maximum of 100 variable length data sets. Each set contains:

III, D, Input Data (cont.)

- a. The element type number (≤ 100)
- b. Number of oxidizer orifices for that type
- c. Diameters of all the oxidizer orifices
- d. Number of fuel orifices for that type
- e. Diameters of all the fuel orifices

EXAMPLE

let T_i = i^{th} element type
 NX_i = number of oxidizer orifices for the i^{th} type element
 DX_{ij} = diameter of the j^{th} oxidizer orifice in the i^{th} type element
 NF_i = number of fuel orifices for the i^{th} type element
 DF_{ij} = diameter of the j^{th} fuel orifice in the i^{th} type element

Then a typical input would read

$L4944 + T_1 + NX_1 + DX_{1,1} + DX_{1,2} + DX_{1,3} + NF_1 + DF_{1,1} + DF_{1,2} + T_2 + NX_2$

$+ DX_{2,1} + \dots$

If NF_i or NX_i is zero, then do not set $DF_{i,1} = 0$ or $DX_{i,1} = 0$.

Assume $NX_1 \equiv 0.0$, then

$L4944 + T_1 + NX_1 + NF_1 + DF_{1,1} + DF_{1,2} + DF_{1,3} + T_2 + NX_2 + DX_{2,1} + \dots$

III, D, Input Data (cont.)

<u>Core Location</u>	<u>Mnemonic</u>	<u>Description</u>
L9569	NT	Total number of injection types
L9570	NE	Number of elements per symmetrical sector
L9571	COORD	COORD = 0: elements are located using polar coordinates COORD > 0: elements are located using cartesian coordinates
L9572	WT	Total injector weight flow, lb/sec
L9573	R _{inj}	Injector radius, in.
L9574	MR	Injector mixture ratio
L9575	NFFC	Total number of fuel film cooling holes
L9576	DFFC	Diameter of fuel film cooling holes

In the event of fuel or oxidizer film cooling, either the percent film cooling or the actual orifice dimensions can be used to describe the cooling. Place a zero(s) in the one(s) not used.

L9578	ROX	Oxidizer density, lb/ft ³
L9579	ROF	Fuel density, lb/ft ³
L9584	CDX	Oxidizer orifice loss coefficient
L9585	CDF	Fuel orifice loss coefficient
L9588	PFFC	Percent fuel film cooling
L9589	PXFC	Percent oxidizer film cooling
L9590	XFC	Total number of oxidizer film cooling orifices
L9591	DFFX	Diameter of film cooling orifices

L2, L3, and L4 from Program E.

III, D, Input Data (cont.)

b. Print Options

$0 < L9 \leq 9:$	Execute J, do not print output or input data
$10 \leq L9 \leq 99:$	Execute J, print output only
$100 \leq L9 \leq 199:$	Execute J, print input and output
$L9 \leq 500:$	Execute J, print input and output, and, if error occurs in J, dump error message with input data.

c. Placement of the Data into the Data Package

Main control data: Section I of the data package.

All other data: Section III of the data package.

Section IV must be included in the data package.

d. Output

The following output results as a consequence of this program:

Miscellaneous information concerning the total orifice area, circuit pressure drops, overall mixture ratio, etc.

Element number, injection type, and location.

Description of various parameters associated with the different types of injection elements.

Element number, location, and distribution coefficient.

The distribution coefficient as a function of the radius across the face of the injector.

III, Deck Setup (cont.)

E. RESTRICTIONS AND LIMITATIONS

1. One limitation which cannot easily be implied from the information given in this manual is the frequency limit in transverse mode analysis. This limit is implied from the relationship

$$\Omega \sinh \Omega Z \leq 0 \quad (M_e)$$

This limitation means that combined transverse-longitudinal modes cannot be analyzed with this program. Long chambers (long compared to their diameter) may also produce erroneous results for the pure transverse modes.

2. The restrictions of the annular nozzle analysis have already been discussed in Section I,B,1,b,(6) of this manual.

3. The transverse mode analysis is restricted to low Mach numbers, those less than approximately 0.3.

4. The sensitive time lag theory is developed for liquid propellant rocket engines. Before applying it to gas injection, many assumptions must be examined critically.

5. Calculations of the distribution coefficients $A_{v\eta}$, $B_{v\eta}$, and $C_{v\eta}$ are not applicable to annular chambers.

III, Deck Setup (cont.)

F. OUTPUT DEFINITION

1. Program A

<u>Label in Output</u>	<u>Symbol in Analysis</u>
GAMMA	γ
DESIRED MACH NUMBER	M_e
CHAMBER RADIUS	R_{AC}^*
CHAMBER LENGTH	L_c^*
SPEED OF SOUND	c_o^*
CHAMBER MODE DESCRIPTION	s_{vn}
MACH DISTRIBUTION	$M(Z)^*$
UIBAR	M_e
K	κ
x	ξ_1
FC(CPS)	f^*
OMEGA	ω
TAU (MS)	τ^* $c \times 45$
N	n
ULM	\bar{u}_{LO}^*
WC	ω

2. Program B

<u>Label in Output</u>	<u>Symbol in Analysis</u>
GAMMA	γ
DESIRED MACH NUMBER	M_e
CHAMBER RADIUS	R_{AC}^*
CHAMBER LENGTH	L_c^*
SPEED OF SOUND	c_o^*

III, F, Output Definition (cont.)

<u>Label in Output</u>	<u>Symbol in Analysis</u>
CHAMBER MODE DESCRIPTION	s_{vn}
CHAMBER FREQUENCIES	ω
WC	ω
MACH DISTRIBUTION	$M(Z^*)$
SNH	s_{vn}
ZE	L_c
UE	M_e
SOUND	c_o^*
ULM	\bar{u}_{Lo}^*
XK	κ
OMEGA (CH)	ω
ERT	E_r
EIT	E_i
H REAL	h_r
H IMAG	h_i

3. Program C

<u>Label in Output</u>	<u>Symbol in Analysis</u>
(SNH)C	s_{vn}
(SNH)N	s_{vn}
WC	ω
WN	$\hat{\omega}$

III, F, Output Definition (cont.)

<u>Label in Output</u>	<u>Symbol in Analysis</u>
MACH NO.	M_e
G	γ
AR	A_r
AI	A_i
-AR/(MACH NO.)	α_r
-AI/(MACH NO.)	α_i
BR	B_r
BI	B_i
T1	E_r
T2	E_i
CR	C_r
CI	C_i
-CR/(Mach No.)	β_{nr}
-CI/(Mach No.)	β_{ni}
FC (CPS)	f^*

4. Program D

<u>Label on Output</u>	<u>Symbol in Analysis</u>
LR/N	$\frac{l_r}{n}$
LT/N	$\frac{l_\theta}{n}$
ERT	E_r
EIT	E_i
CRT	C_r
CIT	C_i
OMEGA (C)	ω
OMEGA (CH)	ω

III, F, Output Definition (cont.)

<u>Label On Output</u>	<u>Symbol in Analysis</u>
HTR	\tilde{hr}
HTI	\tilde{hi}
HTRINT	\tilde{hr} (interpolated)
HTIINT	\tilde{hi} (interpolated)
OMEGA	ω

5. Program E

<u>Label on Output</u>	<u>Symbol in Analysis</u>
AVN	A_{vn}
BVN	B_{vn}
CVN	C_{vn}
MU	μ

6. Program F

<u>Label on Output</u>	<u>Symbol in Analysis</u>
FC(CPS)	f^*
(OMGA)D	ω
TAU(MS)	τ^*
N	n
NMIN	n_{min}

III, F, Output Definition (cont.)

7. Program I

<u>Label on Output</u>	<u>Symbol in Analysis</u>
PRESSURE PERTURBATION	p'
COMBUSTION GAIN	ϕ_p
RADIAL VELOCITY PERTURBATION	v'
COMBUSTION GAIN	ϕ_R
TANGENTIAL VELOCITY PERTURBATION	w'
COMBUSTION GAIN	ϕ_T
OMEGA	ω
FP	F_p
FR	F_R
FT	F_T
AVN REAL	A_{vn}
BVN REAL	B_{vn}
CVN REAL	C_{vn}^R
CVN IMAG	C_{vn}

8. Program J

<u>Label on Output</u>	<u>Symbol in Analysis</u>
PRESSURE (TFLP)	TF_{LP}
RADIAL VELOCITY (TFLR)	TF_{LR}
TANGENTIAL VELOCITY (TFLT)	TF_{LT}
DISTRIBUTION COEFFICIENT MU	μ

III, Deck Setup (cont.)

G. INPUT FORM

A sample input sheet has been prepared on page for the case given below:

1. Illustrative Design Problem

a. Longitudinal Mode Analysis

The following data concerning a hypothetical engine will be used for this analysis:

Engine geometry: see Figure 19

$$\gamma = 1.218$$

$$C_o^* = 3800 \text{ ft/sec}$$

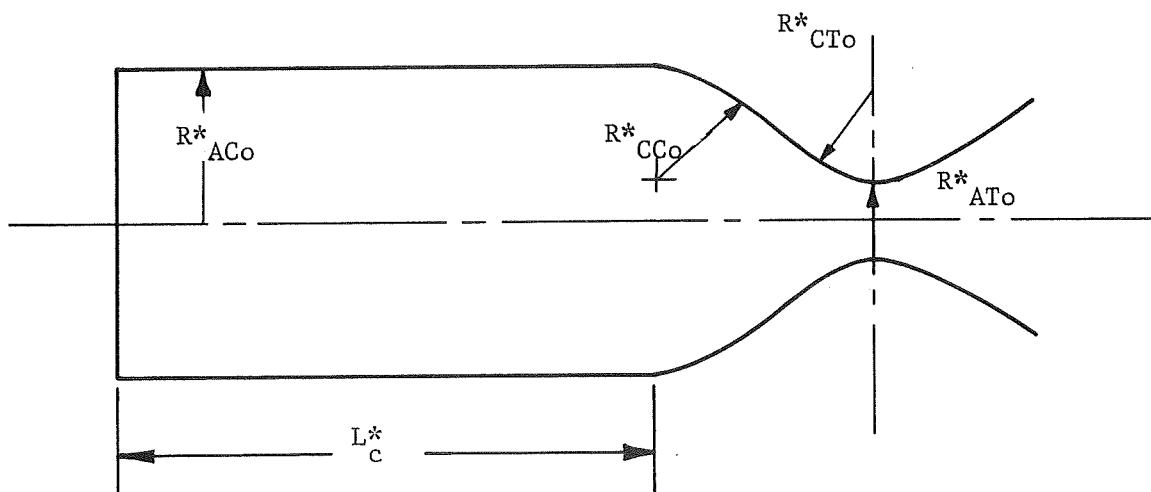
Mach number: unknown

Momentum interchange coefficient = 0.0

Combustion distribution: a linear combustion distribution with complete combustion occurring at 6.4 in.

$$P_c = 600 \text{ psia}$$

The problem is to find the n,r zone for the first longitudinal mode.



$$L_c^* = 11.8, \text{ in.}$$

$$R_{ACo}^* = 6.4, \text{ in.}$$

$$R_{CCo}^* = 3.0, \text{ in.}$$

$$R_{CTo}^* = 7.16, \text{ in.}$$

$$R_{ATo}^* = 3.58, \text{ in.}$$

$$\alpha = 15.0^\circ$$

Figure 19 -- Definition of the Geometrical Factors used in Example Problem

III, G, Input Form (cont.)

b. Transverse Mode

For the transverse case, the problem will be to find the n, τ zones for the first tangential and the second tangential modes. The data given in the longitudinal case will be supplemented by the following information:

$$s_{11} = 1.8413 \text{ and } s_{12} = 3.0543$$

Injector

Number of radial baffle compartments = 180

Total weight flow = 150 lb/sec

Mixture ratio = 2.0

Injection occurs at three radii:

Unlike doublets at $r = 2.0$ in.

Triplets (X-F-X) at $r = 4.0$ in.

Pentads (4F-X) at $r = 6.0$ in.

Injector radius = chamber radius

No film cooling

Storable propellants

Fuel and oxidizer loss coefficients = 0.75

Spinning modes

Tangential mode numbers = 1 and 2

No radial or tangential velocity effects

III, G, Input Form (cont.)

c. Nonlinear Combustion Response

For this case, the first tangential mode will be examined using a deadband nonlinear element. In addition to the above injector data the following additional information will be used:

$$\begin{aligned} P_{\text{oo}} &= 1.0 \\ \text{TFLP} &= 1.0 \end{aligned}$$

III, Deck Setup (cont.)

H. SAMPLE OUTPUT

The following output is run from the sample input given in the previous section:

EXAMPLE PROBLEM - FIRST LONGITUDINAL MODE FOR HYPOTHETICAL ENGINE

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A	B	C	D	E	F	G	H	I	J
100.	0.	100.	0.	0.	0.	0.	0.	0.	0.

***** THE FOLLOWING MAIN CONTROL DATA WILL BE USED IN THIS CASE *****

RATIO OF SPECIFIC HEAT (GAMMA) = 1.2160

DESIRED MACH NUMBER = .30000 (= IF BEING CALCULATED)

CHAMBER RADIUS = 6.400 (INCHES)

CHAMBER LENGTH = 14.600 (INCHES)

SPEED OF SOUND = 3800.000 (FT/SEC)

CHAMBER MODE DESCRIPTION = .000000 (=0 FOR LONGITUDINAL MODES)

***** CHAMBER FREQUENCIES (WC) *****

2.00000	.00000	3.25000	3.50000
3.75000	4.00000	4.50000	4.75000
5.00000	5.50000	6.00000	7.00000

***** MACH DISTRIBUTION IN CHAMBER AS A FUNCTION OF LENGTH *****

CHAMBER LENGTH	MACH DISTRIBUTION	CHAMBER LENGTH	MACH DISTRIBUTION	CHAMBER LENGTH	MACH DISTRIBUTION
.00000	.00600	6.40000	6.39500	25.00000	6.40000
2.50000	2.50000	6.41000	6.40000	50.00000	6.40000
5.00000	5.00000	6.42000	6.40000	75.00000	.00000
6.30000	6.30000	6.43000	6.40000	.00000	.00000
6.32000	6.32000	6.50000	6.40000	.00000	.00000
6.38000	6.38000	7.50000	6.40000	.00000	.00000
6.39000	6.39000	12.50000	6.40000		

EXAMPLE PROBLEM - FIRST LONGITUDINAL MODE FOR HYPOTHETICAL ENGINE

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PROGRAM C INF-UT = CALCULATES NOZZLE ATTENUATION

COEFFICIENTS USING #052

$$\begin{aligned} \delta &= 1.218 & M_{ESTR} &= 3 \\ RAT &= 3.589, RAC &= 6.400, RRC &= 3.000, RCI &= 7.160, ALFA &= 15.000, RN &= 1.01 \end{aligned}$$

A/N	(SNH)N	DEF
.75374+00	.000000	.000000
.113812+01	.000000	.000000
.132781+01	.000000	.000000
.151756+01	.000000	.000000
.170718+01	.000000	.000000
.189687+01	.000000	.000000
.207625+01	.000000	.000000
.614112+01	.000000	.000000

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EXAMPLE PROBLEM - FIRST LONGITUDINAL MODE FOR HYPOTHETICAL ENGINE

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PROGRAM C OUTPUT:

(SNH)C (SNH)N	WC WN	MACH NO G	-AR/ -AR/(MACH NO)	-AI/ -AI/(MACH NO)	-CR i1	E! i2	-CR/ -CR/(MACH NO)	-C1/ -C1/(MACH NO)
.0000	2.0000	1.1885	-.83951+00	-.12120+01	.00000+00	.00000+00	-.10709+00	.66309-03
.0000	.7587	1.2180	.44530+01	.64285+01	.00000	.00000	.56803+00	-.35172-02
F(CPS)=	960.7386							
.0000	3.0000	1.1885	-.14485+01	-.35432+01	.00000+00	.00000+00	-.41367-01	.60754-01
.0000	1.1381	1.2180	.7831+01	.18794+00	.00000	.00000	-.21942+00	.32226+00
F(CPS)=	1471.1079							
.0000	3.5000	1.1885	-.10632+01	.45579-01	.00000+00	.00000	-.45013-01	.12225-01
.0000	1.3278	1.2180	.56396+01	.24176+00	.00000	.00000	.23876+00	.64846-01
F(CPS)=	1716.2925							
.0000	4.0000	1.1885	-.89068+00	-.77292+02	.00000+00	.00000	-.38491-02	.35508-01
.0000	1.5175	1.2180	.47721+01	.40998+00	.00000	.00000	.20417-01	.18835+00
F(CPS)=	1961.4772							
.0000	4.5000	1.1885	-.86898+00	-.21132+00	.00000	.00000	.27857-01	.21121-02
.0000	1.7072	1.2180	.47047+01	.11211+01	.00000	.00000	-.14776+00	.11203-01
F(CPS)=	2206.6618							
.0000	5.0000	1.1885	-.96782+00	-.29622+00	.00000	.00000	-.90676-03	.20969-01
.0000	1.8969	1.2180	.51336+01	.15712+01	.00000	.00000	.48097-02	.11123+00
F(CPS)=	2451.8464							
.0000	6.0000	1.1885	-.11663+01	-.20603+05	.00000	.00000	.72719-02	.14955-01
.0000	2.2762	1.2180	.61862+01	.10928+01	.00000	.00000	.38572-01	.79327-01
F(CPS)=	2942.2157							
.0000	7.0000	1.1885	-.10462+01	-.35016+01	.00000	.00000	-.16826-01	.42143-02
.0000	6.1411	1.2180	.5494+01	.18573+00	.00000	.00000	.89261-01	.22354-01
F(CPS)=	3452.5850							

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EXAMPLE PROBLEM - FIRST LONGITUDINAL MODE FOR HYPOTHETICAL ENGINE

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U1BAR = .18152762+U₁ GAMMA = .12180000+J1 K = .00690000+00 X = .21651235+00 Y = .00690000+00 Z = .20420000+02

RESULTS FOR LONGITUDINAL MODE

FC(CPS)	ONEGA	TAU(YS)	N
1.8017	2.00000	.43362	1.25433
16.2948	2.10000	.35794	1.45551
16.788	2.20000	.30058	1.73711
11.2748	2.30000	.25904	2.37726
11.769	2.40000	.22678	2.45271
12.259	2.50000	.20395	2.63985
12.750	2.60000	.18742	3.21696
13.240	2.70000	.17565	3.56120
13.730	2.80000	.16750	3.85767
14.221	2.90000	.16211	4.09681
14.711	3.00000	.15876	4.26657
14.956	3.05000	.15772	4.52019
15.201	3.10000	.15699	4.54120
15.447	3.12000	.15632	4.55352
15.692	3.20000	.15548	4.31764
15.937	3.25000	.15425	4.28852
16.182	3.30000	.15245	4.25877
16.427	3.35000	.14999	4.23684
16.673	3.40000	.14685	4.23075
16.918	3.45000	.14312	4.24658
17.163	3.50000	.13903	4.28585
17.403	3.55000	.13452	4.35795
17.653	3.60000	.12986	4.45234
17.898	3.65000	.12469	4.57541
18.144	3.70000	.11987	4.72577
19.389	3.75000	.11493	4.90170
18.634	3.80000	.11017	5.10432
18.679	3.82000	.10569	5.31781
19.124	3.90000	.10154	5.54971
19.370	3.95000	.09773	5.79130
19.615	4.01000	.09428	6.03807
19.860	4.05000	.09117	6.28815
20.105	4.10000	.08841	6.53915
20.350	4.15000	.08539	6.78644
20.596	4.20000	.08369	7.02660
20.841	4.25000	.08208	7.25450
21.086	4.30000	.08053	7.46986
21.331	4.35000	.07919	7.67975
21.576	4.40000	.07732	7.85724
21.821	4.45000	.07597	8.03053
22.067	4.50000	.07461	8.19293
22.312	4.55000	.07311	8.34374
22.557	4.60000	.07229	8.48226
22.802	4.65000	.07147	8.61268
23.047	4.70000	.07062	8.74954
23.293	4.75000	.07017	8.8247
23.538	4.80000	.07058	9.01610
23.783	4.85000	.06933	9.17953
24.028	4.90000	.06877	9.37265
24.273	4.95000	.06620	9.60523

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EXAMPLE PROBLEM - FIRST LONGITUDINAL MODE FOR HYPOTHETICAL ENGINE

2451.8	5.00000	.06431
2460.9	5.10000	.06001
2549.9	5.00000	.05517
2599.0	5.30000	.05007
2648.0	5.40000	.04499
2697.0	5.50000	.04015
2746.1	5.60000	.03569
2795.1	5.70000	.03169
2844.1	5.80000	.02814
2893.2	5.90000	.02503
2942.2	6.00000	.02228
2991.3	6.10000	.01983
3040.3	6.20000	.01762
3089.3	6.30000	.01561
3138.4	6.40000	.01377
3187.4	6.50000	.01204
3236.4	6.60000	.01041
3285.5	6.70000	.00884
3334.5	6.80000	.00730
3383.5	6.90000	.00576
3432.6	7.00000	.00419

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 A B C D E F G H I J
 0. 100. 10. 10. 100. 10. 0. -100. 0. 100.

EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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***** THE FOLLOWING MAIN CONTROL DATA WILL BE USED IN THIS CASE *****

RATIO OF SPECIFIC HEAT (GAMMA) = 1.2186
 DESIRED MACH NUMBER = .00000 (=0 IF READING CALCULATED)
 CHAMBER RADIUS = 6.4000 (INCHES)
 CHAMBER LENGTH = 14.8000 (INCHES)
 SPEED OF SOUND = 3800.000 (FT/SEC)
 CHAMBER MODE DESCRIPTION = 1.04118 (=0 FOR LONGITUDINAL MODES)

***** CHAMBER FREQUENCIES (WCO) *****

1.69589	1.73071	1.7654	1.80436
1.87801	1.91483	1.95162	1.98648

***** MACH DISTRIBUTION IN CHAMBER AS A FUNCTION OF LENGTH *****

CHAMBER LENGTH	MACH DISTRIBUTION	CHAMBER LENGTH	MACH DISTRIBUTION	CHAMBER LENGTH	MACH DISTRIBUTION
.00000	.00000	6.40000	6.39500	25.00000	6.40000
2.50000	2.50000	6.41000	6.40000	50.00000	6.40000
5.00000	5.00000	6.42000	6.40000	0.00000	.00000
6.30000	6.30000	6.43000	6.40000	.00000	.00000
6.35000	6.35000	6.50000	6.40000	.00600	.90000
6.38000	6.38000	7.50000	7.40000	.01000	.00000
6.39000	6.39000	12.50000	12.40000	.00300	.00000

SECTION 1.....MISCELLANEOUS INFORMATION FOR INJECTOR DESIGNED BY PROJECTS

A....PROPELLANT ORIFICE AREAS

ELEMENT TOTAL OXIDIZER AREA = .48462972 SQ. IN.
 TOTAL OXIDIZER FILM COOLING AREA = .00000000 SQ. IN.
 INJECTOR TOTAL OXIDIZER AREA = .48462972 SQ. IN.

B....INJECTOR PRESSURE DROPS FOR ABOVE INJECTOR DESIGN

OXIDIZER PRESSURE DROP = 36.6 PSI

C....PROPELLANT FLOWS AND INJECTOR VELOCITIES FOR ABOVE INJECTOR DESIGN

TOTAL WEIGHT FLOW = 150.0 LB/SEC
 AVERAGE MIXTURE RATIO OF THE ELEMENTS = 2.000
 OVERALL MIXTURE RATIO FOR THE INJECTOR = 2.000

ELEMENT TOTAL OXIDIZER FLOW = 100.0 LB/SEC
 TOTAL OXIDIZER FILM COOLING FLOW = 100.0 LB/SEC
 INJECTOR TOTAL OXIDIZER FLOW = 100.0 LB/SEC
 OXIDIZER OVERALL INJECTION VELOCITY = 61.5 FT/SEC

ELEMENT TOTAL FUEL FLOW = 50.0 LB/SEC
 TOTAL FUEL FILM COOLING = 50.0 LB/SEC
 INJECTOR TOTAL FUEL FLOW = 50.0 LB/SEC
 FUEL OVERALL INJECTION VELOCITY = 32.7 FT/SEC

D....INPUT INFORMATION USED IN COMPUTATIONS

TOTAL PROPELLENT FLOW = 150.0 LB/SEC
 TOTAL NUMBER OF ELEMENT TYPES (SYMMETRICAL SECTION ONLY) = 3
 TOTAL NUMBER OF ELEMENTS (SYMMETRICAL SECTION ONLY) = 3
 OXIDIZER LOSS COEFFICIENT = .750
 FUEL LOSS COEFFICIENT = .750
 PERCENT FUEL FILM COOLING = .0
 PERCENT OXIDIZER FILM COOLING = .0
 DIAMETER OF FUEL FILM COOLING ORIFICE = .00000 IN. (NOTE..THIS MIGHT BE AN EQUIVALENT DIAMETER FOR MULTIPLE-ROW COOLING
 DIAMETER OF OXIDIZER FILM COOLING ORIFICE = .00000 IN. (SEE ABOVE NOTE)
 NUMBER OF FUEL FILM COOLING ORIFICES PER INJECTOR = 0.
 NUMBER OF OXIDIZER FILM COOLING ORIFICES PER INJECTOR = 0.
 OXIDIZER DENSITY = 89.52 PCF
 FUEL DENSITY = 56.1 PCF

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EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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SECTION 2 . . . ELEMENT LOCATION AND INJECTION TYPE

ELEMENT NO.	TYPE NO.	R (INCHES)	THETA (DEGREE)	X (INCHES)	Y (INCHES)
1		2.00000	1.00000	1.09970	.03490
2		4.00000	1.00000	3.99939	.06981
3		6.00000	1.00000	5.99919	.10471

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EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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SECTION TYPE DESCRIPTION, ORIFICE AREA, PROPELLANT FLOW, AND MIXTURE RATIO
TYPE ----- OXIDIZER ORIFICE DATA ----- FUEL ORIFICE DATA -----*

NUMBER OF ORIFICE	DIAMETER IN.	AREA SQ. IN.	FLOW LB/SEC	NUMBER OF ORIFICES	DIAMETER IN.	AREA SQ. IN.	FLOW LB/SEC	TOTAL OXIDIZER AREA SQ. IN.	TOTAL FUEL AREA SQ. IN.	TOTAL PROPULSION AREA SQ. IN.	TOTAL FLOW RATE LB/SEC	MIXTURE RATIO
								LE/SEC	LE/SEC			
1	.0785	.004340	.138887	1	.0785	.004840	.046296	.00484	.00484	.00484	.1852	3.000
2	.0785 .0735	.004840 .004840	.138889 .138889	1	.0785	.004840	.046296	.00968	.00968	.00968	.3241	6.000
3	.0785	.004340	.138889	4	.0785 .0785 .0785 .0785	.004840 .004840 .004840 .004840	.046296 .046296 .046296 .046296	.00484	.00484	.00484	.3241	.750

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EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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ELEMENT RESULTS

ELEMENT NO.	RADIUS	ANGLE RADIANs	DISTRIBUTION COEFFICIENT μ_0
1	2.000	.0175	4.4444
2	4.000	.0175	7.7778
3	6.000	.0175	7.7778

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EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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SECTION 4 . RESULTANT FLOW DISTRIBUTION ($\mu(r)$) AS A FUNCTION OF UNARY TIME RADIUS, I.E., AVERAGE OF MU IN A RADIAL BAND

RADIUS IN.	MU(R) IN.	M.(R)/MU(MAX)
1.431	.000	.0000
2.024	4.444	.5714
2.479	.000	.0000
2.862	.000	.0000
3.200	.000	.0000
3.505	.000	.0000
3.766	.000	.0000
4.048	7.778	1.0000
4.293	.000	.0000
4.525	.000	.0000
4.746	.060	.0000
4.951	.000	.0000
5.160	.000	.0000
5.355	.000	.0000
5.543	.000	.0000
5.724	.000	.0000
5.901	.000	.0000
6.072	7.778	1.0000
6.238	.000	.0000
6.400	.000	.0000

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EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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INPUT TO INJECTION DISTRIBUTION PROGRAM

CONSTANTS

NUMBER OF OMEGAS = 1.

NUMBER OF ELEMENTS = 3 FOR EACH OF 180 SYMMETRIC SECTIONS.

RADIAL DIVISIONS (XM) = 20.

ANGULAR DIVISIONS (XN) = 180.

ACUSTIC MODE NUMBER (SYN) = 1.8412

ORDER OF BESSSEL FUNCTIONS (V) = 1.

INJECTOR RADIUS = 6.400, IN.

RATIO OF SPECIFIC HEATS (GAMMA) = 1.2180

MAXIMUM PRESSURE AMPLITUDE RATIO (PCU) = .000

TRANSFER FUNCTIONS FOR LINEAR OPERATION

PRESSURE (TFLP) = .000

RADIAL VELOCITY (TFLR) = .000

TANGENTIAL VELOCITY (TFLT) = .000

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EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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ELEMENT INFORMATION

ELEMENT NO.	RADIUS IN.	ANGLE RADIANs	DISTRIBUTION COEFFICIENT MU
1	2.000	.1475	4.4444
2	4.000	.3150	7.7773
3	6.000	.4725	7.7773

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EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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RESULTS OF INJECTION DISTRIBUTION EFFECTS

OMEGA	AVN REAL	BVN REAL	CVN REAL	IMAG
ALL	1.2745	.8766	.0000	-1.8125

***** THESE VALUES PERTAIN TO A SPINNING MODE *****

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PROGRAM C OUTPUT

EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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(SNH)C (SNH)N	WC wN	MACH NO G	-A1/ -A1/(MACH NO)	A1 -A1/(MACH NO)	B1 -B1/(MACH NO)	C1 -C1/(MACH NO)
1.8412 2.7421	1.6939 1.4861	.1885 .2180	-.6983-03 .37347-02	.48540+00 .25747+01	-.22687-.1 .21724+00	.43915-02 .23294-01
FC(CPS) = 1920.6346						
1.8412 2.7421	1.7675 1.5567	.1885 1.2180	.12542-01 -.66792-01	.40557+00 .21513+01	-.27694-01 .21299-01	.35139-02 -.18639-01
FC(CPS) = 2004.3491						
1.8412 2.7421	1.8412 1.6153	.1885 1.2180	.26233-01 -.13941+00	.32326+00 -.17147+01	-.34799-01 .26550+00	.12062-02 -.63661-02
FC(CPS) = 2057.8636						
1.8412 2.7421	1.9148 1.6799	.1885 1.2180	.41969-01 -.22261+00	.23916+00 -.12686+01	-.18321+00 .29246+00	.34923-02 -.18524-01
FC(CPS) = 2171.3781						
1.8412 2.7421	1.9885 1.7445	.1885 .2180	.65749-01 -.34875+00	.13721+00 -.72779+00	-.21557-01 .23433+00	.63995-03 -.33945-02
FC(CPS) = 2254.8926						
1.8412 2.7421	2.0253 1.7766	.1885 1.2180	.70360-01 -.37321+00	.76014-01 -.40320+00	-.79474-02 .20348+00	.15016-02 -.84956-02
FC(CPS) = 2276.6496						

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TRANSVERSE STABILITY PROGRAM... CALCULATES HR, HI OR HTR, HTI

EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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INPUT DATA

S/N:	ZE	GAMMA	UE	SOUND (FT/SEC)	ULM (FT/SEC)	XK (DRAG)	XCOMPL (IN)
1. 84113374	2.31250000	1.21900	.18852762	3500.00	20.420000	.000000	.000000
INCREMENTS	LR/N	L/T/N					
.0	.0000000	.0000000					

NOZZLE ADMITTANCES INPUT

OMEGA (CH)	EHT	EIT	CRT	CIT
1.6938690	.21723997+00	.42368060+00	.45915419-02	-.38372861-03
1.7675363	.21299294+00	.36165724+00	.35139393-02	-.28287281-02
1.8411837	.20949743+00	.29246183+00	.12001764-02	-.34922587-02
1.9148310	.20611402+00	.21434163+00	-.63995426-03	-.79533766-03
1.9884783	.20434311+00	.12512822+00	.23384384-02	-.74945183-03
2.0253019	.20347937+00	.75667907-01	.16016490-02	-.32095248-02

CALCULATED RESULTS...

FIRST-ORDER SOLN (UNIF INJ)		SECOND-ORDER SOLUTION	
OMEGA	H REAL	H IMAG	HT REAL
1.6938690	.17957059+01	-.27574364+01	
1.7367127	.17782917+01	-.22796713+01	
1.7675364	.17530309+01	-.17919479+01	
1.8043600	.17150791+01	-.12867290+01	
1.8411837	.16552088+01	-.75276300+00	
1.8760073	.15548406+01	-.17326547+00	
1.9148316	.13731173+01	.47663003+00	
1.9516547	.10097995+01	.12250634+01	
1.9274783	.21071933+00	.20269546+01	
2.0253020	.14794744+01	.22718191+01	

PROGRAM L OUTPUT

OMEGA (C)	HTR	HTI
1.693869	1.438977	-2.163586
1.730713	1.395313	-1.788714
1.767536	1.375492	-1.406028
1.804360	1.345714	-1.009615
1.841184	1.298738	-.590645
1.876007	1.219985	-.135950
1.914831	1.077394	.373981
1.951655	.792326	.961230

EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

1.968458
2.025372

*1.65339
-1.149850

1.590423
1.782553

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EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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FOLLOWING WILL BE INTERPOLATION WITHIN HTS Hi TABLE GIVEN ABOVE

OMEGA

HTEINT

HJINT

-1.693889

1.463977

-2.163586

1.702387

1.406370

-2.07770

1.710885

1.403455

-1.991539

1.719382

1.400173

-1.904891

1.727880

1.396583

-1.817826

1.736378

1.392702

-1.730407

1.744876

1.386594

-1.642721

1.753373

1.384121

-1.554571

1.761871

1.379152

-1.465738

1.770369

1.373575

-1.376047

1.778867

1.367628

-1.285807

1.787364

1.361180

-1.194872

1.795862

1.353964

-1.102917

1.804360

1.345714

-1.009616

1.812858

1.336698

-9.15205

1.821355

1.327006

-8.19804

1.829853

1.316099

-7.22934

1.838351

1.303446

-6.24108

1.846849

1.289011

-5.23215

1.855346

1.273568

-4.20881

1.863834

1.256376

-3.16484

1.872342

1.235935

-2.09306

1.880840

1.211438

-0.98749

1.889338

1.185488

.014342

1.897835

1.156400

.130284

1.906333

1.121336

.249892

1.914631

1.077395

.373978

1.923329

1.028341

.503359

1.931826

.974968

.637437

1.940324

.909922

.774907

1.948622

.825851

.914467

1.957320

.721702

1.620716

1.965817

.607967

1.060091

1.974315

.472916

1.220061

1.982813

.303737

1.517271

1.991311

.088155

1.696259

1.999808

-.168259

1.696089

2.008306

-.461870

1.748166

2.016804

-.792735

1.777007

2.025302

-1.160835

1.782553

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EXAMPLE PROBLEM - FIRST TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

PROGRAM F OUTPUT

	FC(CPS)	TAU(MS)
1520.8	1.67389	2.36506
1430.5	1.70239	2.23803
1440.1	1.71088	.41930
1449.7	1.71938	.41472
1459.4	1.72768	.40941
1469.0	1.73638	.40394
1478.7	1.74488	.39831
1488.3	1.75337	.39250
1497.9	1.76187	.38648
2007.6	1.77037	.38024
2017.2	1.77887	.37373
2026.8	1.78736	.36694
2036.5	1.79586	.35983
2046.1	1.80436	.35237
2055.7	1.81286	.34450
2065.4	1.82136	.33518
2075.0	1.82985	.32737
2084.7	1.83835	.31812
2094.3	1.84685	.30603
2103.9	1.85535	.29735
2113.6	1.86384	.28594
2123.2	1.87234	.27373
2132.8	1.88084	.26064
2142.5	1.88934	.24657
2152.1	1.89784	.23158
2161.7	1.90633	.21574
2171.4	1.91483	.19901
2181.0	1.92337	.18129
2190.7	1.93185	.16282
2200.3	1.94032	.14411
2209.9	1.94882	.12519
2219.6	1.95732	.10580
2229.2	1.96582	.08572
2238.8	1.97432	.06691
2248.5	1.98281	.04790
2258.1	1.99131	.02797
2267.7	1.99981	.00756
2277.4	2.00831	.00551
2287.0	2.01680	.00355
2296.6	2.02530	.00152

THE FOLLOWING ARE VALUES INTERPOLATED AT SLOPE OF N=0.0

NMIN =	.58525
TAU(MS) =	.21258
(OMEGA)D =	1.69958
F(CPS) =	2154.1

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 A B C D E F G H I J
 0. 100. 10. 100. 10. 0. -100. 0. 0.

EXAMPLE PROBLEM - SECOND TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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***** THE FOLLOWING MAIN CONTROL DATA WILL BE USED IN THIS CASE *****

RATIO OF SPECIFIC HEAT (GAMMA) = 1.2186
 DESIRED MACH NUMBER = .60000 (=0 IF DRIVING CALCULATED)
 CHAMBER RADIUS = 6.410 (INCHES)
 CHAMBER LENGTH = 14.890 (INCHES)
 SPEED OF SOUND = 3800.050 (FT/SEC)
 CHAMBER MODE DESCRIPTION = 3.05424 (=0 FOR LONGITUDINAL MODES)

***** CHAMBER FREQUENCIES (WC) *****

2.80990	2.93207	2.99315	3.05424
3.11532	3.23749	3.29858	3.35966

***** MACH DISTRIBUTION IN CHAMBER AS A FUNCTION OF LENGTH *****

CHAMBER LENGTH	MACH DISTRIBUTION	CHAMBER LENGTH	MACH DISTRIBUTION	CHAMBER LENGTH	MACH DISTRIBUTION
.00000	.00000	6.40000	6.39500	25.00000	6.40000
2.50000	2.50000	6.41000	6.40000	50.00000	6.40000
5.00000	5.00000	6.42000	6.40000	.00000	.00000
6.30000	6.30000	6.43000	6.40000	.00000	.00000
6.35000	6.35000	6.50000	6.40000	.00000	.00000
6.38000	6.38000	7.50000	6.40000	.00000	.00000
6.39600	6.39600	12.50000	6.40000		

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EXAMPLE PROBLEM - SECOND TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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INPUT TO INJECTOR DISCRETIZATION PROGRAM

CONSTANTS

NUMBER OF OMEGAS = 1

NUMBER OF ELEMENTS = 4 FOR EACH OF 180 SYMMETRIC SECTIONS.

RADIAL DIVISIONS(XA) = 26.

ANGULAR DIVISIONS (XR) = 150.

ACOUSTIC MODE NUMBER(S,N) = 3.0542

ORDER OF HESSEL FUNCTIONS(Y) = 2.

INJECTOR RADIUS = 6.400, IN.

RATIO OF SPECIFIC HEATS(CP/MMA) = 1.2180

MAXIMUM PRESSURE AMPLITUDE RATIO(P0%) = .060

TRANSFER FUNCTIONS FOR LINEAR OPERATION

PRESSURE(TFLP) = .000

RADIAL VELOCITY(TFLR) = .000

TANGENTIAL VELOCITY(TFLT) = .000

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EXAMPLE PROBLEM - SECOND TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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ELEMENT INFORMATION

ELEMENT NO.	RADIUS IN.	ANGLE RADIANs	DISTRIBUTION COEFFICIENT MIL
1	2.000	.0175	4.444
2	4.000	.0175	7.778
3	6.000	.0175	7.778

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EXAMPLE PROBLEM - SECOND TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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RESULTS OF LINEARIZATION AND TANGENTIAL MODES

Mode	GEN GEAL	GEN GEAL	GEN GEAL	GEN IMAG
All	1.2761	1.2828	.0090	-3.2524

* * * * * THESE VALUES PERTAIN TO A SPINNING MODE * * * * *

DATE 03 MAY 69

EXAMPLE PROBLEM - SECOND TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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PROGRAM JUTPUT

(SNH)C (SNH)N	W _C W _N	MACH NO G	A _R -AR/(MACH NO)	A _I -AI/(MACH NO)	B _R T ₁	B _I T ₂	CR -CR/(MACH NO)	C _I -CI/(MACH NO)
3.0542	2.0099	.1885	.14637-01	.45547+00	-.50957-02	-.20204+00	.68186-03	.20889-03
4.5487	2.4651	1.2180	-.77441-01	-.24139+01	.21550+00	.41394+00	-.36168-02	.11080-02
FC(CPS) = 3184.3651								
3.0542	2.9321	.1885	.19685-01	.36188+00	-.46909-02	-.19214+00	.67167-03	.64559-03
4.5487	2.5733	1.2180	-.16441+00	-.19195+01	.21103+00	.34271+00	-.35627-02	.34244-02
FC(CPS) = 3124.9026								
3.0542	3.0542	.1885	.24287-01	.26445+00	-.39316-02	-.16399+00	-.19082-03	.66101-03
4.5487	2.6795	1.2180	-.16382+00	-.14027+01	.20827+00	.26052+00	.10122-02	.35062-02
FC(CPS) = 3463.4402								
3.0542	3.1764	.1885	.31553-01	.16051+00	-.35605-02	-.17486+00	-.22172-03	.27431-03
4.5487	2.7867	1.2180	-.16737+00	-.85140+00	.20768+00	.16337+00	.11761-02	.14550-02
FC(CPS) = 3501.9778								
3.0542	3.2986	.1885	.39549-01	.40666-01	.11319-02	-.16749+00	.83306-04	.41939-04
4.5487	2.8939	1.2180	-.20975+00	-.21571+00	.21320+00	.45052-01	-.44188-03	.22245-03
FC(CPS) = 3740.5154								
3.0542	3.3547	.1885	.42122-01	-.24362-01	.13055-02	-.16696+00	.44631-03	.77124-03
4.5487	2.9474	1.2180	-.23741+00	-.12926+00	.21329+00	.25501-01	.23674-02	.40909-02
FC(CPS) = 3809.7641								

EXAMPLE PROBLEM - SECOND TANGENTIAL MODE FOR HYPOTHETICAL ENGINE
 TRANSVERSE STABILITY PROGRAM... CALCULATES HR, HI, G, HTR, HTI
 INPUT DATA

SINH	7E	GAMMA	UE	SOUND (FT/SEC)	ULN (FT/SEC)	XK (URAG)	XCOMPL (IN)
3.05425580	2.31250000	1.21E+0	.18352762	3839.0	20.420000	.000000	.000000
INCREMENTS	LRT/N	LRT/N					
.0	.000000	.000000					

NOZZLE ALTERNANCES INPUT

OMEGA(CH)	EIT	CFT	CIT
2.9098978	.21520144+00	.41393717+00	.68185882-03
2.9320672	.21105374+00	.34271131+00	.67167071-03
3.0542567	.20822044+00	.26051653+00	.64559413-03
3.1764061	.20767955+00	.16387189+00	.66101016-03
3.2985756	.21019255+00	.45021624-01	.27430632-03
3.3596603	.21329456+00	-.2550060/-01	.41938501-04

CALCULATED RESULTS...

OMEGA	H REAL	H IMAG	H REAL	H IMAG
2.6198078	.18477270+01	-.33330533+01		
2.8109826	.18420155+01	.26730276+01		
2.9320673	.18303412+01	-.20026716+01		
2.9931520	.18046494+01	.13051752+01		
3.0542567	.17417167+01	-.54798279+00		
3.1764061	.15558282+01	.33563596+00		
3.2985756	.82928105+00	.13542761+01		
3.3596603	-.74346571+00	.94920094+00		
	.19611624+00	-.42130505-02		
	.64748577+00	.65183567+00		

PROGRAM OUTPUT

OMEGA(1)	TR	T
2.6198078	1.447911	-2.611330
2.8109826	1.424511	-2.064650
2.9320673	1.427264	-1.569328
2.9931520	1.44182	-1.022258
3.0542567	1.44839	-.420402
3.1764061	1.226174	.250973
3.2985756	.675986	1.061229
3.3596603	-.252571	.047109

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EXAMPLE PROBLEM - SECOND TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

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3.298576	.15518	-.003301
3.359660	.742466	.510790

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FOLLOWING WILL BE DIFFERENTIATION WITH RESPECT TO TIME ABOVE	
COMMA	HIGH
2.811598	4.424911
2.820962	1.447458
2.825225	1.446953
2.842790	1.440947
2.853754	1.445187
2.864717	1.44126
2.875681	1.442929
2.886645	1.446697
2.897609	1.440398
2.908573	1.443806
2.919537	1.447934
2.930501	1.431634
2.941465	1.432066
2.952429	1.429461
2.963393	1.426503
2.974357	1.42876
2.985321	1.419260
2.996284	1.412647
3.007248	1.406766
3.018212	1.400807
3.029176	1.393407
3.040140	1.383402
3.051104	1.389629
3.062068	1.353722
3.073032	1.342228
3.083996	1.323383
3.094960	1.30921
3.105924	1.26575
3.116888	1.210281
3.127851	1.145059
3.138815	1.07603
3.149779	.92123
3.150743	.672631
3.171707	.77937
3.182671	.56587
3.193635	.313985
3.204599	.026976
3.215567	-.246402
3.226527	-.468232
3.237491	-.462590

EXAMPLE PROBLEM - SECOND TANGENTIAL MODE FOR HYPOTHETICAL ENGINE

THE FOLLOWING ARE VALUES INTERPOLATED AT STAGE OF $N=0.8$

NMIN = .63752
 TAU(NS) = .12561
 (OMEGA)D = .11224
 FCF(PS) = .22942

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DATE 03 NOV 69 T LOADS2 SHOWING EFFECTS OF DEADBAND NONLINEARITY

A	B	C	D	E	F	G	H	I	J
0.	0.	0.	0.	203.	0.	0.	0.	50.	0.

***** THE FOLLOWING MAIN CONTROL DATA WILL BE USED IN THIS CASE *****

RATIO OF SPECIFIC HEAT (GAMMA) = 1.2180

DESIRED MACH NUMBER = .90000 (=0 IF BEING CALCULATED)

CHAMBER RADIUS = 6.400 (INCHES)

CHAMBER LENGTH = 14.800 (INCHES)

SPEED OF SOUND = 3890.000 (FT/SEC)

CHAMBER MODE DESCRIPTION = 1.64116 (=0 FOR LONGITUDINAL MODES)

***** CHAMBER FREQUENCIES (WC) *****

1.69389 1.73071 1.76754 1.80436 1.84118

1.87801 1.91483 1.95165 1.98848 2.02530

***** MACH DISTRIBUTION IN CHAMBER AS A FUNCTION OF LENGTH *****

CHAMBER LENGTH	MACH DISTRIBUTION	CHAMBER LENGTH	MACH DISTRIBUTION	CHAMBER LENGTH	MACH DISTRIBUTION
.06000	.00000	6.40000	6.39500	25.00000	6.40000
.20000	2.50000	6.41000	6.40000	50.00000	6.40000
.50000	5.00000	6.42000	6.40000	.00000	.00000
6.30000	6.39000	6.43000	6.40000	.00000	.00000
6.35000	6.35000	6.50000	6.40000	.00000	.00000
6.38000	6.38000	7.50000	6.40000	.00000	.00000
6.39000	6.39000	12.50000	6.40000		

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TLODE2 RHOWING EFFECTS OF DEADBAND NONLINEARITY

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TLODE2 RHOWING EFFECTS OF DEADBAND NONLINEARITY

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INPUT TO INJECTION DISTRIBUTION PROGRAM

CONSTANTS

NUMBER OF OMEGAS = 6

NUMBER OF ELEMENTS = 3 FOR EACH OF 180 SYMMETRIC SECTIONS.

RADIAL DIVISIONS (XM) = 20.

ANGULAR DIVISIONS (XN) = 180.

ACOUSTIC MODE NUMBER (SVN) = 1.8412.

ORDER OF BESSSEL FUNCTIONS (V) = 1.

INJECTOR RADIUS = 6.400, IN.

RATIO OF SPECIFIC HEATS (GAMMA) = 1.2180

MAXIMUM PRESSURE AMPLITUDE RATIO (P00) = 1.000

TRANSFER FUNCTIONS FOR LINEAR OPERATION

PRESSURE (TFLP) = .000

RADIAL VELOCITY (TFLR) = 1.000

TANGENTIAL VELOCITY (TFLT) = .000

INPUT FREQUENCIES

1.6939 1.7675 1.8412 1.9148 1.9885

2.0253

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TRANSMITTING ELEMENTS OF DEJURAS NONLINEARITY

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ELEMENT INFORMATION

ELEMENT NO.	RADIUS IN.	ANGLE RADIANs	DISTRIBUTION COEFFICIENT MU
1	2.000	.0175	4.4444
2	4.000	.0175	7.7778
3	6.000	.0175	7.7778

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TITLE 2 RHODIUM EFFECTS OF DEADBAND NONLINEARITY

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RESULTS OF DESCRIPTING FUNCTION

CMEGA	ELEMENT NO.	RADIUS	ANGLE RAD	FRACTIONAL FLOW-RATE	FP	FR	FT
1.6939	1	.313	.0175	.00123	1.00000	.678814	1.000000
1.6939	2	.625	.0175	.00216	1.00000	.493693	1.000000
1.6939	3	.938	.0175	.00216	1.00000	.000000	1.000000

DATE 03 NOV 69 T LOGEE2 SHOWING EFFECTS OF DEADBAND NONLINEARITY

RESULTS OF DESCRIBING FUNCTION

OMEGA	ELEMENT NO.	RADIUS	ANGLE RAD	FRACTIONAL FLOW-RATE	FP	FR	FT
1.7675	1	.313	.0175	.00123	1.900000	.665192	1.000000
1.7675	2	.625	.0175	.00216	1.000000	.472795	1.000000
1.7675	3	.938	.0175	.00216	1.000000	.000000	1.000000

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T : ODE2 RHOWING EFFECTS OF DEADBAND NONLINEARITY

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RESULTS OF UNSCRIBING FUNCTION

OMEGA	ELEMENT NO.	RADIUS	ANGLE RAD	FRACTIONAL FLOW-RATE	FP	FR	FT
1.8412	1	.313	.0175	.00125	1.30000	.651640	1.000000
1.8412	2	.625	.0175	.00216	1.00000	.452589	1.000000
1.8412	3	.938	.0175	.00216	1.00000	.000000	1.000000

DATE 03 NOV 69 T LOADS SHOWING EFFECTS OF DEADBAND NONLINEARITY

RESULTS OF DESCRIBING FUNCTION

OMEGA	ELEMENT NO.	RADIUS	ANGLE RAD	FRACTIONAL FLOW-RATE	FP	FR	FT
1.9148	1	.313	.0175	.00123	1.00000	.637977	1.000000
1.9148	2	.625	.0175	.00216	1.00000	.432330	1.000000
1.9148	3	.938	.0175	.00216	1.00000	.000000	1.000000

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TIODE2 SHOWING EFFECTS OF DEADBAND NONLINEARITY

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RESULTS OF DESCRIBING FUNCTION

OMEGA NO.	ELEMENT NO.	RADIUS	ANGLE RAD	FRACTIONAL FLOW-RATE	F P	F R	F T
1.9885	1	.313	.0175	.00123	1.00000	.624504	1.000000
1.9885	2	.625	.0175	.00216	1.00000	.412330	1.000000
1.9885	3	.938	.0175	.00216	1.00000	.000000	1.000000

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 1 LONE2 RHOING EFFECTS OF DEADBAND NONLINEARITY

RESULTS OF DESCRIBING FUNCTION

OMEGA	ELEMENT NO.	RADIUS	ANGLE RAD	FRACTIONAL FLOW-RATE	FP	FR	FT
2.0253	1	.313	.0175	.00123	1.000000	.617796	1.000000
2.0253	2	.625	.0175	.00216	1.000000	.402424	1.000000
2.0253	3	.938	.0175	.00216	1.000000	.000000	1.000000

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LOGIC SHOWING EFFECTS OF DEADBAND NONLINEARITY

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RESULTS OF INJECTION DISTRIBUTION EFFECTS

OMEGA	AVG REAL	BVN REAL	CVN REAL	CVN IMAG
1.6939	1.2745	.4300	.0000	-1.8125
1.7675	1.2745	.4158	.0000	-1.8125
1.8412	1.2745	.4020	.0000	-1.8125
1.9148	1.2745	.3881	.0000	-1.8125
1.9885	1.2745	.3744	.0000	-1.8125
2.0253	1.2745	.3676	.0000	-1.8125

* * * * * THESE VALUES PERTAIN TO A SPINNING MODE * * * * *

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AS138 CALLED	AT	SEQUENCE	NUMBER	00161	OF	CHAMBR
CHAMBR CALLED	AT	SEQUENCE	NUMBER	00104	OF	MAIN PROGRAM

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